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DEFIN 2.9: The rank of a linear transformation $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is $\dim(\text{img}(T)) =: \text{rank}(T)$
 The nullity is $\dim(\text{ker}(T)) =: \text{nullity}(T)$

THM 2.5.8 (rank-nullity formula)

For linear maps $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$,
 $\text{rank}(T) + \text{nullity}(T) = n$.

proof:

~~rank(A) = rank(T)~~ If $A = [T]$, then
 $m \times n$

$\text{rank}(T) = \text{rank}(A) = \# \text{ pivot columns}$

$\text{nullity}(T) = \text{nullity}(A) = \# \text{ non-pivot columns}$

TOTAL: # columns = n \blacksquare

A remarkable consequence...

COR 2.5.10: For linear maps $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$, \leftarrow must be same!

$T(\bar{x}) = \bar{b}$ has a sol'n for every $\bar{b} \in \mathbb{R}^n \iff T(\bar{x}) = \bar{0}$ has only the trivial sol'n $\bar{x} = \bar{0}$

proof:

\updownarrow
 T surjective (onto \mathbb{R}^n)

\updownarrow
 T injective

\updownarrow
 $\text{rank}(T) = n$

\longleftrightarrow THM 2.5.8 \longleftrightarrow

\updownarrow
 $\text{nullity}(T) = 0$ \blacksquare

RMK: Compare with FACT: If A, B are finite sets of same cardinality n , then $f: A \rightarrow B$ is injective \iff surjective

RMK: See p. 201 for some equivalent ways to phrase $A: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is surjective or is injective, when $m \neq n$.

Another curious fact relates A and A^T .

$\text{img}(A) = \text{span}\{\text{columns of } A\}$ has $\dim(\text{img}(A)) = \text{rank}(A)$
 $= \{x_1 \bar{a}_1 + \dots + x_n \bar{a}_n : x_i \in \mathbb{R}\} = \text{the column space of } A$

so $\text{img}(A^T) = \text{span}\{\text{rows of } A\} = \text{the row space of } A$.

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PROP 2.5.11 ("row rank = column rank")

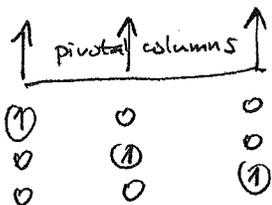
For any matrix A , $\text{rank}(A) = \text{rank}(A^T)$,

i.e. column space and row space have same dimension.

proof: Invertible row operations don't affect the row space (Why?),
so ~~if~~ if A row-reduce \tilde{A} then $\text{rank}(A^T) = \text{rank}(\tilde{A}^T)$
" $\text{dim}(\text{row space of } \tilde{A}^T)$

But the rows containing a pivotal 1 in \tilde{A} give a basis for the row space, since the other rows are zero, and restricting to the pivotal columns they look like $I_r = \begin{pmatrix} 1 & & 0 \\ & \ddots & \\ 0 & & 1 \end{pmatrix}$

e.g.
$$\tilde{A} = \begin{bmatrix} 0 & \textcircled{1} & * & 0 & * & 0 & * & * & * \\ 0 & 0 & 0 & \textcircled{1} & * & * & 0 & * & * \\ 0 & 0 & 0 & 0 & 0 & 0 & \textcircled{1} & * & * \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$



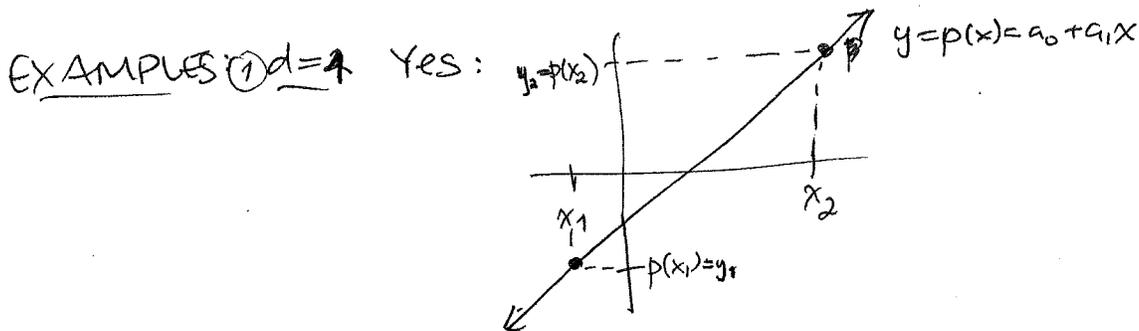
Hence $\text{dim}(\text{img } \tilde{A}^T) = \# \text{pivotal ones in } \tilde{A} = \text{rank}(A) = \text{dim}(\text{img } A)$

An application of cor 2.5.10 lets us answer this question:

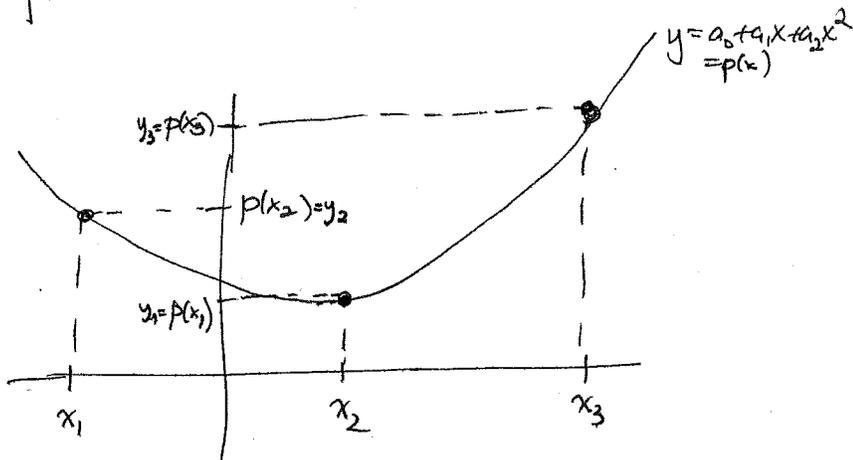
Can we find a polynomial of degree d , say $p(x) = a_0 + a_1x + \dots + a_dx^d$,
that has $d+1$ specified values $y_1 = p(x_1), \dots, y_{d+1} = p(x_{d+1})$
at $d+1$ specified x_1, \dots, x_{d+1} ?

This is called interpolating the points $(x_1, \underset{y_1}{p(x_1)}), \dots, (x_{d+1}, \underset{y_{d+1}}{p(x_{d+1})})$ with the polynomial $p(x)$.

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(2) $d=2$: Seems plausible:



THM: Yes, it can always be done, for any d .

proof: If we want to find a polynomial

$$p(x) = a_0 + a_1x + \dots + a_dx^d \text{ that}$$

interpolates $(x_1, y_1), \dots, (x_{d+1}, y_{d+1})$,

we'd like to solve for a_0, a_1, \dots, a_d as

unknowns in a system of equations

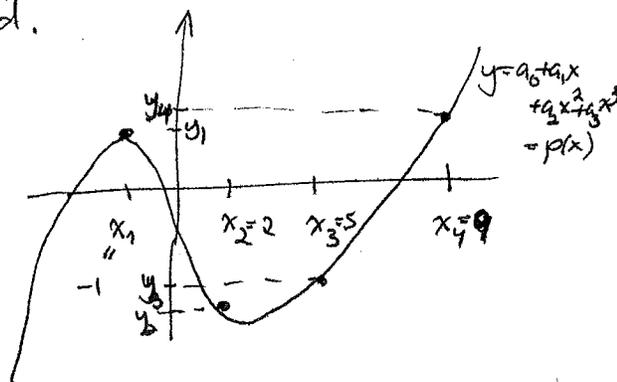
$$y_1 = p(x_1) = a_0 + a_1x_1 + a_2x_1^2 + \dots + a_dx_1^d$$

\vdots

$$y_{d+1} = p(x_{d+1}) = a_0 + a_1x_{d+1} + a_2x_{d+1}^2 + \dots + a_dx_{d+1}^d$$

$$\begin{bmatrix} y_1 \\ \vdots \\ y_{d+1} \end{bmatrix} = \begin{bmatrix} 1 & x_1 & x_1^2 & \dots & x_1^d \\ 1 & x_2 & x_2^2 & \dots & x_2^d \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & x_{d+1} & x_{d+1}^2 & \dots & x_{d+1}^d \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ \vdots \\ a_d \end{bmatrix}$$

called a Vandermonde matrix for x_1, x_2, \dots, x_{d+1}



$$\begin{bmatrix} 1 & -1 & (-1)^2 & (-1)^3 \\ 1 & 2 & 2^2 & 2^3 \\ 1 & 5 & 5^2 & 5^3 \\ 1 & 9 & 9^2 & 9^3 \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ a_2 \\ a_3 \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \end{bmatrix}$$

Vandermonde matrix for $(1, 2, 5, 9)$
 x_1, x_2, x_3, x_4

e.g. $d=3$

$$\begin{aligned} x_1 &= -1 \\ x_2 &= 2 \\ x_3 &= 5 \\ x_4 &= 9 \end{aligned}$$

We'd like to know that this $(d+1) \times (d+1)$ matrix is invertible, since then a solution always exists.

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