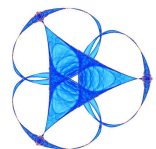


Differential Complexes and Mixed Finite Elements for Elasticity

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1. Mixed finite elements for elasticity
2. Exterior calculus
3. Discrete exterior calculus
4. Construction of the elasticity complex

Coming Attractions!

Construction of the elements

1. Mixed finite elements for elasticity
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$$\begin{array}{ll} \text{displacement} & u : \Omega \rightarrow \mathbb{V} := \mathbb{R}^n & A\sigma = \epsilon u := [\nabla u + (\nabla u)^T]/2 \\ \text{stress} & \sigma : \Omega \rightarrow \mathbb{S} := \mathbb{R}_{\text{sym}}^{n \times n} & \operatorname{div} \sigma = f \end{array}$$

$\sigma \in H(\operatorname{div}, \Omega; \mathbb{S}), u \in L^2(\Omega; \mathbb{V})$ satisfy

$$\int_{\Omega} A\sigma : \tau \, dx + \int_{\Omega} \operatorname{div} \tau \cdot u \, dx = 0 \quad \forall \tau \in H(\operatorname{div}, \Omega; \mathbb{S})$$

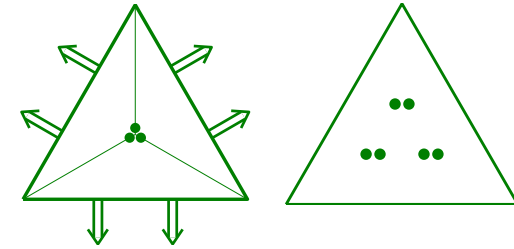
$$\int_{\Omega} \operatorname{div} \sigma \cdot v \, dx = \int_{\Omega} f \cdot v \, dx \quad \forall v \in L^2(\Omega; \mathbb{V})$$

$(\sigma, u) \in H(\operatorname{div}, \Omega; \mathbb{S}) \times L^2(\Omega; \mathbb{V})$ saddle point of

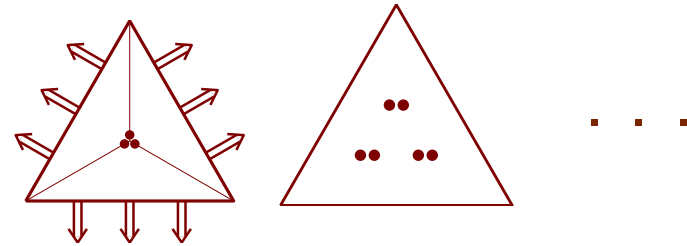
$$\mathcal{L}(\tau, v) = \int_{\Omega} \left(\frac{1}{2} A\tau : \tau + \operatorname{div} \tau \cdot v - f \cdot v \right) dx.$$

Stable mixed elements

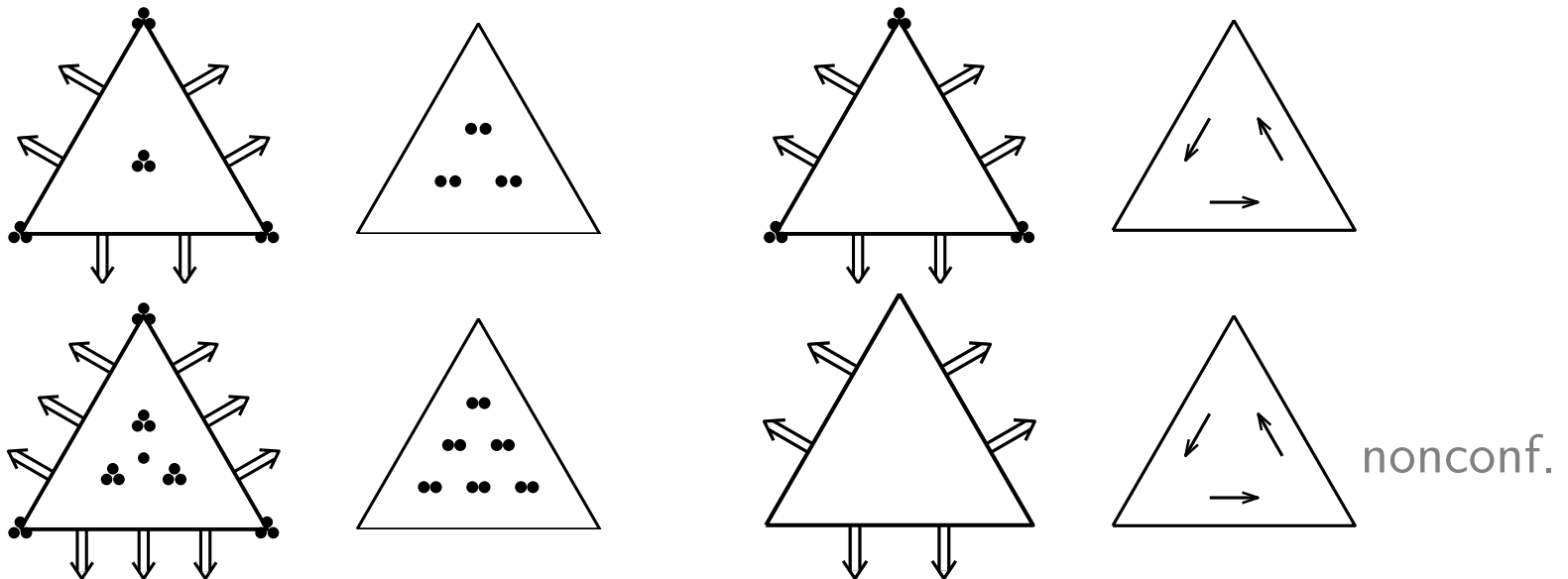
2D composite elts: Johnson–Mercier '78
cf. Fraeijs de Veubeke '65; Watwood–Hartz '68



Arnold–Douglas–Gupta '84



2D polynomial elements, Arnold–Winther 2002:



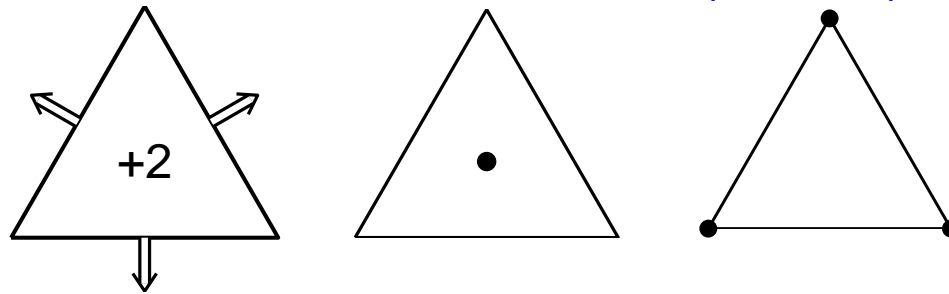
3D very complicated. . .

Weak symmetry

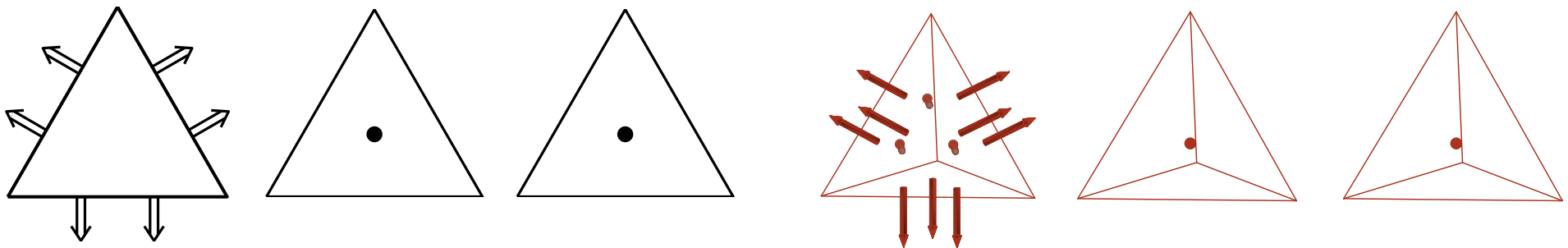
To avoid the problems arising from the symmetry of the stress tensor, it can be imposed *weakly*

$$(\sigma, u, p) = \underset{H(\operatorname{div}, \Omega; \mathbb{M}) \times L^2(\Omega; \mathbb{V}) \times L^2(\Omega; \mathbb{K})}{\operatorname{argcrit}} \left(\frac{1}{2} \int A\tau : \tau + \int v \cdot \operatorname{div} \tau + \int \tau : p + \int f \cdot v \right)$$

Fraeijis de Veubeke '75, Arnold-Brezzi-Douglas '84 (PEERS), Stenberg, Morley, . . .



Major result of these talks: new elements in 2D and 3D



These were obtained via a new “homological” viewpoint. . .

The elasticity complexes

A key to developing stable elements for elasticity (with strongly imposed symmetry) is the *elasticity complex*:

$$\mathbb{T} \hookrightarrow C^\infty(\Omega, \mathbb{V}) \xrightarrow{\epsilon} C^\infty(\Omega, \mathbb{S}) \xrightarrow{J} C^\infty(\Omega, \mathbb{S}) \xrightarrow{\text{div}} C^\infty(\Omega, \mathbb{V}) \longrightarrow 0$$

↑ displacement ↑ strain ↑ stress ↑ load

$J = \text{curl}_c \text{curl}_r$, second order

\mathbb{T} is the space of infinitesimal rigid motions

For weakly imposed symmetry the relevant sequence is

$$\mathbb{T} \hookrightarrow C^\infty(\mathbb{V} \times \mathbb{K}) \xrightarrow{(\text{grad}, -I)} C^\infty(\mathbb{M}) \xrightarrow{J} C^\infty(\mathbb{M}) \xrightarrow{\begin{pmatrix} \text{div} \\ \text{skw} \end{pmatrix}} C^\infty(\mathbb{V} \times \mathbb{K}) \longrightarrow 0$$

where J is defined to be zero on skew matrices.

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de Rham complex:

$$0 \rightarrow \mathbb{R} \xrightarrow{\subset} \Lambda^0(\Omega) \xrightarrow{d} \Lambda^1(\Omega) \xrightarrow{d} \dots \xrightarrow{d} \Lambda^n(\Omega) \rightarrow 0$$

$$\omega \in \Lambda^k(\Omega) \iff \omega_x \text{ is } k\text{-linear alternating form on } T_x\Omega \forall x \in \Omega$$

L^2 de Rham complex:

$$0 \rightarrow \mathbb{R} \xrightarrow{\subset} H\Lambda^0(\Omega) \xrightarrow{d} H\Lambda^1(\Omega) \xrightarrow{d} \dots \xrightarrow{d} H\Lambda^n(\Omega) \rightarrow 0$$

$$H\Lambda^k(\Omega) = \{ \omega \in L^2\Lambda^k(\Omega) \mid d\omega \in L^2\Lambda^{k+1}(\Omega) \}$$

Polynomial de Rham complexes

$$0 \rightarrow \mathbb{R} \xrightarrow{\subset} \mathcal{H}_r\Lambda^0 \xrightarrow{d} \mathcal{H}_{r-1}\Lambda^1 \xrightarrow{d} \dots \xrightarrow{d} \mathcal{H}_{r-n}\Lambda^n \rightarrow 0$$

$$0 \rightarrow \mathbb{R} \xrightarrow{\subset} \mathcal{P}_r\Lambda^0 \xrightarrow{d} \mathcal{P}_{r-1}\Lambda^1 \xrightarrow{d} \dots \xrightarrow{d} \mathcal{P}_{r-n}\Lambda^n \rightarrow 0$$

Koszul differential $\kappa : \Lambda^{k+1} \rightarrow \Lambda^k$:

$$(\kappa\omega)_x(v^1, \dots, v^k) = \omega_x(x, v^1, \dots, v^k)$$

• $\kappa : \mathcal{P}_r\Lambda^k \rightarrow \mathcal{P}_{r+1}\Lambda^{k-1}$ (c.f. $d : \mathcal{P}_{r+1}\Lambda^{k-1} \rightarrow \mathcal{P}_r\Lambda^k$)

$$0 \leftarrow \mathbb{R} \leftarrow \mathcal{P}_r\Lambda^0 \xleftarrow{\kappa} \mathcal{P}_{r-1}\Lambda^1 \xleftarrow{\kappa} \dots \xleftarrow{\kappa} \mathcal{P}_{r-n}\Lambda^n \leftarrow 0$$

Koszul complex

• $(d\kappa + \kappa d)\omega = (r + k)\omega \quad \forall \omega \in \mathcal{H}_r\Lambda^k$

κ is a contracting chain homotopy

• $\mathcal{H}_r\Lambda^k = d\mathcal{H}_{r+1}\Lambda^{k-1} \oplus \kappa\mathcal{H}_{r-1}\Lambda^{k+1}$

Using the Koszul differential, we define a special space of polynomial differential k -forms between $\mathcal{P}_r \Lambda^k$ and $\mathcal{P}_{r+1} \Lambda^k$:

$$\mathcal{P}_r^+ \Lambda^k := \mathcal{P}_r \Lambda^k + \kappa \mathcal{H}_r \Lambda^{k+1}$$

Note that $\mathcal{P}_r^+ \Lambda^0 = \mathcal{P}_{r+1} \Lambda^0$ and $\mathcal{P}_r^+ \Lambda^n = \mathcal{P}_r \Lambda^n$



*God made $\mathcal{P}_r \Lambda^k$ and $\mathcal{P}_r^+ \Lambda^k$,
all the rest is the work of man.*



The case $\Omega \subset \mathbb{R}^3$

$$\begin{array}{ccccccccccc}
 0 & \rightarrow & \mathbb{R} & \xrightarrow{\subset} & \Lambda^0(\Omega) & \xrightarrow{d} & \Lambda^1(\Omega) & \xrightarrow{d} & \Lambda^2(\Omega) & \xrightarrow{d} & \Lambda^3(\Omega) \rightarrow 0 \\
 0 & \rightarrow & \mathbb{R} & \xrightarrow{\subset} & C^\infty(\Omega) & \xrightarrow{\text{grad}} & C^\infty(\Omega, \mathbb{R}^3) & \xrightarrow{\text{curl}} & C^\infty(\Omega, \mathbb{R}^3) & \xrightarrow{\text{div}} & C^\infty(\Omega) \rightarrow 0
 \end{array}$$

smooth de Rham complex

$$0 \rightarrow \mathbb{R} \xrightarrow{\subset} H^1(\Omega) \xrightarrow{\text{grad}} H(\text{curl}) \xrightarrow{\text{curl}} H(\text{div}) \xrightarrow{\text{div}} L^2(\Omega) \rightarrow 0$$

L^2 de Rham complex

$$0 \rightarrow \mathbb{R} \xrightarrow{\subset} \mathcal{P}_r(\Omega) \xrightarrow{\text{grad}} \mathcal{P}_{r-1}(\Omega, \mathbb{R}^3) \xrightarrow{\text{curl}} \mathcal{P}_{r-2}(\Omega, \mathbb{R}^3) \xrightarrow{\text{div}} \mathcal{P}_{r-3}(\Omega) \rightarrow 0$$

polynomial de Rham complex

$$0 \leftarrow \mathbb{R} \leftarrow \mathcal{P}_r(\Omega) \xleftarrow{\cdot x} \mathcal{P}_{r-1}(\Omega, \mathbb{R}^3) \xleftarrow{\times x} \mathcal{P}_{r-2}(\Omega, \mathbb{R}^3) \xleftarrow{x} \mathcal{P}_{r-3}(\Omega) \leftarrow 0$$

Koszul complex

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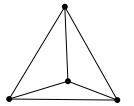
Piecewise polynomial differential forms

\mathcal{T} a triangulation of $\Omega \subset \mathbb{V}$ by n -simplices

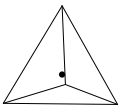
$$\mathcal{P}_r \Lambda^k(\mathcal{T}) := \{ \omega \in H\Lambda^k(\Omega) \mid \omega|_T \in \mathcal{P}_r \Lambda^k(T) \quad \forall T \in \mathcal{T} \}$$

$$\mathcal{P}_r^+ \Lambda^k(\mathcal{T}) := \{ \omega \in H\Lambda^k(\Omega) \mid \omega|_T \in \mathcal{P}_r^+ \Lambda^k(T) \quad \forall T \in \mathcal{T} \}$$

● $\mathcal{P}_r^+ \Lambda^0(\mathcal{T}) = \mathcal{P}_{r+1} \Lambda^0(\mathcal{T}) \subset H^1$ Lagrange elts



● $\mathcal{P}_r^+ \Lambda^n(\mathcal{T}) = \mathcal{P}_r \Lambda^n(\mathcal{T}) \subset L^2$ discontinuous elts



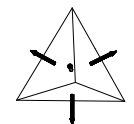
● $n = 3$: $\mathcal{P}_r^+ \Lambda^1(\mathcal{T}) \subset H(\text{curl})$ Nedelec 1st kind elts



