

Poisson Structures and Integrability

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Hamiltonian Systems

M — phase space; $\dim M = 2n$

Local coordinates: $z = (p, q) = (p^1, \dots, p^n, q^1, \dots, q^n)$

Canonical Hamiltonian system:

$$\frac{dz}{dt} = J \nabla H \quad J = \begin{pmatrix} O & -I \\ I & O \end{pmatrix}$$

Equivalently:

$$\frac{dp^i}{dt} = - \frac{\partial H}{\partial q^i} \quad \frac{dq^i}{dt} = \frac{\partial H}{\partial p^i}$$

Lagrange Bracket (1808):

$$[u, v] = \sum_{i=1}^n \frac{\partial p^i}{\partial u} \frac{\partial q^i}{\partial v} - \frac{\partial q^i}{\partial u} \frac{\partial p^i}{\partial v}$$

(Canonical) Poisson Bracket (1809):

$$\{u, v\} = \sum_{i=1}^n \frac{\partial u}{\partial p^i} \frac{\partial v}{\partial q^i} - \frac{\partial u}{\partial q^i} \frac{\partial v}{\partial p^i}$$

Given functions u_1, \dots, u_{2n} , the $(2n) \times (2n)$ matrices with respective entries

$$[u_i, u_j] \qquad \{u_i, u_j\} \qquad i, j = 1, \dots, 2n$$

are mutually inverse.

Canonical Poisson Bracket

$$\{ F, H \} = \nabla F^T J \nabla H = \sum_{i=1}^n \frac{\partial F}{\partial p^i} \frac{\partial H}{\partial q^i} - \frac{\partial F}{\partial q^i} \frac{\partial H}{\partial p^i}$$

\implies Poisson (1809)

Hamiltonian flow:

$$\frac{dz}{dt} = \{ z, H \} = J \nabla H$$

\implies Hamilton (1834)

First integral:

$$\{ F, H \} = 0 \iff \frac{dF}{dt} = 0 \iff F(z(t)) = \text{const.}$$

Poisson Brackets

$$\{ \cdot, \cdot \} : C^\infty(M, \mathbb{R}) \times C^\infty(M, \mathbb{R}) \longrightarrow C^\infty(M, \mathbb{R})$$

Bilinear:

$$\{ aF + bG, H \} = a \{ F, H \} + b \{ G, H \}$$

$$\{ F, aG + bH \} = a \{ F, G \} + b \{ F, H \}$$

Skew Symmetric: $\{ F, H \} = - \{ H, F \}$

Jacobi Identity:

$$\{ F, \{ G, H \} \} + \{ H, \{ F, G \} \} + \{ G, \{ H, F \} \} = 0$$

Derivation: $\{ F, GH \} = \{ F, G \} H + G \{ F, H \}$

$$F, G, H \in C^\infty(M, \mathbb{R}), \quad a, b \in \mathbb{R}.$$

In coordinates $z = (z^1, \dots, z^m)$,

$$\{ F, H \} = \nabla F^T J(z) \nabla H$$

where $J(z)^T = -J(z)$ is a skew symmetric matrix.

The Jacobi identity imposes a system of quadratically nonlinear partial differential equations on its entries:

$$\sum_l \left(J^{il} \frac{\partial J^{jk}}{\partial z^l} + J^{jl} \frac{\partial J^{ki}}{\partial z^l} + J^{kl} \frac{\partial J^{ij}}{\partial z^l} \right) = 0$$

Given a Poisson structure, the Hamiltonian flow corresponding to $H \in C^\infty(M, \mathbb{R})$ is the system of ordinary differential equations

$$\frac{dz}{dt} = \{ z, H \} = J(z) \nabla H$$

Lie's Theory of Function Groups

Used for integration of partial differential equations:

$$\{ F_i, F_j \} = G_{ij}(F_1, \dots, F_n)$$

\implies predates Lie groups!!

Ausgezeichnete Funktionen = distinguished functions
= Casimirs

$$\{ F, C \} = 0 \quad \text{for all} \quad F \in C^\infty(M, \mathbb{R})$$

★ ★ All distinguished functions are first integrals (conservation laws) of any associated Hamiltonian system.

Darboux' Theorem

If $J(z)$ has constant rank, then there exist local coordinates $z = (p, q, y)$ such that the Poisson bracket is in canonical form

$$\{ F, H \} = \sum_{i=1}^n \frac{\partial F}{\partial p^i} \frac{\partial H}{\partial q^i} - \frac{\partial F}{\partial q^i} \frac{\partial H}{\partial p^i}$$

Canonical degenerate Hamiltonian system:

$$\frac{dz}{dt} = J \nabla H \quad J = \begin{pmatrix} O & -I & O \\ I & O & O \\ O & O & O \end{pmatrix}$$

Equivalently:

$$\frac{dp^i}{dt} = - \frac{\partial H}{\partial q^i} \quad \frac{dq^i}{dt} = \frac{\partial H}{\partial p^i} \quad \frac{dy^j}{dt} = 0$$

Distinguished (Casimir) functions: $F(y) = \text{const.}$

Variable rank: Weinstein, Conn.

Symplectic Structures

A two form $\Omega \in \wedge^2 T^*M$ is called *symplectic* if it is

- closed: $d\Omega = 0$, and
- nondegenerate: $\Omega \wedge \dots \wedge \Omega \neq 0$.

Nondegeneracy implies that Ω defines an isomorphism

$TM \simeq T^*M$, mapping

the Hamiltonian vector field \mathbf{v}_H to $dH = \mathbf{v}_H \lrcorner \Omega$.

In coordinates $\Omega = dz^T \wedge J(z)^{-1} dz$ and $\mathbf{v}_H = J(z) \nabla H(z) \partial_z$.

The associated nondegenerate Poisson bracket:

$$\{F, H\} = \langle \mathbf{v}_F \wedge \mathbf{v}_H; \Omega \rangle = \nabla F^T J(z) \nabla H$$

Lie–Poisson Structure

- Originally due to Lie
 - Rediscovered by Kirillov, Kostant, Souriau, ...
-

\mathfrak{g} — r -dimensional Lie algebra

$M = \mathfrak{g}^* \simeq \mathbb{R}^r$ — dual vector space

$$\{F, H\} = \langle z; [\nabla F(z), \nabla H(z)] \rangle$$

$$z \in \mathfrak{g}^* \quad F(z), H(z) \in C^\infty(\mathfrak{g}^*, \mathbb{R})$$

$$\nabla F(z) \in \mathfrak{g} \quad [\nabla F(z), \nabla H(z)] \text{ — Lie bracket in } \mathfrak{g}$$

Lie–Poisson Structure

\mathfrak{g} — r -dimensional Lie algebra

$M = \mathfrak{g}^* \simeq \mathbb{R}^r$ — dual vector space

Lie–Poisson bracket: $\{F, H\} = \langle z; [\nabla F(z), \nabla H(z)] \rangle$

$z \in \mathfrak{g}^*$ $F(z), H(z) \in C^\infty(\mathfrak{g}^*, \mathbb{R})$

$\nabla F(z) \in \mathfrak{g}$ $[\nabla F(z), \nabla H(z)]$ — Lie bracket in \mathfrak{g}

In coordinates: $J_{ij}(z) = \sum_{k=1}^r c_{ij}^k z_k$, $z = z_1 \mu^1 + \cdots + z_r \mu^r \in \mathfrak{g}^*$

c_{ij}^k — structure constants

μ^1, \dots, μ^r — Maurer–Cartan forms

The Euler Equations

⇒ Arnold

Let $G = \text{SDiff}(M)$ be the infinite-dimensional pseudo-group of volume preserving diffeomorphisms of a Riemannian manifold M .

Lie algebra: $\mathfrak{g} =$ divergence-free vector fields.

Hamiltonian functional on \mathfrak{g}^* : the L^2 norm.

★ The corresponding Lie–Poisson flow is equivalent to the Euler equations governing the motion of an incompressible fluid.

In \mathbb{R}^n :

$$u_t + u \cdot \nabla u = -\nabla p \quad \text{div } u = 0$$

u — fluid velocity p — pressure

⇒ Ebin, Marsden

Vorticity Equations

u — fluid velocity

$\omega = \nabla \wedge u$ — vorticity

$$\frac{\partial \omega}{\partial t} = \omega \cdot \nabla u - u \cdot \nabla \omega = J \frac{\delta H}{\delta \omega}$$

$H = \int \frac{1}{2} |u|^2 d\mathbf{x}$ — kinetic energy

$J = (\omega \cdot \nabla - \nabla \omega) \nabla \wedge \cdot$ — Poisson operator

Distinguished (Casimir) functions:

2D: $\iint f(\omega) dx dy$ 3D: $\iiint (u \cdot \omega) dx dy dz$ — helicity

Camassa–Holm Equation and Euler–Poincaré Flows

Use the H^1 norm as the Hamiltonian for the Lie–Poisson structure on the diffeomorphism pseudo-group:

$$\mathcal{H}[u] = \int (u^2 + \alpha |\nabla u|^2) dx$$

Camassa–Holm Equation:

$$u_t \pm u_{xxt} = 3u u_x \pm (u u_{xx} + \frac{1}{2}u_x^2)_x$$

\implies nonanalytic solutions — peakons or compactons

α models: regularized Euler; geophysics, magnetohydrodynamics, computational anatomy, mathematical morphology

Poisson Bivector Field

\implies Lichnerowicz

$$\Theta = \partial_z^T \wedge J(z) \partial_z \in \Lambda^2 TM$$

Poisson bracket:

$$\{ F, H \} = \langle \Theta ; dF \wedge dH \rangle$$

★ Bilinearity, skew symmetry and derivation properties are automatic.

Theorem. The Jacobi identity holds if and only if

$$[\Theta, \Theta] = 0$$

where $[\cdot, \cdot]$ denotes the **Schouten bracket**.

The Schouten Bracket

The **Schouten bracket** $[\Theta, \Psi]$ is the natural extension of the Lie bracket $[\mathbf{v}, \mathbf{w}]$ to **multi-vector fields** (sections of $\wedge^n TM$):

- Bilinear.
- Super-symmetric:

$$[\Theta, \Psi] = (-1)^{\deg \Theta \deg \Psi} [\Psi, \Theta] \in \wedge^{\deg \Theta + \deg \Psi - 1} TM$$

- Super-Jacobi identity:

$$\begin{aligned} (-1)^{\deg \Theta \deg \Xi} [[\Theta, \Psi], \Xi] + (-1)^{\deg \Xi \deg \Psi} [[\Xi, \Theta], \Psi] + \\ + (-1)^{\deg \Psi \deg \Theta} [[\Psi, \Xi], \Theta] = 0 \end{aligned}$$

- Super-derivation:

$$[\Theta, \Psi \wedge \Xi] = [\Theta, \Psi] \wedge \Xi + (-1)^{\deg \Psi (\deg \Theta - 1)} \Psi \wedge [\Theta, \Xi]$$

The Poisson Complex

$$\mathbb{R} \rightarrow \wedge^0 TM \xrightarrow{\delta_\Theta} \wedge^1 TM \xrightarrow{\delta_\Theta} \wedge^2 TM \xrightarrow{\delta_\Theta} \dots$$

Suppose Θ is a Poisson bivector:

$$[\Theta, \Theta] = 0$$

Poisson derivation:

$$\delta_\Theta(\Psi) = [\Theta, \Psi]$$

Closure: By super-Jacobi:

$$\delta_\Theta^2(\Psi) = [\Theta, [\Theta, \Psi]] = -[\Theta, [\Theta, \Psi]] - (-1)^{\deg \Psi} [\Psi, [\Theta, \Theta]] = 0$$

In particular, applying δ_Θ to a function gives the associated Hamiltonian vector field:

$$\delta_\Theta(H) = [\Theta, H] = \mathbf{v}_H$$

Poisson Cohomology

Unless Θ is nondegenerate, the Poisson complex is not locally exact. If Θ has constant rank, the local cohomology involves the distinguished functions and forms.

★ Poisson cohomology is poorly understood in general.

A nondegenerate Θ defines an algebra isomorphism $\wedge^k TM \simeq \wedge^k T^*M$ via $\omega \mapsto \mathbf{v} = \omega \lrcorner \Theta$. In this case, the Poisson complex is isomorphic to the de Rham complex:

$$\begin{array}{ccccccc}
 \mathbb{R} & \rightarrow & \wedge^0 T^*M & \xrightarrow{d} & \wedge^1 T^*M & \xrightarrow{d} & \wedge^2 T^*M & \xrightarrow{d} & \dots \\
 & & \uparrow & & \uparrow & & \uparrow & & \\
 \mathbb{R} & \rightarrow & \wedge^0 TM & \xrightarrow{\delta_\Theta} & \wedge^1 TM & \xrightarrow{\delta_\Theta} & \wedge^2 TM & \xrightarrow{\delta_\Theta} & \dots
 \end{array}$$

BiHamiltonian Systems

Definition. A system of first order differential equations is called **biHamiltonian** if it can be written in Hamiltonian form in two distinct ways:

$$\frac{du}{dt} = J_1 \nabla H_1 = J_2 \nabla H_0$$

Thus both J_1 and J_2 define Poisson brackets, which we assume are not constant multiples of each other.

