

New chapter - integration to produce signed volume where sign \pm depends on orientation. On curve, two clear choices of orientation: e.g. circle has clockwise/counterclockwise. What about surface? Less clear. Roughly - linearize to consider tangent hyperplanes at each point, and attach orientation to tangent hyperplanes (i.e. k -vector spaces in \mathbb{R}^n) according to choice of basis. Subtle -

Also need new objects to integrate, that are responsive to this orientation. With absolute volume $|d^k x|$ or $|\det T| \cdot |d^k x|$ and $|\det(T)|$ not sensitive to swapping of rows.

Some fixes: ① $\det(T)$ is sensitive to swapping of rows. changes by -1 as we'd like -

② if manifold is parametrized: $\gamma: U \rightarrow M$ then γ indicates an orientation. Think again about unit circle: $\begin{bmatrix} \cos t \\ \sin t \end{bmatrix}$: counterclockwise $\begin{bmatrix} \sin t \\ \cos t \end{bmatrix}$: clockwise. Turns out same is true in higher dimensions.

Expanding on ①, what is it about \det that makes it respect orientation is antisymmetric. (also want it to be linear in each component.)

Definition: A k -form on \mathbb{R}^n is a function $\phi: (\mathbb{R}^n)^k \rightarrow \mathbb{R}$ with

- linear in each factor
- antisymmetric.

 k -vectors in \mathbb{R}^n

If $k = n$, then these are precisely our earlier defining properties of determinant.

If $k \geq n$, then any k vectors are linearly dependent.

Write, say $\vec{v}_k = \sum_{i=1}^{k-1} c_i \vec{v}_i$. Then k -form takes

$$\phi(v_1, \dots, v_k) = \phi(v_1, \dots, v_{k-1}, \sum c_i v_i) = \sum_i c_i \underbrace{\phi(v_1, \dots, v_{k-1}, v_i)}_{\text{linearity}}$$

So there are no nonzero k forms if $k > n$.

If $k < n$, might try

$$\sqrt{\det(v_1, \dots, v_k)^T (v_1, \dots, v_k)}$$

Doomed to fail since
always positive so
can't be antisymmetric.

(also fails to be linear in
variables. Try to
check this.)

≈ 0 since
anti-symmetry
says switching i^{th}
position and k^{th}
position produces
neg. sgn. On
other hand, both
have v_i 's as
component.

Given k vectors in \mathbb{R}^n , arrange them in matrix as usual:

$$n \text{ rows } \left\{ \begin{bmatrix} | & & | \\ v_1 & \dots & v_k \\ | & & | \end{bmatrix} \right. \quad \begin{array}{l} \text{How can we produce scalar-valued} \\ \text{antisymmetric, multilinear function?} \end{array}$$

Ans.: Select k rows and take determinant.

e.g. $k=3, n=7$ could select any three rows in $1, 2, \dots, 7$

We have funny notation for this which will be clearer later. For now, just use it. $dx_1 \wedge dx_4 \wedge dx_5$: pick rows 1, 4, 5. Order matters.

so 4,1,5 with notation $dx_4 \wedge dx_1 \wedge dx_5 = - dx_1 \wedge dx_4 \wedge dx_5$.
 (meaning select row 4 first, etc.)

e.g.

$$\begin{bmatrix} 3 & 5 & 6 \\ 1 & -2 & -1 \\ 0 & 0 & 3 \\ 2 & 0 & 0 \\ -4 & 1 & 2 \\ 0 & 2 & 1 \\ 7 & 3 & 0 \end{bmatrix}$$

$$\text{then } dx_1 \wedge dx_4 \wedge dx_5 (v_1, v_2, v_3)$$

$$= \det \begin{bmatrix} 3 & 5 & 6 \\ 2 & 0 & 0 \\ 4 & 1 & 2 \end{bmatrix}$$

$$v_1, v_2, v_3$$

$$= -5 \cdot 4 + 6 \cdot 2 = \boxed{-8}$$

What have we done geometrically?

call them i_1, \dots, i_k .

Selecting k rows means taking a projection from $\mathbb{R}^n \rightarrow \mathbb{R}^k$

where subspace \mathbb{R}^k is spanned by basis e_{i_1}, \dots, e_{i_k}

Then compute area of the k -parallelogram obtained in projection.

e.g. $k=2, n=3$

$$\begin{bmatrix} v_1 & w_1 \\ v_2 & w_2 \\ v_3 & w_3 \end{bmatrix}$$

mapped by

$$\det \begin{bmatrix} v_1 & w_1 \\ v_2 & w_2 \end{bmatrix}$$

$dx_1 \wedge dx_2$ to



Even better, it is the signed area of parallelogram.

1-forms: signed length (degenerate parallelogram)

area of 1 -gram
in x_1, x_2
plane

For parallelograms, get positive answer if \vec{v} lies clockwise from \vec{w} .



(remember \vec{e}_1 clockwise from \vec{e}_2 in standard basis)

$$\leftrightarrow \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

What is the structure of the set of k -forms? Are we missing some?

No. : refer to forms with $dx_{i_1} \wedge \dots \wedge dx_{i_k}$ with $i_1 < i_2 < \dots < i_k$ as "elementary k -forms". We can add and scalar multiply k forms and get another k -form. (i.e. - they form a vector space.)

claim : elementary k -forms are a basis for space of k -forms on \mathbb{R}^n .

Even stronger : Given k -form ϕ , we can write

↑
rather,
more specific.

$$\phi = \sum_{i_1 < \dots < i_k} a_{i_1, \dots, i_k} \underbrace{dx_{i_1} \wedge \dots \wedge dx_{i_k}}_{\parallel} \phi(e_{i_1}, \dots, e_{i_k})$$

Hence dimension of space of k -forms in \mathbb{R}^n is "n choose k "

$$\binom{n}{k} := \frac{n!}{k!(n-k)!}$$