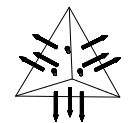
● $\mathcal{P}_r \Lambda^1(\mathcal{T}) \subset H(\text{curl})$ Nedelec 2nd kind elts



● $\mathcal{P}_r^+ \Lambda^2(\mathcal{T}) \subset H(\text{div})$ Raviart–Thomas elts



● $\mathcal{P}_r \Lambda^2(\mathcal{T}) \subset H(\text{div})$ Brezzi–Douglas–Marini elts



Degrees of freedom

T an n -simplex, $\Delta_d(T) =$ set of faces of dimension d , $0 \leq d \leq n$

DOF for $\mathcal{P}_r \Lambda^k(T)$:

$$u \mapsto \int_f u \wedge v, \quad v \in \mathcal{P}_{r-d-1+k}^+ \Lambda^{d-k}(f), \quad f \in \Delta_d(T), \quad k \leq d \leq n$$

DOF for $\mathcal{P}_r^+ \Lambda^k(T)$:

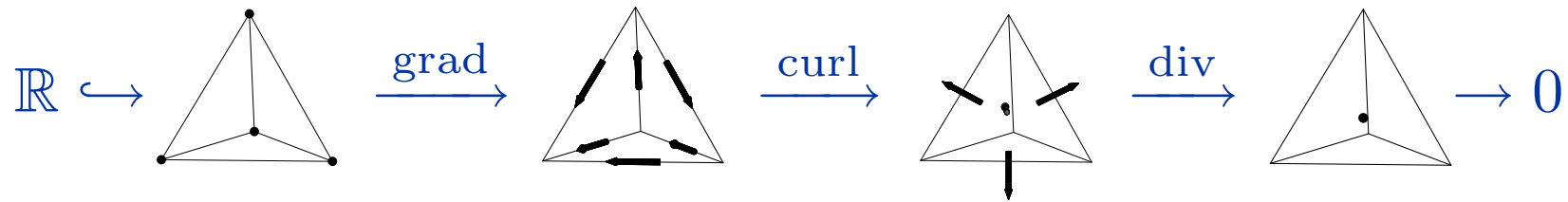
$$u \mapsto \int_f u \wedge v, \quad v \in \mathcal{P}_{r-d+k} \Lambda^{d-k}(f), \quad f \in \Delta_d(T_n), \quad k \leq d \leq n$$

Discrete exact sequences

For every $r \geq 0$, the $\mathcal{P}_r^+ \Lambda^k$ spaces give an exact piecewise polynomial subcomplex:

$$0 \rightarrow \mathbb{R} \xrightarrow{\subset} \mathcal{P}_r^+ \Lambda^0(\mathcal{T}) \xrightarrow{d} \mathcal{P}_r^+ \Lambda^1(\mathcal{T}) \xrightarrow{d} \dots \xrightarrow{d} \mathcal{P}_r^+ \Lambda^n(\mathcal{T}) \rightarrow 0$$

For $n = 3$, $r = 0$ these are the Whitney elements:



For all r , the natural projections $\Pi_{r+}^k : \Lambda^k(\Omega) \rightarrow \mathcal{P}_r^+ \Lambda^k(\mathcal{T})$ relate this to the de Rham sequence commutatively:

$$\begin{array}{ccccccc} 0 \rightarrow \mathbb{R} & \xrightarrow{\subset} & \Lambda^0(\Omega) & \xrightarrow{d} & \Lambda^1(\Omega) & \xrightarrow{d} & \dots \xrightarrow{d} & \Lambda^n(\Omega) \rightarrow 0 \\ & & \Pi_{r+}^0 \downarrow & & \Pi_{r+}^1 \downarrow & & & \Pi_{r+}^n \downarrow \\ 0 \rightarrow \mathbb{R} & \xrightarrow{\subset} & \mathcal{P}_r^+ \Lambda^0(\mathcal{T}) & \xrightarrow{d} & \mathcal{P}_r^+ \Lambda^1(\mathcal{T}) & \xrightarrow{d} & \dots \xrightarrow{d} & \mathcal{P}_r^+ \Lambda^n(\mathcal{T}) \rightarrow 0 \end{array}$$

Other discrete exact sequences

Another exact sequence ending at $\mathcal{P}_r\Lambda^n(\mathcal{T})$ uses the $\mathcal{P}_s\Lambda^k$ spaces of increasing degree: (Demkowicz-Vardepetyan '99):

$$\mathbb{R} \xrightarrow{\subset} \mathcal{P}_{r+n}\Lambda^0(\mathcal{T}) \xrightarrow{d} \mathcal{P}_{r+n-1}\Lambda^1(\mathcal{T}) \xrightarrow{d} \dots \xrightarrow{d} \mathcal{P}_r\Lambda^n(\mathcal{T}) \rightarrow 0$$

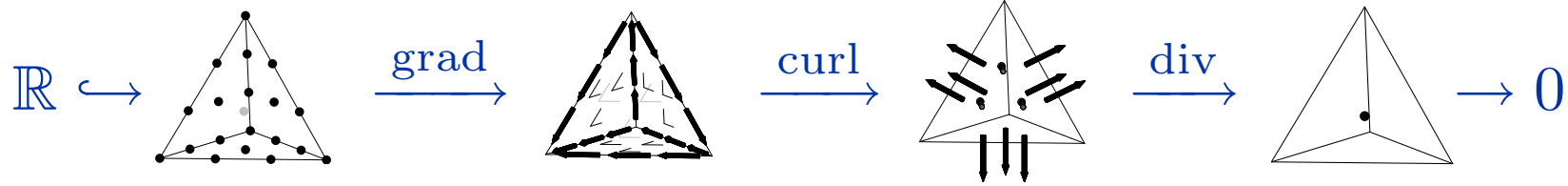
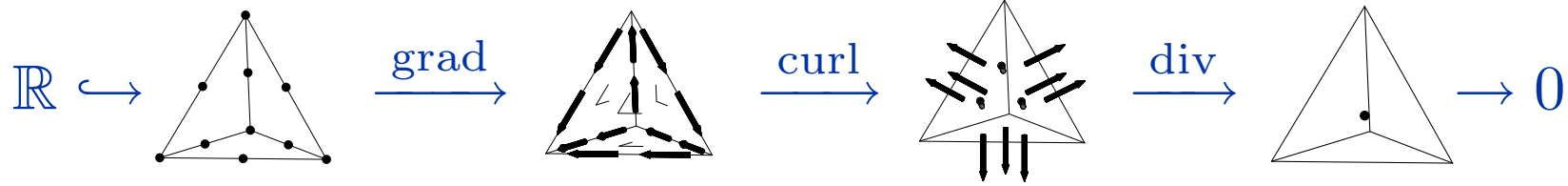
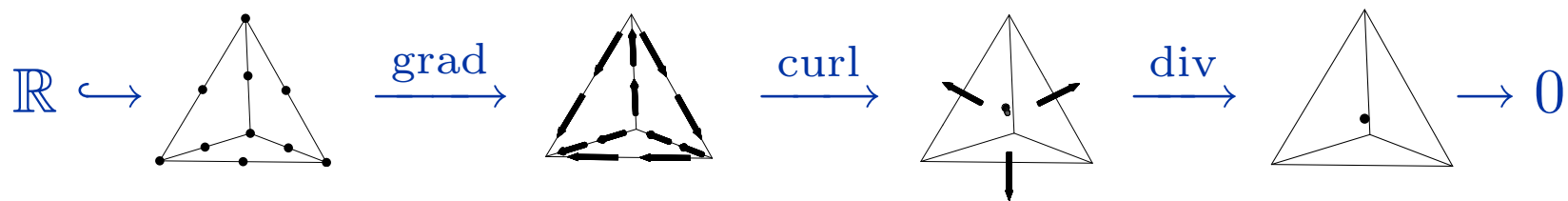
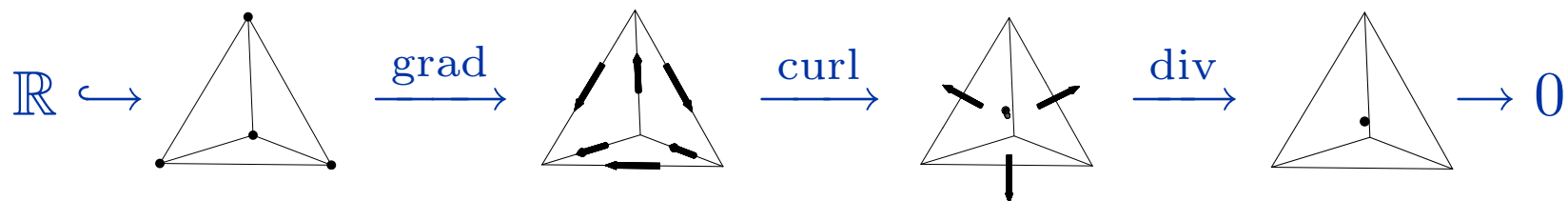
In fact, these are just the extreme cases. There are 2^{n-1} pw polynomial de Rham sequences in n dimensions. All relate to the de Rham complex through a commuting diagram.

For $n = 3$ the other two are:

$$\mathbb{R} \xrightarrow{\subset} \mathcal{P}_{r+2}\Lambda^0(\mathcal{T}) \xrightarrow{d} \mathcal{P}_{r+1}\Lambda^1(\mathcal{T}) \xrightarrow{d} \mathcal{P}_r^+\Lambda^2(\mathcal{T}) \xrightarrow{d} \mathcal{P}_r\Lambda^3(\mathcal{T}) \rightarrow 0$$

$$\mathbb{R} \xrightarrow{\subset} \mathcal{P}_{r+2}\Lambda^0(\mathcal{T}) \xrightarrow{d} \mathcal{P}_{r+1}^+\Lambda^1(\mathcal{T}) \xrightarrow{d} \mathcal{P}_{r+1}\Lambda^2(\mathcal{T}) \xrightarrow{d} \mathcal{P}_r\Lambda^3(\mathcal{T}) \rightarrow 0$$

The four sequences ending with $\mathcal{P}_0\Lambda^3(\mathcal{T})$ in 3D



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Bernstein–Gelfand–Gelfand construction, I

1. Start with the de Rham sequence with values in $\mathbb{W} := \mathbb{K} \times \mathbb{V}$:

$$\mathbb{W} \hookrightarrow \Lambda^0(\Omega; \mathbb{W}) \xrightarrow{\begin{pmatrix} d & 0 \\ 0 & d \end{pmatrix}} \Lambda^1(\Omega; \mathbb{W}) \xrightarrow{\begin{pmatrix} d & 0 \\ 0 & d \end{pmatrix}} \Lambda^2(\Omega; \mathbb{W}) \xrightarrow{\begin{pmatrix} d & 0 \\ 0 & d \end{pmatrix}} \Lambda^3(\Omega; \mathbb{W}) \longrightarrow 0$$

2. For any $x \in \mathbb{R}^3$ define $K_x : \mathbb{V} \rightarrow \mathbb{K}$ by $K_x v = 2 \operatorname{skw}(xv^T)$ and $K : \Lambda^k(\Omega; \mathbb{V}) \rightarrow \Lambda^k(\Omega; \mathbb{K})$ by

$$(K\omega)_x(v_1, \dots, v_k) = K_x[\omega_x(v_1, \dots, v_k)].$$

3. Define automorphisms $\Phi : \Lambda^k(\mathbb{W}) \rightarrow \Lambda^k(\mathbb{W})$ by

$$\Phi = \begin{pmatrix} I & K \\ 0 & I \end{pmatrix}, \quad \Phi^{-1} = \begin{pmatrix} I & -K \\ 0 & I \end{pmatrix}$$

4. Define $\mathcal{A} = \Phi \circ \begin{pmatrix} d & 0 \\ 0 & d \end{pmatrix} \circ \Phi^{-1}$ to get a modified de Rham sequence:

$$\Phi(\mathbb{W}) \hookrightarrow \Lambda^0(\mathbb{W}) \xrightarrow{\mathcal{A}} \Lambda^1(\mathbb{W}) \xrightarrow{\mathcal{A}} \Lambda^2(\mathbb{W}) \xrightarrow{\mathcal{A}} \Lambda^3(\mathbb{W}) \longrightarrow 0$$

Bernstein–Gelfand–Gelfand construction, II

5. Note that $\mathcal{A} = \begin{pmatrix} d & -S \\ 0 & d \end{pmatrix}$, where $S = dK - Kd : \Lambda^k(\Omega; \mathbb{V}) \rightarrow \Lambda^{k+1}(\Omega; \mathbb{K})$ is given by

$$(S\omega)_x(v_1, \dots, v_{k+1}) = \sum_{\mu} \text{sign}(\mu) K_{v_{\mu_{k+1}}} \omega_x(v_{\mu_1}, \dots, v_{\mu_k}).$$

Properties: S is algebraic; for $k = 1$, S is an isomorphism; $dS = -Sd$
 $d(dK - Kd) = -dKd = -(dK - Kd)d$