\implies Both Hamiltonians H_1 and H_2 are conserved.

Infinite Toda Lattice

$$H = \sum_i \left(\frac{1}{2} p_i^2 + e^{q_{i-1} - q_i} \right)$$

$$a_i = \frac{1}{2} e^{(q_{i-1} - q_i)/2} \quad b_i = \frac{1}{2} p_{i-1} \quad \Longrightarrow \quad \text{Flaschka}$$

$$\frac{da_i}{dt} = a_i(b_{i+1} - b_i) \quad \frac{db_i}{dt} = 2(a_i^2 - a_{i-1}^2)$$

$$H_1 = \sum_i \left(a_i^2 + \frac{1}{2} b_i^2 \right) \quad H_0 = \sum_i b_i$$

$$J_1 = \begin{pmatrix} 0 & a(T_+ - 1) \\ (1 - T_-)a & 0 \end{pmatrix} \quad J_2 = \begin{pmatrix} \frac{1}{2}a(T_+ - T_-)a & a(T_+ - 1)b \\ b(1 - T_-)a & 2(a^2T_+ - T_-a^2) \end{pmatrix}$$

T_+, T_- — shift operators

Compatibility

- J_1 , J_2 , and $J_1 + J_2$ are all Poisson
- The Poisson bivectors satisfy

$$[\Theta_1, \Theta_1] = [\Theta_2, \Theta_2] = [\Theta_1, \Theta_2] = 0$$

- The recursion operator $R = J_2 J_1^{-1}$ satisfies the Nijenhuis torsion condition

$$R^2[\mathbf{v}, \mathbf{w}] - R[R\mathbf{v}, \mathbf{w}] - R[\mathbf{v}, R\mathbf{w}] + [R\mathbf{v}, R\mathbf{w}] = 0$$

- The symplectic forms satisfy

$$d\Omega_1 = d\Omega_2 = d(\Omega_1^{-1} + \Omega_2^{-1})^{-1} = 0$$

Theorem. (*Magri*) Suppose

$$\frac{du}{dt} = J_1 \nabla H_1 = J_2 \nabla H_0$$

is a biHamiltonian system, where J_1, J_2 form a **compatible** pair of Hamiltonian operators. Assume that J_1 is nondegenerate, and define the recursion operator $R = J_2 J_1^{-1}$. Then there exist an infinite sequence of conserved Hamiltonians H_0, H_1, H_2, \dots such that

- Each associated flow is a biHamiltonian system

$$\frac{du}{dt} = F_n = J_1 \nabla H_n = J_2 \nabla H_{n-1} = R F_{n-1}$$

- The Hamiltonians are in involution with respect to either Poisson bracket:

$$\{ H_n, H_m \}_1 = 0 = \{ H_n, H_m \}_2$$

and hence conserved by all flows.

- The flows mutually commute.

Proof: Recursion: Starting at $n = 1$, the n^{th} flow comes from the vector field

$$\mathbf{v}_n = [\Theta_2, H_{n-1}] = [\Theta_1, H_n]$$

Set $\mathbf{v}_{n+1} = [\Theta_2, H_n]$. Then, by super-Jacobi, compatibility, and closure

$$\begin{aligned} [\Theta_1, \mathbf{v}_{n+1}] &= [\Theta_1, [\Theta_2, H_n]] = - [\Theta_2, [\Theta_1, H_{n-1}]] - [[\Theta_1, \Theta_2], H_{n-1}] \\ &= - [\Theta_2, \mathbf{v}_{n-1}] = - [\Theta_2, [\Theta_2, H_{n-2}]] = 0 \end{aligned}$$

Then, by exactness of the Θ_1 -Poisson complex $\mathbf{v}_{n+1} = [\Theta_1, H_{n+1}]$ for some H_{n+1} .

Conservation: Using compatibility:

$$\begin{aligned} \mathbf{v}_n(H_m) &= [\mathbf{v}_n, H_m] = [[\Theta_2, H_{n-1}], H_m] = - [H_{n-1}, [\Theta_2, H_m]] \\ &= - [H_{n-1}, [\Theta_1, H_{m+1}]] = [[\Theta_1, H_{n-1}], H_{m+1}] = \mathbf{v}_{n-1}(H_{m+1}) \end{aligned}$$

and repeat ... to reduce to $\mathbf{v}_n(H_n) = \mathbf{v}_n(H_{n-1}) = 0$.

Completely Integrable Systems

Definition. A nondegenerate Hamiltonian system $u_t = J \nabla H$ on an $2n$ dimensional phase space is called **completely integrable** if there exist n first integrals $H = F_1, F_2, \dots, F_n$ that are in *involution*

$$\{ F_i, F_j \} = 0$$

Is a Completely Integrable System Necessarily BiHamiltonian?

Theorem. (*Fernandes*) A completely integrable Hamiltonian system is biHamiltonian in the neighborhood of an invariant torus if and only if the graph of its Hamiltonian function is a hypersurface of translation relative to the affine structure determined by the action variables (s^1, \dots, s^n) :

$$\begin{aligned}s^i &= a_1^i(y^1) + \dots + a_n^i(y^n), \\ H(s^1, \dots, s^n) &= \phi_1(y^1) + \dots + \phi_n(y^n).\end{aligned}$$

Example. The perturbed Kepler problem

$$H = \frac{1}{2} \left(p_r^2 + \frac{p_\theta^2}{r^2} + \frac{p_\phi^2}{r^2 \sin^2 \theta} \right) - \frac{1}{r} + \frac{\varepsilon}{2r^2}$$

★ completely integrable for all ε ; biHamiltonian only when $\varepsilon = 0$

Incompatible BiHamiltonian Systems

Ω_1, Ω_2 — symplectic two-forms on \mathbb{C}^4

$$\Omega_1 \wedge \Omega_2 \neq 0$$

Canonical forms (Debever):

$$\Omega_1 = dp_1 \wedge dq_1 + dp_2 \wedge dq_2$$

$$\Omega_2 = \begin{cases} dp_1 \wedge dq_1 - dp_2 \wedge dq_2 \\ e^{p_1} (dp_1 \wedge dq_1 - dp_2 \wedge dq_2 - p_2 dp_1 \wedge dq_2) \\ e^{p_1+p_2} (dp_1 \wedge dq_1 - dp_2 \wedge dq_2 + (q_1 + q_2) dp_1 \wedge dp_2) \end{cases}$$

\implies The first pair are compatible, but the latter two are not.

