

Catastrophes and Resilience of a Zero-Dim Climate System

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Motivation: exhibit catastrophes in realistic situations

K. Fraedrich, "Catastrophes and resilience of a zero dim'l climate system w/ ice-albedo and greenhouse feedback" *Quart. J. R. Met. Soc.* (1979)

Definition

A catastrophe is a singularity (of a smooth map), exhibited by (small) changes of an external parameter.

- The names for catastrophes and bifurcations differ, but they refer to the same phenomena.

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- The author's goal is to exhibit fold catastrophes and cusp catastrophes.

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- 3 Along the way: bifurcation diagrams

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Assumptions

$$c \frac{dT}{dt} = R \downarrow - R \uparrow,$$

where

- T is temperature,
- t is time, and
- $R \downarrow$ and $R \uparrow$ are incoming and outgoing radiation.

Here, c is a positive constant, determined by external measurements.

Assumptions: incoming radiation

$$R_{\downarrow} = \frac{1}{4} \mu I_0 (1 - \alpha_p).$$

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- ▶ For Fraedrich:

$$\alpha_p = a_2 - b_2 T^2$$

Assumptions: outgoing radiation

$$R \uparrow = \epsilon_{sa} \sigma T^4 = \epsilon_s \sigma T^4 - \epsilon_a \sigma T^4,$$

(Stefan-Boltzmann)

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Usually, a linear approximation is used.

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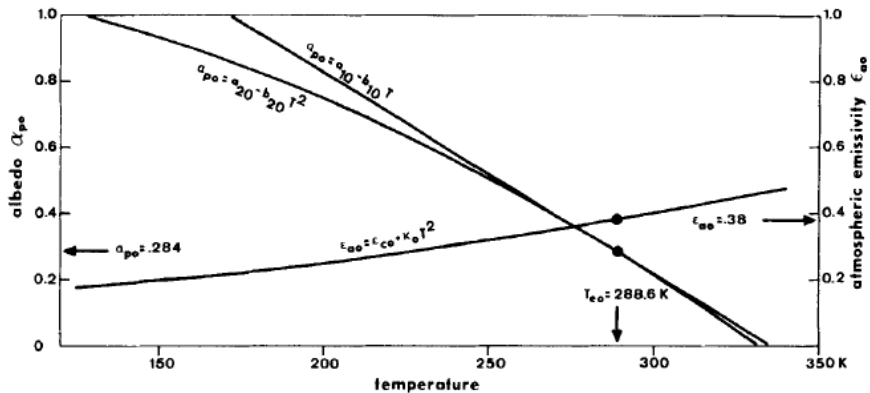
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Picture of temp feedbacks (from p. 149)



Use equations

$$c \frac{dT}{dt} = R_{\downarrow} - R_{\uparrow}; \quad (1)$$

$$R_{\downarrow} = \frac{1}{4} \mu I_0 (1 - \alpha_p), \quad (2)$$

where α_p is a constant;

$$R_{\uparrow} = \epsilon_{sa} \sigma T^4, \quad (3)$$

where $\epsilon_{sa} = \epsilon_s - \epsilon_a$, which are constants.

Let $x = (\mu, \alpha_p, \epsilon_s, \epsilon_a, c)$.

First model - solving

Let $\frac{dT}{dt} = f(T; x)$, where x is the vector of parameter values.

Let $T_e(x)$ stand for the temperature(s) at which $\left. \frac{dT}{dt} \right|_{T_e} = f(T_e; x) = 0$.

- Linearization about $T = T_e$:

$$dT/dt \approx f(T_e; x) + \left. \frac{df}{dT} \right|_{T_e} (T - T_e) = -\lambda(T - T_e).$$

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- ▶ Unstable:

$$-\lambda = \left. \frac{df}{dT} \right|_{T_e} > 0.$$

First model - solving

Want:

$$\begin{aligned} f(T_e; x) &= 0, \\ \left. \frac{df}{dT} \right|_{T_e} &= \frac{d}{dT} \frac{1}{c} \left(-\epsilon_{sa} \sigma T^4 + \frac{1}{4} \mu l_0 (1 - \alpha_p) \right) \Big|_{T_e} \\ &= -4(\epsilon_{sa} \sigma / c) T_e^3 < 0. \end{aligned}$$

We have a single, stable equilibrium:

$$T_e = \sqrt[4]{\frac{\mu l_0}{4 \epsilon_{sa} \sigma} (1 - \alpha_p)}.$$

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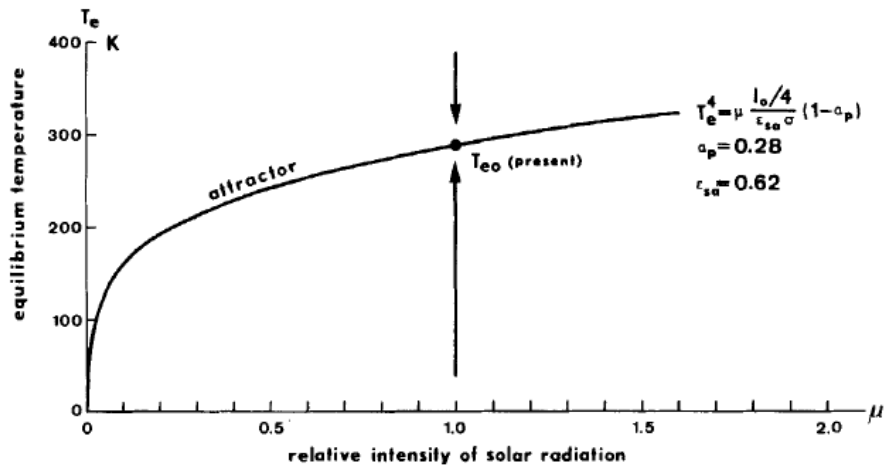
$$T_e = \sqrt[4]{\frac{\mu I_0}{4\epsilon_{sa}\sigma}(1 - \alpha_p)}.$$

Use

$$x_0 = (\alpha_{p0} = 0.284, \epsilon_{sa0} = 0.62, \mu_0 = 1, c_0 = 10^8 \text{ kgK}^{-1}\text{s}^{-2}),$$

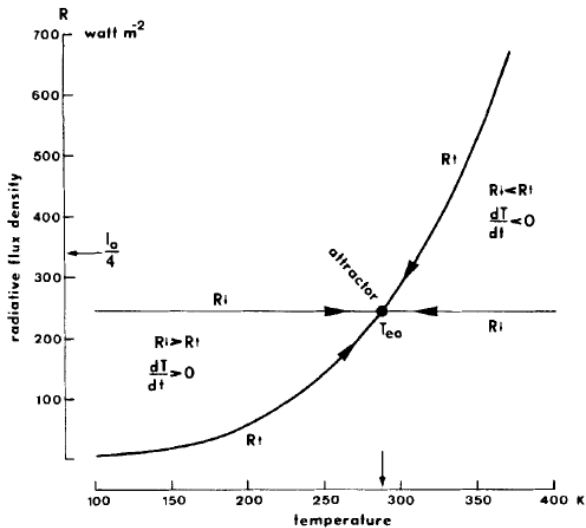
and to get the “present day” (1979) averaged equilibrium: $T_{e0} = 288.6\text{K}$.

First model - equilibrium diagram



p. 152

First model - phase portrait



Second model - ice albedo

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- Fraedrich uses

$$\alpha_{p0} = a_{20} - b_{20}T^2,$$

where a_{20} and b_{20} are chosen to match present day albedo, and

$$\alpha_{p0} = \frac{d(a_{10} - b_{10}T)}{dt}$$

at present day.

Second model - ice albedo feedback

This time,

$$\frac{dT}{dt} = (1/c) \left(-\epsilon_{sa}\sigma T^4 + \frac{1}{4}\mu l_0 b_2 T^2 + \frac{1}{4}\mu l_0(1 - a_2) \right) = f(T; x).$$

The equilibria T_e are again where $f(T_e; x) = 0$, where

$$x = (a_2, b_2, \epsilon_{sa}, \mu, c).$$

Second model - equilibria

Equilibria are (positive) solutions to

$$T_e^4 - mT_e^2 + n = 0,$$

$$\text{where } m = \frac{\mu l_0}{4\epsilon_{sa}\sigma} b_2,$$

$$n = -\frac{\mu l_0}{4\epsilon_{sa}\sigma} (1 - a_2).$$

Second model - ice albedo - new parameters

Allowing μ to vary:

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 - ▶ What is the sign of $\frac{1}{4}m^2 - n$?

Second model - stability of equilibria

Equilibria:

$$T_e^\pm = \sqrt{\frac{1}{2}m \pm \sqrt{\frac{1}{4}m^2 - n}},$$

$$\frac{dT}{dt} = \frac{1}{c}f(T; x),$$

Assume at least one solution ($\frac{1}{4}m^2 - n \geq 0$) Determine the stability the same way as in the trivial model.

- Linearize about T_e : $T(t; x) \approx \frac{df}{dT}\bigg|_{T_e}(T - T_e)$

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$$-\frac{4\epsilon_{sa}}{c} (T_e^2 - m/2) T_e < 0$$

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- Unstable:

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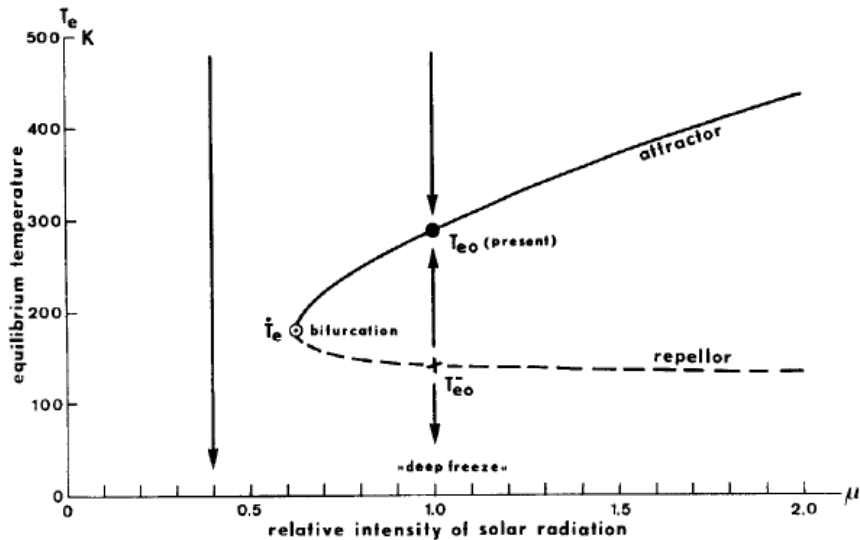
$$-\frac{4\epsilon_{sa}}{c} (T_e^2 - m/2) T_e < 0$$

- Unstable:

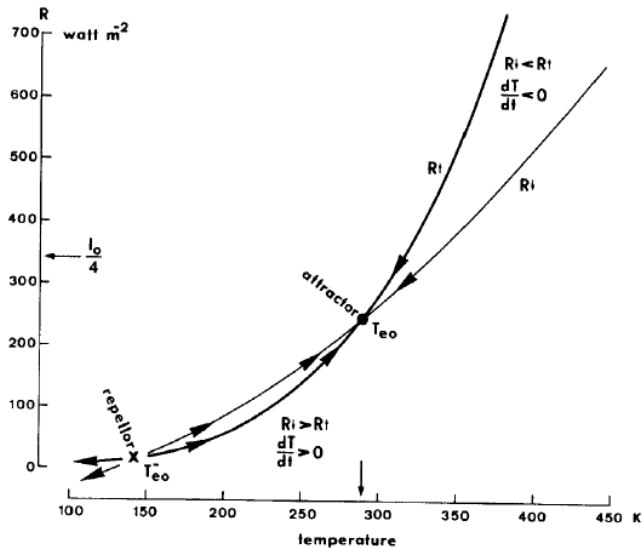
$$-\frac{4\epsilon_{sa}}{c} (T_e^2 - m/2) T_e > 0$$

- T_e^+ stable, T_e^- unstable

Second model - ice albedo - equilibria

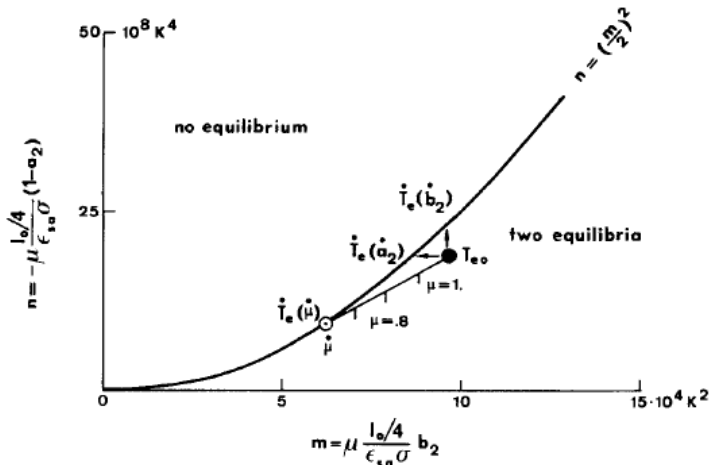


Second model - ice albedo - phase portrait



Second model - bifurcation diagram

$$\text{Equilibria: } T_e^\pm = \sqrt{\frac{1}{2}m \pm \sqrt{\frac{1}{4}m^2 - n}}$$



Third model

Greenhouse feedback, no ice albedo:

$$c \frac{dT}{dt} = R_{\downarrow} - R_{\uparrow}$$

with

$$R_{\downarrow} = \frac{1}{4} \mu I_0 (1 - \alpha_p),$$

where α_p is held constant;

$$R_{\uparrow} = \epsilon_s \sigma T^4 - \epsilon_a \sigma T^4,$$

where $\epsilon_a = \epsilon_c + \kappa T^2$, (ϵ_c is CO_2 emittance), so

$$R_{\uparrow} = \epsilon_s \sigma T^4 - \epsilon_c \sigma T^4 - \kappa \sigma T^6.$$

Third model - equilibria

Combining the previous equations gives

$$\frac{dT}{dt} = \frac{1}{c} \left(\kappa\sigma T^6 - \epsilon_{sc}\sigma T^4 + \frac{1}{4}\mu l_0(1 - \alpha_p) \right),$$

where $\epsilon_{sc} = \epsilon_s - \epsilon_c$.

Equilibria satisfy

$$T_e^6 - \frac{\epsilon_{sc}}{\kappa} T_e^4 + \frac{\mu l_0}{4\kappa\sigma}(1 - \alpha_p) = 0.$$

Third model - equilibria

Equilibria:

$$T_e^6 - \frac{\epsilon_{sc}}{\kappa} T_e^4 + \frac{\mu l_0}{4\kappa\sigma}(1 - \alpha_p) = 0.$$

To solve, let $y = -\frac{\epsilon_{sc}}{3\kappa} + T_e^2$ and get

$$y^3 - uy + v = 0,$$

where

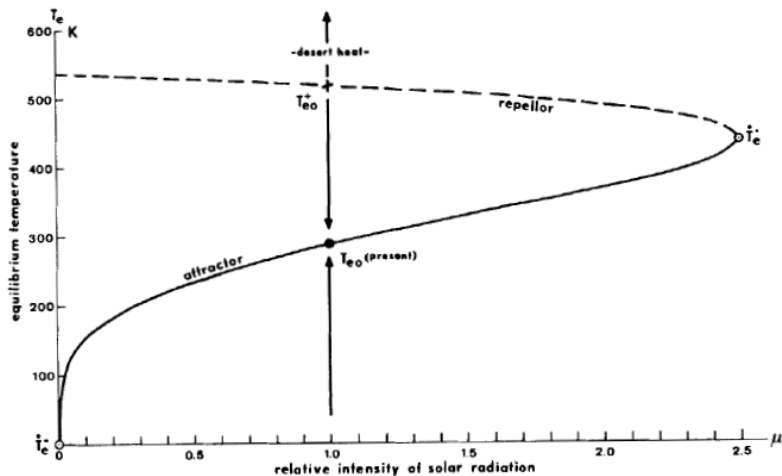
$$u = 3 \left(\frac{\epsilon_{sc}}{3\kappa} \right)^2, \quad v = -2 \left(\frac{\epsilon_{sc}}{3\kappa} \right)^3 + \frac{\mu l_0}{4\kappa\sigma}(1 - \alpha_p).$$

We get

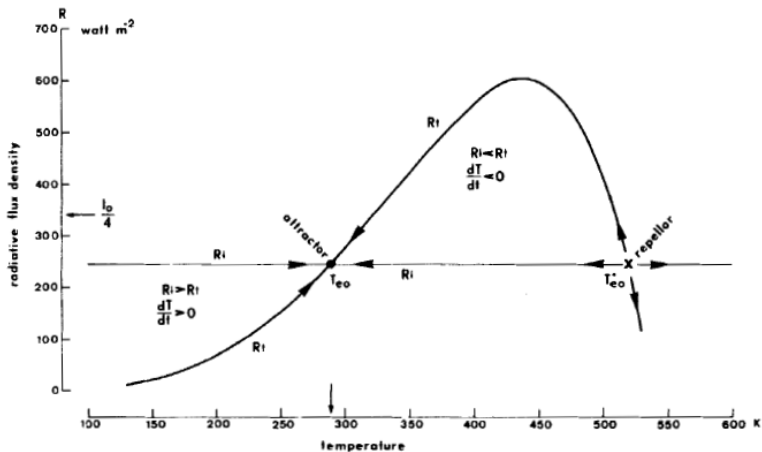
$$T_e = \sqrt{\frac{\epsilon_{sc}}{3\kappa} + 2\sqrt{u/3A}},$$

where A depends on u and v .

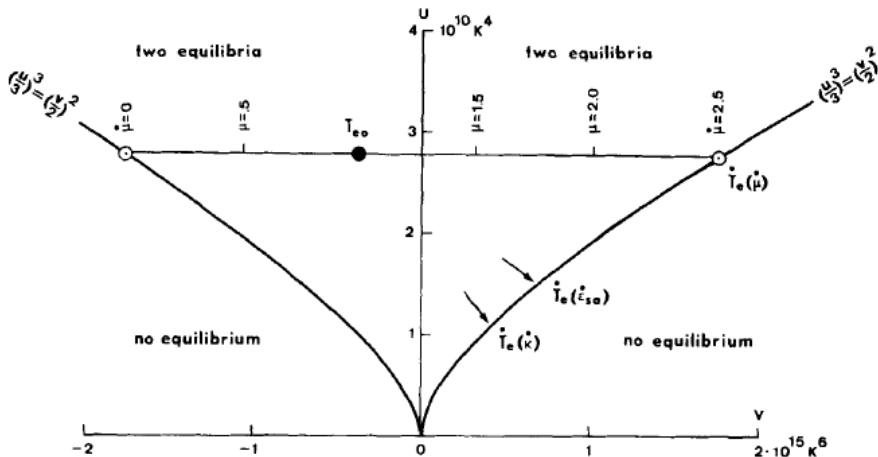
Third model - equilibria diagram



Third model - phase portrait



Third model - bifurcation diagram



Combining greenhouse temperature feedback and ice temperature feedback:

$$\alpha_p = a_2 - b_2 T^2, \quad \epsilon_a = \epsilon_c + \kappa T^2,$$

we get

$$\frac{dT}{dt} = \frac{1}{c} \left(\kappa \sigma T^6 - \epsilon_{sc} \sigma T^4 + \frac{1}{4} \mu l_0 b_2 T^2 + \frac{1}{4} \mu l_0 (1 - a_2) \right).$$

The equilibria are solutions to

$$T_e^6 - T_e^4 \frac{\epsilon_{sc}}{\kappa} + T_e^2 \left(\frac{\mu l_0}{4 \kappa \sigma} \right) b_2 + \frac{\mu l_0}{4 \kappa \sigma} (1 - a_2) = 0.$$

Fourth model - solving

$$T_e^6 - T_e^4 \frac{\epsilon_{sc}}{\kappa} + T_e^2 \left(\frac{\mu l_0}{4\kappa\sigma} \right) b_2 + \frac{\mu l_0}{4\kappa\sigma} (1 - a_2) = 0$$

Let $y = -\frac{\epsilon_{sc}}{3\kappa} + T_e^2$, and this becomes

$$y^3 - py + q = 0,$$

where

$$p = 3 \left(\frac{\epsilon_{sc}}{3\kappa} \right)^2 - \frac{\mu l_0}{4\kappa\sigma} b_2$$
$$q = -2 \left(\frac{\epsilon_{sc}}{3\kappa} \right)^3 + \frac{\epsilon_{sc} \mu l_0}{3 \cdot 4\kappa^2 \sigma} b_2 + \frac{\mu l_0}{4\kappa\sigma} (1 - a_2).$$

The parameters are $x = (a_2, b_2, \epsilon_s, \epsilon_c, \kappa, \mu)$.

Fourth model - stability

At $T = T_e$, stability is determined by

$$-\lambda = \left. \frac{df}{dT} \right|_{T_e} = \frac{\kappa\sigma}{c} \left(T_e^4 - \frac{2\epsilon_{sc}}{3\kappa} T_e^2 + \frac{\mu l_0 b_2}{4 \cdot 3\kappa\sigma} \right) 6T_e$$

- Stable: $-\lambda < 0$

With certain parameter values, there are three equilibrium branches: one attractor, two repellers.

Fourth model - stability

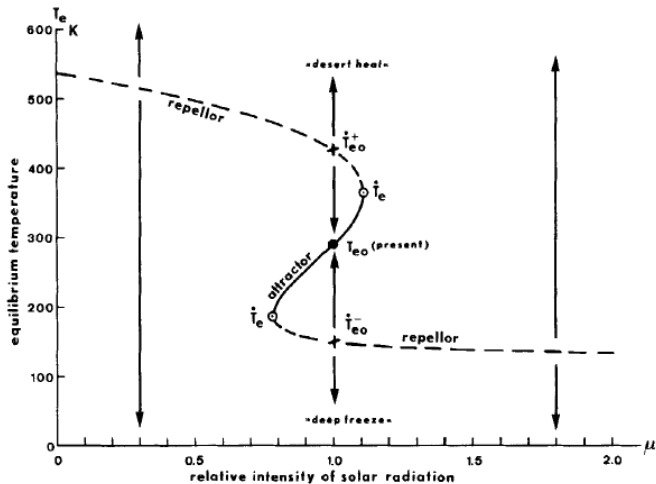
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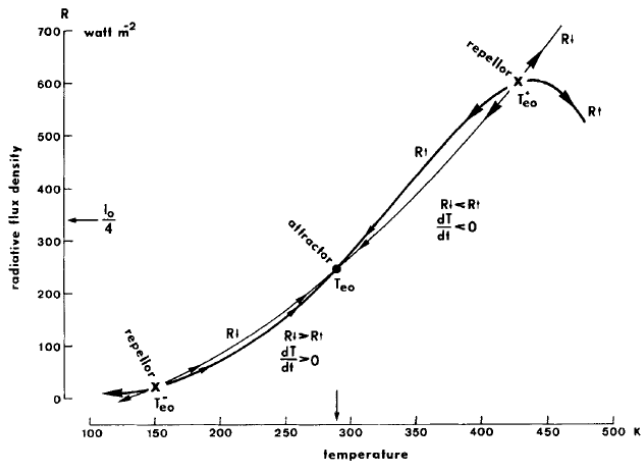
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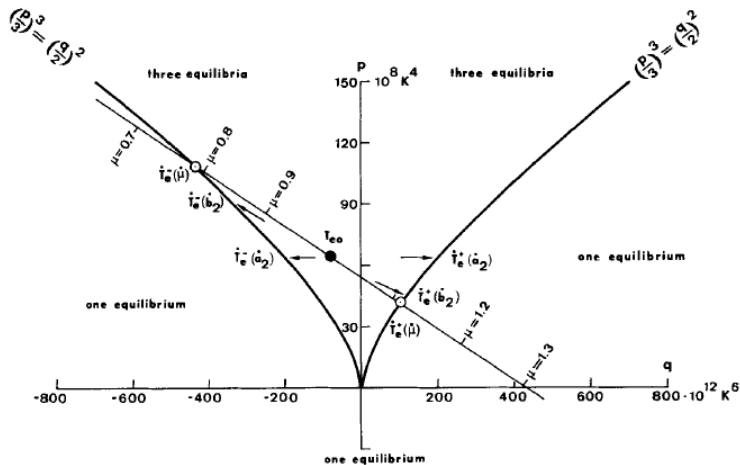
Fourth model - equilibria diagram



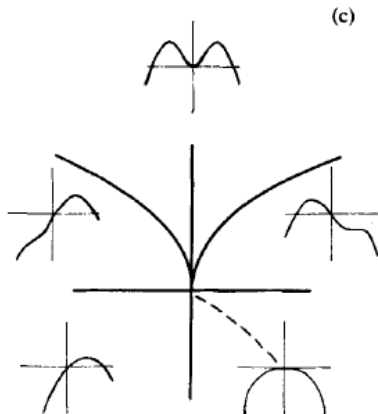
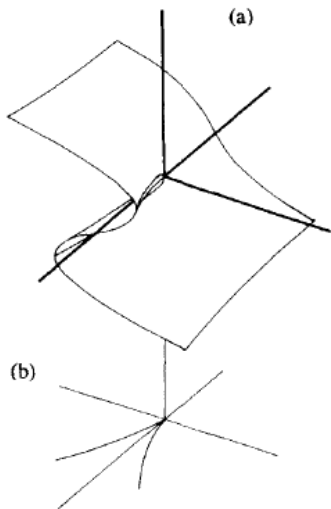
Fourth model - phase portrait



Fourth model - bifurcation diagram



Fourth model - some perspective



- 1 K. Fraedrich. “Catastrophes and resilience of a zero-dimensional climate system with ice-albedo and greenhouse feedback.” *Quart. J. R. Met. Soc.* **105**, 147-167 (1979).