6. Define subspaces $\Gamma^k \subset \Lambda^k(\Omega; \mathbb{W})$ satisfying $\mathcal{A}(\Gamma^k) \subset \Gamma^{k+1}$ and projections

$$\pi_k : \Lambda^k(\Omega; \mathbb{W}) \rightarrow \Gamma^k \quad \text{satisfying} \quad \pi_{k+1}\mathcal{A} = \mathcal{A}\pi_k :$$

$$\Gamma^0 = \Lambda^0(\Omega; \mathbb{W}), \quad \pi_0 = id, \quad \Gamma^3 = \Lambda^3(\Omega; \mathbb{W}), \quad \pi_3 = id,$$

$$\Gamma^1 = \{ (\omega, \mu) \in \Lambda^1(\Omega; \mathbb{W}) : d\omega = S\mu \}, \quad \Gamma^2 = \{ (\omega, \mu) \in \Lambda^2(\Omega; \mathbb{W}) : \omega = 0 \}$$

$$\pi^1 = \begin{pmatrix} I & 0 \\ S^{-1}d & 0 \end{pmatrix} : \Lambda^1(\Omega; \mathbb{W}) \rightarrow \Gamma^1, \quad \pi^2 = \begin{pmatrix} 0 & 0 \\ dS^{-1} & I \end{pmatrix} : \Lambda^2(\Omega; \mathbb{W}) \rightarrow \Gamma^2.$$

Bernstein–Gelfand–Gelfand construction, III

6. The following diagram commutes (use $dS = -Sd$):

$$\begin{array}{ccccccccccc} \Phi(\mathbb{W}) & \hookrightarrow & \Lambda^0(\mathbb{W}) & \xrightarrow{\mathcal{A}} & \Lambda^1(\mathbb{W}) & \xrightarrow{\mathcal{A}} & \Lambda^2(\mathbb{W}) & \xrightarrow{\mathcal{A}} & \Lambda^3(\mathbb{W}) & \rightarrow & 0 \\ & & \downarrow \pi_0 & & \downarrow \pi^1 & & \downarrow \pi^2 & & \downarrow \pi_3 & & \\ \Phi(\mathbb{W}) & \hookrightarrow & \Gamma^0 & \xrightarrow{\mathcal{A}} & \Gamma^1 & \xrightarrow{\mathcal{A}} & \Gamma^2 & \xrightarrow{\mathcal{A}} & \Gamma^3 & \rightarrow & 0 \end{array}$$

Therefore, the subcomplex on the bottom row is exact.

7. *This subcomplex may be identified with the elasticity complex.*

Bernstein–Gelfand–Gelfand construction, concluded

$$\begin{array}{ccccccc}
 \Gamma^0 & \xrightarrow{\mathcal{A}} & \Gamma^1 & \xrightarrow{\mathcal{A}} & \Gamma^2 & \xrightarrow{\mathcal{A}} & \Gamma^3 \\
 = & & \cong & & \cong & & = \\
 \Lambda^0(\mathbb{K} \times \mathbb{V}) & \xrightarrow{(d_0, -S_0)} & \Lambda^1(\Omega; \mathbb{K}) & \xrightarrow{d_1 \circ S_1^{-1} \circ d_1} & \Lambda^2(\Omega; \mathbb{V}) & \xrightarrow{(-S_2, d_2)^T} & \Lambda^3(\mathbb{K} \times \mathbb{V})
 \end{array}$$

With the identifications

$$\Lambda^0(\mathbb{K} \times \mathbb{V}) \leftrightarrow C^\infty(\mathbb{V} \times \mathbb{K})$$

$$\Lambda^1(\mathbb{K}) \leftrightarrow C^\infty(\mathbb{M})$$

$$\Lambda^2(\mathbb{K}) \leftrightarrow C^\infty(M)$$

$$\Lambda^3(\mathbb{K} \times \mathbb{V}) \leftrightarrow C^\infty(\mathbb{V} \times \mathbb{K})$$

this becomes the elasticity sequence

$$\mathcal{T}' \hookrightarrow C^\infty(\mathbb{V} \times \mathbb{K}) \xrightarrow{(\text{grad}, -I)} C^\infty(\mathbb{M}) \xrightarrow{J} C^\infty(\mathbb{M}) \xrightarrow{(\text{div}, \text{skw})^T} C^\infty(\mathbb{V} \times \mathbb{K}) \rightarrow 0$$