Bi-Hamiltonians:

$$H_1 = f(p_1, q_1) + g(p_2, q_2)$$

$$H_2 = f(p_2 e^{p_1/2}, q_2) e^{-p_1/2} + g(p_1)$$

$$H_3 = c(q_1 - q_2) + f(p_1, p_2) \quad \frac{\partial^2 f}{\partial p_1 \partial p_2} + \frac{\partial f}{\partial p_1} + \frac{\partial f}{\partial p_2} = 0.$$

Poisson brackets for Field Theories

$$\mathcal{H}[u] = \int H[u] dx \quad \text{— Hamiltonian functional}$$

$$\frac{\delta \mathcal{H}}{\delta u} = E(H)$$

— variational derivative = Euler–Lagrange expression

$$\{ \mathcal{F}, \mathcal{H} \} = \int \left(\frac{\delta \mathcal{F}}{\delta u} J \frac{\delta \mathcal{H}}{\delta u} \right) dx \quad \text{— Poisson bracket}$$

J — Poisson (differential) operator

\implies Formally skew-adjoint: $J^* = -J$

\implies Jacobi identity ★★

Korteweg–deVries Equation

$$\frac{\partial u}{\partial t} = u_{xxx} + u u_x = J_1 \frac{\delta \mathcal{H}_1}{\delta u} = J_2 \frac{\delta \mathcal{H}_2}{\delta u}$$

$$J_1 = D_x \qquad \mathcal{H}_1[u] = \int \left(\frac{1}{6} u^3 - \frac{1}{2} u_x^2 \right) dx$$

$$J_2 = D_x^3 + \frac{2}{3} u D_x + \frac{1}{3} u_x \qquad \mathcal{H}_2[u] = \int \frac{1}{2} u^2 dx$$

★ ★ Bi-Hamiltonian system with recursion operator

$$\mathcal{R} = J_2 \cdot J_1^{-1} = D_x^2 + \frac{2}{3} u + \frac{1}{3} u_x D_x^{-1}$$

⇒ Gardner, Lax, Lenard, PJO, Magri, Gel'fand–Dikii, Adler, ...

⇒ Lie–Poisson structure on the Lie algebra of pseudo-differential operators (Virasoro algebra)

Poisson Functional Multi-vectors

$$\Theta = \int \theta \wedge J(\theta) dx$$

In general, $\int D_x \Omega dx = 0$ — work mod image of D_x

Schouten bracket:

$$0 = [\Theta, \Theta] = \int \text{pr } \mathbf{v}_{J\theta}[\theta \wedge J(\theta)] dx$$

- prolonged evolutionary “vector field”:

$$\text{pr } \mathbf{v}_{J\theta} \text{ commutes with } D_x \text{ and } \text{pr } \mathbf{v}_{J\theta}(\theta) = 0.$$

Lemma. Any constant coefficient, skew-adjoint differential operator is Poisson.

Example. Second KdV Hamiltonian operator:

$$J = D_x^3 + \frac{2}{3} u D_x + \frac{1}{3} u_x$$

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Functional multi-vector:

$$\Theta = \int \theta \wedge \theta_{xxx} + \frac{2}{3} u \theta \wedge \theta_x dx$$

Example. Second KdV Hamiltonian operator:

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Functional multi-vector:

$$\Theta = \int \theta \wedge \theta_{xxx} + \frac{2}{3} u \theta \wedge \theta_x dx$$

Schouten bracket:

$$\begin{aligned} [\Theta, \Theta] &= \int \text{pr } \mathbf{v}_{\theta_{xxx} + \frac{2}{3}u\theta + \frac{1}{3}u_x\theta}(u) \wedge \theta \wedge \theta_x dx \\ &= \int (\theta_{xxx} + \frac{2}{3}u\theta + \frac{1}{3}u_x\theta) \wedge \theta \wedge \theta_x dx \\ &= \int \theta_{xxx} \wedge \theta \wedge \theta_x dx = 0 \end{aligned}$$

since

$$\theta_{xxx} \wedge \theta \wedge \theta_x = D_x(\theta_{xx} \wedge \theta \wedge \theta_x)$$

First Order Poisson Operators

⇒ Dubrovin, Novikov

Field variables: $u(x) = (u^1(x), \dots, u^n(x))$

$$J_{ij} = g^{ij}(u) D_x + b_k^{ij}(u) u_x^k$$

Nondegenerate Poisson operator:

- $g^{ij} = g^{ji}$ — flat (pseudo-)Riemannian metric
 - $b_k^{ij} = \sum_l g^{il} \Gamma_{lk}^j$ — Christoffel symbols (connection)
-

Hyperbolic systems of hydrodynamic type:

$$\frac{\partial u}{\partial t} = J \frac{\delta \mathcal{H}}{\delta u}$$

Nonlinear Transport

⇒ Nutku, PJO

$$u_t = u u_x$$

Conserved densities:

$$H_n(u) = \frac{1}{n} u^n$$

Hamiltonian structures:

$$J_0 = D_x$$

$$J_1 = 2u D_x + u_x$$

$$J_2 = u^2 D_x + u u_x$$

$$J_3 = D_x \frac{1}{u_x} D_x \frac{1}{u_x} D_x$$

Hamiltonian flows:

$$u_t = V_n = u^n u_x = J_0 \delta H_{n+1} = J_1 \delta H_n = J_2 \delta H_{n-1} = J_3 \delta H_{n+3}$$

- J_0, J_1, J_2 are mutually compatible
- J_0, J_3 are compatible
- J_1, J_3 and J_2, J_3 are **not** compatible
- $J_3 J_0^{-1} = R^2$ $R = D_x \frac{1}{u_x}$ — recursion operator

Rational flows: $u_t = \widehat{V}_2 = \frac{u_{xx}}{u_x}$ $u_t = \widehat{V}_n = R^{n-2} \widehat{V}_2$

Rational conserved densities: $\widehat{H}_1 = \frac{1}{u_x}$

$$\widehat{V}_{2j+1} = J_0 \delta \widehat{H}_j = J_3 \delta \widehat{H}_{j-1}$$

2-D Hyperbolic Systems

$$\mathbf{u}_t = J_0 \delta \mathcal{H} / \delta \mathbf{u}$$

$$\mathbf{u} = \begin{pmatrix} u \\ v \end{pmatrix} \quad \mathcal{H}[\mathbf{u}] = \int H(u, v) dx$$

$$J_0 = \sigma_1 D_x = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} D_x$$

$$\frac{\partial u}{\partial t} = D_x \frac{\delta H}{\delta v} \quad \frac{\partial v}{\partial t} = D_x \frac{\delta H}{\delta u}$$

Examples

Gas dynamics: $H(u, v) = -\frac{1}{2}u^2v + F(v)$

- Polytropic: $F(v) = \frac{v^\gamma}{\gamma(\gamma - 1)}$
 - Shallow water: $F(v) = \frac{1}{2}v^2, \quad \gamma = 2.$
-

Elastodynamics:

$$H(u, v) = \frac{1}{2}u^2 + F(v)$$

- van der Waals fluid; acoustic Euler equation
-

Born–Infeld equation:

$$H(u, v) = \frac{u}{v} + \frac{v}{u}$$

\implies Chaplygin gas $\gamma = -1$

Zero-th Order Conservation Laws

Theorem. $F(u, v)$ is a conserved density if and only if

$$H_{uu} F_{vv} = H_{vv} F_{uu}$$

Separable Hyperbolic System:

$$\frac{H_{uu}}{H_{vv}} = \frac{\lambda(u)}{\mu(v)}$$

$\lambda(u) \equiv 1$ — generalized gas dynamics

Higher Order Hamiltonian Structure

Separable:

$$\frac{H_{uu}}{H_{vv}} = \frac{\lambda(u)}{\mu(v)}$$

$$L(u) = \int \lambda(u) du \quad M(v) = \int \mu(v) dv$$

$$U(u, v) = \begin{pmatrix} u & M(v) \\ v & L(u) \end{pmatrix} \quad V(u, v) = \begin{pmatrix} L(u) & M(v) \\ v & u \end{pmatrix}$$

Poisson operator:

$$J_3 = D_x V_x^{-1} D_x U_x^{-1} \sigma_1 D_x$$

BiHamiltonian system:

$$\mathbf{u}_1 = J_0 \delta H = J_3 \delta \widehat{H}$$

Recursion operator (Sheftel'):

$$\widehat{R} = J_3 J_0^{-1} = D_x V_x^{-1} D_x U_x^{-1}$$

For gas dynamics, $U = V$ and $\widehat{R} = R^2$ where $R = D_x U_x^{-1}$ is a recursion operator

There are also two other first order Poisson operators J_1, J_2 , along with hierarchies of zeroth order polynomial conservation laws and higher order rational conservation laws, e.g.

$$\widehat{H}_1 = \frac{v_x}{u_x^2 - \mu(v) v_x^2}$$

\implies Verosky

Deformed Lie–Poisson Structure

$u(x) \in C^\infty(\mathbb{R}, \mathfrak{g}^*)$ — curve in \mathfrak{g}^* — dual to Lie algebra

Poisson bracket:

$$\{ \mathcal{F}, \mathcal{H} \} = \int \left(\frac{\delta \mathcal{F}}{\delta u} \mathcal{P} \frac{\delta \mathcal{H}}{\delta u} \right) dx$$

Hamiltonian curve flow:

$$\frac{\partial u}{\partial t} = \mathcal{P} \frac{\delta \mathcal{H}}{\delta u} = B D_x \frac{\delta \mathcal{H}}{\delta u} + \text{ad}_{\delta \mathcal{H} / \delta u}^*(u)$$

$B: \mathfrak{g} \longrightarrow \mathfrak{g}^*$ — ad^* -invariant symmetric linear map

- If \mathfrak{g} is semi-simple, B is a multiple of the Killing form

Noncanonical Perturbation Theory

$$\frac{dv}{dt} = J(v)\nabla H(v)$$

Perturbation expansion:

$$v = u + \varepsilon \varphi(u) + \varepsilon^2 \psi(u) + \dots$$

$$H(v) = H_0(u) + \varepsilon H_1(u) + \varepsilon^2 H_2(u) + \dots$$

$$J(v) \longmapsto J_0(u) + \varepsilon J_1(u) + \varepsilon^2 J_2(u) + \dots$$

Perturbed system:

$$\frac{du}{dt} = J_0 \nabla H_0 + \varepsilon (J_1 \nabla H_0 + J_0 \nabla H_1) + \dots$$

First order Hamiltonian perturbation

$$\begin{aligned}\frac{du}{dt} &= (J_0 + \varepsilon J_1) \nabla (H_0 + \varepsilon H_1) \\ &= J_0 \nabla H_0 + \varepsilon (J_1 \nabla H_0 + J_0 \nabla H_1) + \varepsilon^2 J_1 \nabla H_1\end{aligned}$$

★ There is no guarantee that $J_0 + \varepsilon J_1$ is a Poisson operator.

Theorem. If $J_1 \nabla H_0 = \lambda J_0 \nabla H_1$ and J_0, J_1 are compatible, then the first order perturbation equation

$$\frac{du}{dt} = J_0 \nabla H_0 + \varepsilon (J_1 \nabla H_0 + J_0 \nabla H_1)$$

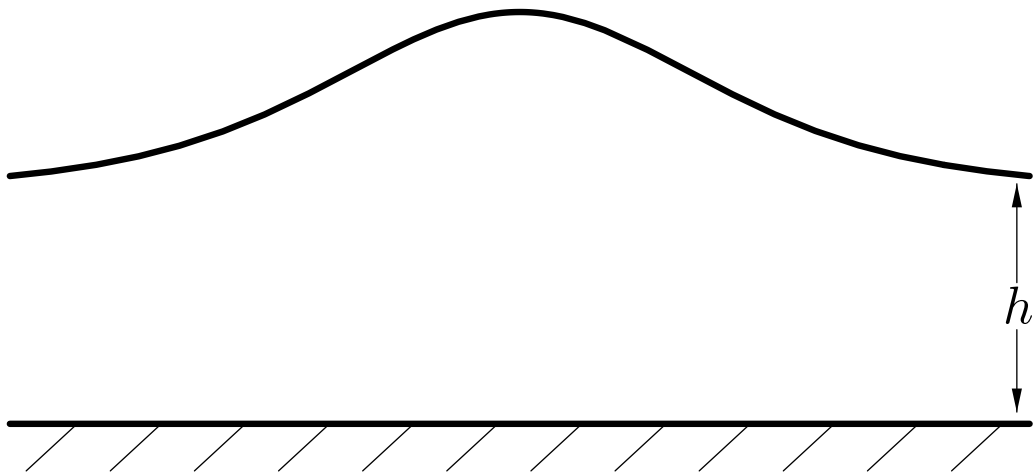
and the first order Hamiltonian perturbation

$$\frac{du}{dt} = J_0 \nabla H_0 + \varepsilon (J_1 \nabla H_0 + J_0 \nabla H_1) + \varepsilon^2 J_1 \nabla H_1$$

are biHamiltonian systems.

\implies KdV equation

2D Water Waves



$y = h + \eta(t, x)$ surface elevation

$\phi(t, x, y)$ velocity potential

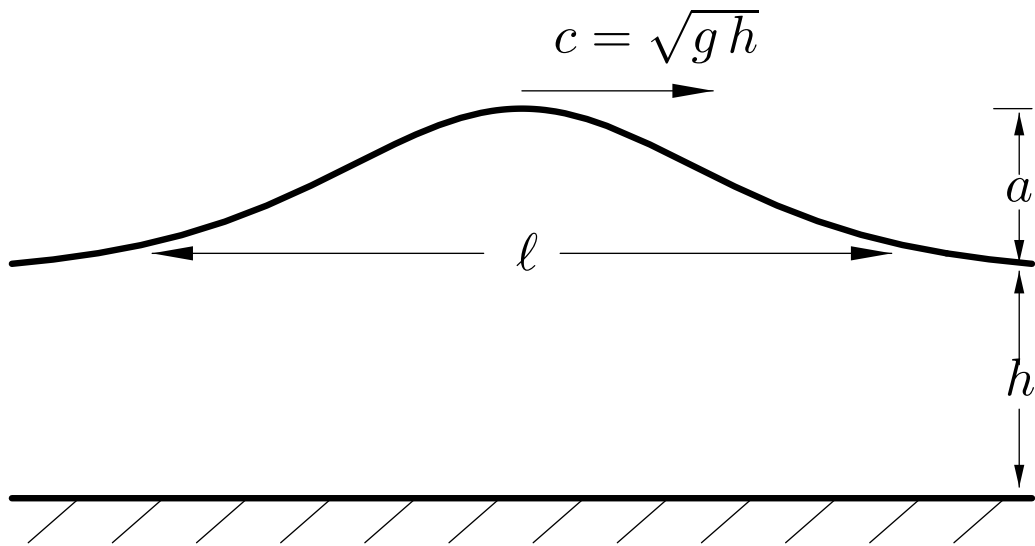
2D Water Waves

- Incompressible, irrotational fluid.
- No surface tension

$$\left. \begin{aligned} \phi_t + \frac{1}{2} \phi_x^2 + \frac{1}{2} \phi_y^2 + g \eta &= 0 \\ \eta_t &= \phi_y - \eta_x \phi_x \end{aligned} \right\} \quad y = h + \eta(t, x)$$

$$\phi_{xx} + \phi_{yy} = 0 \quad 0 < y < h + \eta(t, x)$$

$$\phi_y = 0 \quad y = 0$$



Small parameters — long waves in shallow water

(KdV regime)

$$\alpha = \frac{a}{h} \quad \beta = \frac{h^2}{\ell^2} = O(\alpha)$$

Rescale:

$$\begin{aligned}x &\longmapsto \ell x & y &\longmapsto h y & t &\longmapsto \frac{\ell t}{c} \\ \eta &\longmapsto a \eta & \phi &\longmapsto \frac{g a \ell \phi}{c} & c &= \sqrt{g h}\end{aligned}$$

Rescaled water wave system:

$$\left. \begin{aligned}\phi_t + \frac{\alpha}{2} \phi_x^2 + \frac{\alpha}{2\beta} \phi_y^2 + \eta &= 0 \\ \eta_t &= \frac{1}{\beta} \phi_y - \alpha \eta_x \phi_x\end{aligned}\right\} \begin{aligned}y &= 1 + \alpha \eta \\ 0 < y &< 1 + \alpha \eta \\ y &= 0\end{aligned}$$
$$\beta \phi_{xx} + \phi_{yy} = 0$$
$$\phi_y = 0$$

Boussinesq expansion:

$$w(t, x) = \phi(t, x, 0) \quad u(t, x) = \phi_x(t, x, \theta) \quad 0 \leq \theta \leq 1$$

Solve Laplace equation:

$$\phi(t, x, y) = w(t, x) - \frac{\beta^2}{2} y^2 w_{xx} + \frac{\beta^4}{4!} y^4 w_{xxxx} + \dots$$

Plug expansion into free surface conditions: To first order

$$w_t + \eta + \frac{\alpha}{2} w_x^2 - \frac{\beta}{2} w_{xxt} = 0$$

$$\eta_t + w_x + \alpha(\eta w_x)_x - \frac{\beta}{6} w_{xxxx} = 0$$

Bidirectional Boussinesq system:

$$u_t + \eta_x + \alpha u u_x - \frac{1}{2} \beta (\theta^2 - 1) u_{xxt} = 0$$

$$\eta_t + u_x + \alpha (\eta u)_x - \frac{1}{6} \beta (3\theta^2 - 1) u_{xxx} = 0$$

★ ★ at $\theta = 1$ this system is integrable

(in fact tri-Hamiltonian!!)

\implies Kaup–Kupershmidt

Unidirectional waves:

$$u = \eta - \frac{1}{4} \alpha \eta^2 + \left(\frac{1}{3} - \frac{1}{2} \theta^2 \right) \beta \eta_{xx}$$

Korteweg-deVries (1895) equation:

$$\eta_t + \eta_x + \frac{3}{2} \alpha \eta \eta_x + \frac{1}{6} \beta \eta_{xxx} = 0$$

★ ★ Due to Boussinesq in 1877!

Hamiltonian Water Waves

⇒ Zakharov

$$u = \begin{pmatrix} \phi_S \\ \eta \end{pmatrix}$$

$$\phi_S(x, t) = \phi(x, h + \eta(x, t), t) \quad \text{— surface potential}$$

Hamiltonian functional:

$$\mathcal{H}[u] = \int \int_D |\nabla \phi|^2 dx dy + \int_S \frac{1}{2} g \eta^2 dx$$

kinetic

potential

energy

$$\frac{\partial u}{\partial t} = J \frac{\delta \mathcal{H}}{\delta u} = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} \delta \mathcal{H} / \delta \phi_S \\ \delta \mathcal{H} / \delta \eta \end{pmatrix}$$

Water Waves

Symmetries and Conservation Laws

# spatial dimensions	surface tension	dim. symm. group	# cons. laws
2		9	8
2	✓	8	7
3		13	12
3	✓	12	13

⇒ T.B. Benjamin - PJO

Symmetries of 2D Water Waves

(1) Horizontal translation: $\frac{\partial}{\partial x} \quad (x + \alpha, y, t, \varphi)$

(2) Time translations: $\frac{\partial}{\partial t} \quad (x, y, t + \alpha, \varphi)$

(3) Change in potential: $\frac{\partial}{\partial \varphi} \quad (x, y, t, \varphi + \alpha)$

(4) Vertical translation: $\frac{\partial}{\partial y} - g t \frac{\partial}{\partial t} \quad (x, y + \alpha, t, \varphi - \alpha g t)$

(5) Horizontal Galilean boost:

$$t \frac{\partial}{\partial x} + x \frac{\partial}{\partial \varphi} \quad (x + \alpha t, y, t, \varphi + \alpha x + \frac{1}{2} \alpha^2 t)$$

(6) Vertical Galilean boost:

$$t \frac{\partial}{\partial y} + (y - \frac{1}{2} g t^2) \frac{\partial}{\partial \varphi} \quad (x, y + \alpha t, t, \varphi + \alpha (y - \frac{1}{2} g t^2) + \frac{1}{2} \alpha^2 t)$$

(7) Vertical acceleration:

$$g t^2 \frac{\partial}{\partial y} - t \frac{\partial}{\partial t} + \left(\varphi + 2 g t y - \frac{1}{2} g^2 t^3 \right) \frac{\partial}{\partial \varphi}$$
$$\left(x, y + \frac{1}{2} g t^2 (1 - \lambda^{-2}), \lambda^{-1} t, \lambda \varphi + g t y (\lambda - \lambda^{-1}) + \frac{1}{6} g^2 t^3 (\lambda - 3 \lambda^{-1} + 2 \lambda^{-3}) \right)$$

(8) Gravity-free rotation:

$$\left(y + \frac{1}{2} g t^2 \right) \frac{\partial}{\partial x} - x \frac{\partial}{\partial y} + g t x \frac{\partial}{\partial \varphi}$$
$$\left(x \cos \alpha + \left(y + \frac{1}{2} g t^2 \right) \sin \alpha, -x \sin \alpha + \left(y + \frac{1}{2} g t^2 \right) \cos \alpha - \frac{1}{2} g t^2, \right.$$
$$\left. t, \varphi + g t (x \sin \alpha + \left(y + \frac{1}{2} g t^2 \right) \cos \alpha) \right)$$

(9) Rescaling: $x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} + \frac{1}{2} t \frac{\partial}{\partial t} + \frac{3}{2} \varphi \frac{\partial}{\partial \varphi} \quad \left(\lambda x, \lambda y, \sqrt{\lambda} t, \lambda^{3/2} \varphi \right)$

Conservation Laws of 2D Water Waves

- (1) Horizontal momentum: $\int_S \varphi dy = P_x$
- (2) Energy: $\int_S \left(\frac{1}{2} \varphi \nu ds + \frac{1}{2} g^2 dx \right) = E$
- (3) Mass: $\int_S y dx = M$
- (4) Vertical momentum: $\int_S \varphi dx = -g M t + P_y$
- (5) Horizontal Center of Mass: $\int_S x y dx = -P_x t + C_x$
- (6) Potential Energy: $\int_S \frac{1}{2} y^2 dx = -\frac{1}{2} g M t^2 + P_y t + U$
- (7) Radial Momentum:
 $\int_S \varphi (x dy - y dx) = -\frac{7}{6} g^2 M t^3 + \frac{7}{2} g P_y t^2 + \left(\frac{7}{2} g U - 4 E \right) t + P_r$
- (8) Angular Momentum: $\int_S \varphi (x dx - y dy) = \frac{1}{2} y P_x t^2 - g C_x t + P_\theta$

Infinite Depth Ocean

- (1) Horizontal momentum: $\int_S \varphi dy = P_x$
- (2) Energy: $\int_S \left(\frac{1}{2} \varphi v ds + \frac{1}{2} g^2 dx \right) = E$
- (3) Mass: $\int_S y dx = M$
- (4) Vertical momentum: $\int_S \varphi dx = -g M t + P_y$
- (5) Horizontal Center of Mass: $\int_S x y dx = -P_x t + C_x + B_\infty^5$
- (6) Potential Energy: $\int_S \frac{1}{2} y^2 dx = -\frac{1}{2} g M t^2 + P_y t + U + B_\infty^6$
- (7) Radial Momentum: $\int_S \varphi (x dy - y dx) = -\frac{7}{6} g^2 M t^3 + \frac{7}{2} g P_y t^2 + \left(\frac{7}{2} g U - 4 E \right) t + P_r + B_\infty^7$
- (8) Angular Momentum: $\int_S \varphi (x dx - y dy) = \frac{1}{2} y P_x t^2 - g C_x t + P_\theta + B_\infty^8$
- $$B_\infty^6 = \lim_{y \rightarrow \infty} \int_0^t \int_{-\infty}^{\infty} y [v(x, y, t) - v(x, y, 0)] dx d\tau$$

First Order Hamiltonian KdV Model

For surface elevation $\eta(t, x)$:

Energy:

$$\mathcal{H}[\eta] = \int \left[\frac{1}{2} \eta^2 + \frac{1}{8} \alpha \eta^3 \right] dx$$

Poisson operator:

$$J = D_x + \frac{1}{6} \beta D_x^3 + \frac{1}{4} \alpha (\eta D_x + D_x \eta)$$

Hamiltonian flow:

$$\eta_t + J \frac{\delta \mathcal{H}}{\delta \eta} = 0$$

Unidirectional model:

$$\eta_t + \eta_x + \frac{3}{2} \alpha \eta \eta_x + \frac{1}{6} \beta \eta_{xxx} + \frac{1}{16} \alpha \beta (\eta^2)_{xxx} + \frac{15}{32} \alpha^2 \eta^2 \eta_x = 0$$

First Order Hamiltonian KdV Model

For **horizontal velocity** at height $0 \leq \theta \leq 1$:

$$u(t, x) = \varphi_x(t, x, y)$$

Energy:

$$\mathcal{H}[u] = \int \left[\frac{1}{2} u^2 + \frac{3}{8} \alpha u^3 + \frac{1}{6} \beta (2 - 3\theta^2) u_x^2 \right] dx$$

Poisson operator:

$$J = D_x + \beta \left(\frac{5}{6} - \theta^2 \right) D_x^3 - \frac{1}{4} \alpha (u D_x + D_x u)$$

Hamiltonian flow:

$$u_t + J \frac{\delta \mathcal{H}}{\delta u} = 0$$

Unidirectional model:

$$\begin{aligned} u_t + u_x + \frac{3}{2} \alpha u u_x + \frac{1}{6} \beta u_{xxx} - \frac{1}{18} \beta^2 \left(\frac{5}{9} - \frac{3}{2} \theta^2 + \theta^4 \right) u_{xxxxx} \\ + \alpha \beta \left(\frac{53}{24} - \frac{11}{4} \theta^2 \right) u u_{xxx} + \alpha \beta \left(\frac{139}{24} - 7 \theta^2 \right) u_x u_{xx} - \frac{45}{32} \alpha^2 u^2 u_x = 0 \end{aligned}$$

A “Magic” Depth

At depth

$$\theta^* = \sqrt{\frac{11}{12} - \frac{3}{4}\tau}$$

τ — surface tension

- The bidirectional Boussinesq model has a Hamiltonian structure
- The unidirectional Hamiltonian model is a version of KdV 5, and has a family of exact sech^2 soliton solutions
- The first order expansion of the water wave Poisson structure gives the Korteweg-deVries biHamiltonian structure exactly.

Vortex Filaments

The motion of a vortex filament $C \subset \mathbb{R}^3$ is described by $\frac{\partial C}{\partial t} = \kappa \mathbf{b}$, where κ is the curvature, and $\mathbf{t}, \mathbf{n}, \mathbf{b}$ are the Frenet frame on the curve.

Theorem. (*Hasimoto*) The curvature and torsion of a vortex filament evolve according to the completely integrable nonlinear Schrödinger equation

$$-i \frac{\partial \psi}{\partial t} = \frac{\partial^2 \psi}{\partial s^2} + \frac{1}{2} |\psi|^2 \psi$$

where

$$\psi(t, s) = \kappa(t, s) \exp \left(i \int \tau(t, s) ds \right).$$

- ★ Integrable biHamiltonian systems appear in a surprising range of geometric curve flows. (Lamb, Langer, Singer, Perline, Mari–Beffa, Sanders, Wang, Qu, Chou, Anco, ...)

Euclidean plane curves

$$\frac{\partial C}{\partial t} = J \mathbf{n}, \quad \frac{\partial \kappa}{\partial t} = \mathcal{R}(J) \quad G = \text{SE}(2) = \text{SO}(2) \ltimes \mathbb{R}^2$$

$$\mathcal{A} = \mathcal{D}^2 + \kappa^2, \quad \mathcal{B} = -\kappa$$

$$\mathcal{R} = \mathcal{A} - \kappa_s \mathcal{D}^{-1} \mathcal{B} = \mathcal{D}^2 + \kappa^2 + \kappa_s \mathcal{D}^{-1} \cdot \kappa$$

$$\kappa_t = \mathcal{R}(\kappa_s) = \kappa_{sss} + \frac{3}{2} \kappa^2 \kappa_s$$

\implies modified Korteweg-deVries equation

Equi-affine plane curves

$$\frac{\partial C}{\partial t} = J \mathbf{n}, \quad \frac{\partial \kappa}{\partial t} = \mathcal{R}(J) \quad G = \text{SA}(2) = \text{SL}(2) \ltimes \mathbb{R}^2$$

$$\mathcal{A} = \mathcal{D}^4 + \frac{5}{3} \kappa \mathcal{D}^2 + \frac{5}{3} \kappa_s \mathcal{D} + \frac{1}{3} \kappa_{ss} + \frac{4}{9} \kappa^2, \quad \mathcal{B} = \frac{1}{3} \mathcal{D}^2 - \frac{2}{9} \kappa,$$

$$\mathcal{R} = \mathcal{A} - \kappa_s \mathcal{D}^{-1} \mathcal{B}$$

$$= \mathcal{D}^4 + \frac{5}{3} \kappa \mathcal{D}^2 + \frac{4}{3} \kappa_s \mathcal{D} + \frac{1}{3} \kappa_{ss} + \frac{4}{9} \kappa^2 + \frac{2}{9} \kappa_s \mathcal{D}^{-1} \cdot \kappa$$

$$\kappa_t = \mathcal{R}(\kappa_s) = \kappa_{5s} + \frac{5}{3} \kappa \kappa_{sss} + \frac{5}{3} \kappa_s \kappa_{ss} + \frac{5}{9} \kappa^2 \kappa_s$$

\implies Sawada–Kotera equation

Euclidean space curves

$$\frac{\partial C}{\partial t} = J_1 \mathbf{n} + J_2 \mathbf{b}, \quad \frac{\partial}{\partial t} \begin{pmatrix} \kappa \\ \tau \end{pmatrix} = \mathcal{R}(J)$$

$$G = \text{SE}(3) = \text{SO}(3) \ltimes \mathbb{R}^3$$

$$\mathcal{A} = \begin{pmatrix} D_s^2 + (\kappa^2 - \tau^2) \\ \frac{2\tau}{\kappa} D_s^2 + \frac{3\kappa\tau_s - 2\kappa_s\tau}{\kappa^2} D_s + \frac{\kappa\tau_{ss} - \kappa_s\tau_s + 2\kappa^3\tau}{\kappa^2} \\ -2\tau D_s - \tau_s \\ \frac{1}{\kappa} D_s^3 - \frac{\kappa_s}{\kappa^2} D_s^2 + \frac{\kappa^2 - \tau^2}{\kappa} D_s + \frac{\kappa_s\tau^2 - 2\kappa\tau\tau_s}{\kappa^2} \end{pmatrix}$$

$$\text{Recursion operator: } \begin{pmatrix} \kappa_t \\ \tau_t \end{pmatrix} = \mathcal{R} \begin{pmatrix} \kappa_s \\ \tau_s \end{pmatrix} \quad \mathcal{R} = \mathcal{A} - \begin{pmatrix} \kappa_s \\ \tau_s \end{pmatrix} \mathcal{D}^{-1} \begin{pmatrix} \kappa & 0 \end{pmatrix}$$

\implies vortex filament flow

Tri-Hamiltonian Duality

\implies Fokas–Fuchssteiner; Camassa–Holm; PJO–Rosenau

There are, in fact, three mutually compatible Poisson structures associated with the Korteweg–deVries equation:

$$J_1 = D_x, \quad J_2 = u D_x + D_x u, \quad J_3 = D_x^3$$

- The Hamiltonian pair $J_1, J_2 + J_3$ produces the KdV biHamiltonian flow.
- The Hamiltonian pair $J_1 + J_3, J_2$ produces the Camassa–Holm biHamiltonian flow.
- ★ The same construction applies to other integrable systems, producing compacton/peakon integrable duals.