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DEF'N 2.6.10-2.6.14: As before, we define

- Lin. independence of $\{\bar{v}_i\}_{i=1, \dots, k}$ in V , i.e. $\sum_{i=1}^k c_i \bar{v}_i = \bar{0} \Rightarrow c_1 = \dots = c_k = 0$
- $\text{span}(\bar{v}_1, \dots, \bar{v}_k) := \{c_1 \bar{v}_1 + \dots + c_k \bar{v}_k : c_i \in \mathbb{R}\}$
- $\{\bar{v}_i\}_{i=1, \dots, k}$ are a basis for V if they are lin. indep. & $\text{span}\{\bar{v}_i\}_{i=1, \dots, k} = V$
or equivalently, every $\bar{v} \in V$ can be written uniquely as $\bar{v} = \sum_{i=1}^k x_i \bar{v}_i$

(in which case, you call $\begin{bmatrix} x_1 \\ \vdots \\ x_k \end{bmatrix}$ the coordinates of \bar{v} with respect to the (ordered) basis $(\bar{v}_1, \dots, \bar{v}_k)$)

11/11/2016 Once you have picked (ordered) bases $(\bar{v}_1, \dots, \bar{v}_n)$ for V
 $(\bar{w}_1, \dots, \bar{w}_m)$ for W

one can express any linear transformation uniquely in these bases
via an $m \times n$ matrix A
 $T: V \rightarrow W$

where $T(\bar{v}_j) = \sum_{i=1}^m a_{ij} \bar{w}_i$

that is, $A = \begin{bmatrix} | & | & & | \\ T(\bar{v}_1) & T(\bar{v}_2) & \dots & T(\bar{v}_n) \\ | & | & & | \end{bmatrix}$ where $T(\bar{v}_j)$ is expressed in coordinates with respect to $(\bar{w}_1, \dots, \bar{w}_m)$

As before, composition of linear maps com. to multiplying matrices

EXAMPLES:

① $P_d = \{a_0 + a_1 x + \dots + a_d x^d\}$ has basis $(1, x, x^2, \dots, x^d)$

P_{d-1} has basis $(1, x, x^2, \dots, x^{d-1})$

The linear transformation $P_d \xrightarrow{d/dx} P_{d-1}$ expressed with respect to these choices of bases has matrix

$A = \begin{matrix} & \begin{matrix} 1 & x & x^2 & \dots & x^{d-1} & x^d \end{matrix} \\ \begin{matrix} 1 \\ x \\ x^2 \\ \vdots \\ x^{d-1} \end{matrix} & \begin{bmatrix} 0 & 1 & 0 & \dots & 0 & 0 \\ 0 & 0 & 2 & \dots & 0 & 0 \\ 0 & 0 & 0 & \dots & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & d-1 & 0 \\ 0 & 0 & 0 & \dots & 0 & d \end{bmatrix} \end{matrix}$

eg. $d=3$
 $A = \begin{matrix} 1 \\ x \\ x^2 \end{matrix} \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 3 \end{bmatrix}$

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(2) The integration map $P_{d-1} \xrightarrow{\int_0^x} P_d$
 $p(x) \longmapsto \int_0^x p(t) dt$

is also linear (Why?)

and with respect to the same chosen of bases has matrix

$$B = \begin{matrix} & 1 & x & x^2 & \dots & x^{d-1} \\ \begin{matrix} 1 \\ x \\ x^2 \\ x^3 \\ \vdots \\ x^{d-1} \\ x^d \end{matrix} & \begin{bmatrix} 0 & 0 & 0 & \dots & 0 \\ 0 & 1 & 0 & \dots & 0 \\ 0 & \frac{1}{2} & 0 & \dots & 0 \\ 0 & 0 & \frac{1}{3} & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & \frac{1}{d-1} \\ 0 & 0 & 0 & \dots & 0 & \frac{1}{d} \end{bmatrix} \end{matrix}$$

e.g. $d=3$ $B = \begin{matrix} & 1 & x & x^2 \\ \begin{matrix} 1 \\ x \\ x^2 \\ x^3 \end{matrix} & \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & \frac{1}{2} & 0 \\ 0 & 0 & \frac{1}{3} \end{bmatrix} \end{matrix}$

(3) Since the composite map

$$P_{d-1} \xrightarrow{\int_0^x} P_d \xrightarrow{\frac{d}{dx}} P_{d-1}$$

$$p(x) \longmapsto \int_0^x p(t) dt \longmapsto \frac{d}{dx} \int_0^x p(t) dt = p(x)$$

is the identity map $1_{P_{d-1}}$, one should have $AB = I_d$

(i.e. $\frac{d}{dx} \int_0^x = 1_{P_{d-1}}$)

and this is what happens, e.g. for $d=3$

$$\underbrace{\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 2 \\ 0 & 0 & 0 & 3 \end{bmatrix}}_A \underbrace{\begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & \frac{1}{2} & 0 \\ 0 & 0 & \frac{1}{3} \end{bmatrix}}_B = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = I_3$$

$\frac{d}{dx}$ \int_0^x

A has B as a right-inverse; $\frac{d}{dx} : P_d \rightarrow P_{d-1}$ is surjective (but not injective; who is $\ker(\frac{d}{dx})$?)
 B has A as a left-inverse; $\int_0^x : P_{d-1} \rightarrow P_d$ is injective. (but not surjective; who is not in $\text{img}(\int_0^x)$?)

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④ Similarly one could do the composite in the other order:

$$P_d \xrightarrow[A]{\frac{d}{dx}} P_{d+1} \xrightarrow[B]{\int_0^x} P_d$$

The composite $\int_0^x \frac{d}{dx}$ has matrix (w.r.t. to the ordered basis $(1, x, x^2, \dots, x^d)$ for P_d)

BA =

$$\begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & \frac{1}{2} & 0 \\ 0 & 0 & \frac{1}{3} \end{bmatrix} \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 3 \end{bmatrix} = \begin{matrix} 1 & x & x^2 & x^3 \\ \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \end{matrix}$$

e.g. take $d=4$

$$\left(\int_0^x \frac{d}{dx} \right) (x^m) = \begin{cases} x^m & \text{if } m > 0 \\ 0 & \text{if } m = 0 \end{cases}$$

DEFIN 2.6.5:
+ 2.6.14

An isomorphism of vector spaces V, W

is a bijective linear transformation $T: V \rightarrow W$
 ("injective, surjective")
 $\ker T = \{0\}$, $\text{img}(T) = W$

Picking an ordered basis $(\bar{v}_1, \dots, \bar{v}_n)$ for V

leads to the isomorphism $\mathbb{R}^n \xrightarrow{\Phi_{\{\bar{v}_i\}}} V$

$$\begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} \longmapsto x_1 \bar{v}_1 + \dots + x_n \bar{v}_n$$

which the book calls the "concrete to abstract" function.

$\Phi_{\{\bar{v}_i\}}^{-1}(\bar{w})$ gives the coordinates $\begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}$ of \bar{w} with respect to the ordered basis $(\bar{v}_1, \dots, \bar{v}_n)$

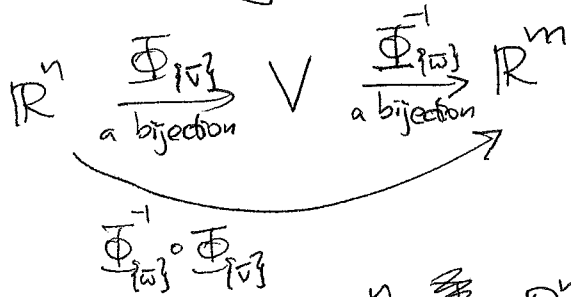
i.e. $\bar{w} = x_1 \bar{v}_1 + \dots + x_n \bar{v}_n$

What is interesting is how one changes the coordinates in V from one choice of an ordered basis $(\bar{v}_1, \dots, \bar{v}_n)$ to another one $(\bar{w}_1, \dots, \bar{w}_m)$

First, let's check that we should have $m=n$ here.

THM 2.6.22: If $\{\bar{v}_1, \dots, \bar{v}_n\}, \{\bar{w}_1, \dots, \bar{w}_m\}$ are 2 bases for V , then $m=n$;
& DEFIN 2.6.23 $n = \text{dim}(V)$ dimension of V

proof: We'd like to say that the composite bijection



is a lin. transformation $\mathbb{R}^n \xrightarrow{\cong} \mathbb{R}^m$ which is bijective, hence $m=n$.

However, 1st we should check that $\Phi_{\{\bar{w}\}}^{-1}$ is linear,

by noting LEMMA: If $T: V \rightarrow W$ is a bijective, linear map then $T^{-1}: W \rightarrow V$ is also linear.

proof (same as for PROP 1.3.14):

Want to check $T^{-1}(a\bar{v}_1 + b\bar{v}_2) = aT^{-1}(\bar{v}_1) + bT^{-1}(\bar{v}_2)$,
but since T is bijective, this is true if and only if

$$T T^{-1}(a\bar{v}_1 + b\bar{v}_2) \stackrel{?}{=} T(aT^{-1}(\bar{v}_1) + bT^{-1}(\bar{v}_2))$$

$\parallel \quad \leftarrow T \text{ is linear}$

$$a\bar{v}_1 + b\bar{v}_2 \quad \parallel \quad aT T^{-1}(\bar{v}_1) + bT T^{-1}(\bar{v}_2)$$

$\parallel \quad \quad \quad \parallel$

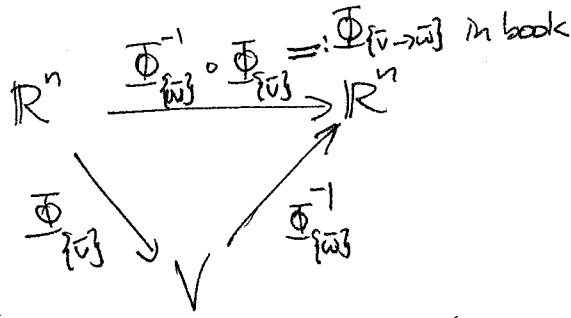
$$a\bar{v}_1 + b\bar{v}_2 \quad \parallel \quad a\bar{v}_1 + b\bar{v}_2 \quad \blacksquare$$

Thus $\Phi_{\{\bar{w}\}}^{-1}$ is linear,

so the composite $\Phi_{\{\bar{w}\}}^{-1} \circ \Phi_{\{\bar{v}\}}: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is linear, bijective, forcing $m=n$ \blacksquare

11/15/2016

In fact, the matrix that represents



is the matrix that converts the coordinates w.r.t. $\{\bar{v}_i\}$ for a vector in V to its coordinates w.r.t. $\{\bar{w}_i\}$:

