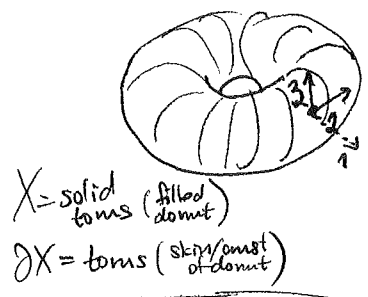


$k=3$ $X =$ a 3-dim'l manifold with boundary surfaces S_1, S_2, \dots, S_r



$$\int_X \overset{3\text{-form}}{d\varphi} = \int_{\partial X} \overset{2\text{-form}}{\varphi} = \sum_{i=1}^r \int_{S_i} \varphi$$

a volume integral a sum of flux integrals

Turns out we'll need to integrate more generally over "pieces-with-boundary" $X \subset M$ when M is a manifold ...

Our old notion of boundary $\partial X = \overline{X} - \overset{\circ}{X}$ is not what we want, inside of M ...

closure of X interior of X

DEFIN 6.6.1: For $X \subset M$ a k -dim'l manifold

- the boundary of X in M

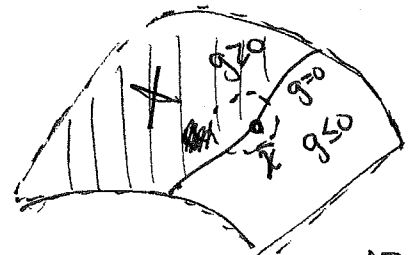
$$\partial_M X := \{ \bar{x} \in M : \text{every open set } U \ni \bar{x} \text{ has both } U \cap X \neq \emptyset, U \cap (M-X) \neq \emptyset \}$$

- the smooth points in $\partial_M X$

$$\partial_M^s X := \{ \bar{x} \in M : \text{not only is there some } U \overset{\text{open}}{\cap} \mathbb{R}^n \xrightarrow{\bar{f}} \mathbb{R}^{n-k} \text{ in } C^1(U),$$

U containing \bar{x} , such that $U \cap M = \bar{f}^{-1}(0)$,
 $D\bar{f}(\bar{x})$ surjective

but one can extend it to $U \overset{\text{open}}{\cap} \mathbb{R}^n \xrightarrow{\begin{pmatrix} \bar{f} \\ \bar{g} \end{pmatrix}} \mathbb{R}^{n-k+1}$ in $C^1(U)$
 such that $g(\bar{x})=0$, and $U \cap X = \bar{f}^{-1}(0) \cap \{g \geq 0\}$
 $D\begin{pmatrix} \bar{f} \\ \bar{g} \end{pmatrix}(\bar{x})$ surjective,



$$U \cap M = \{ \bar{f} = 0 \}$$

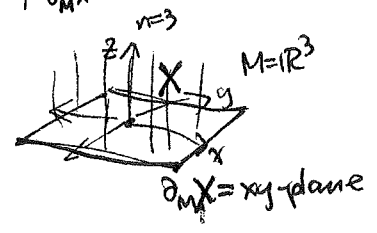
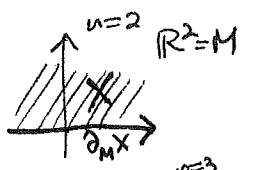
4/17/2017 EXAMPLES:

① Inside $M = \mathbb{R}^n$ itself,

$$X = \{ \bar{x} = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} : x_n \geq 0 \}$$

$$\partial_M X = \{ \bar{x} = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} : x_n = 0 \} \stackrel{S}{=} \partial_M^s X$$

i.e. the whole boundary $\partial_M X$ in M is smooth



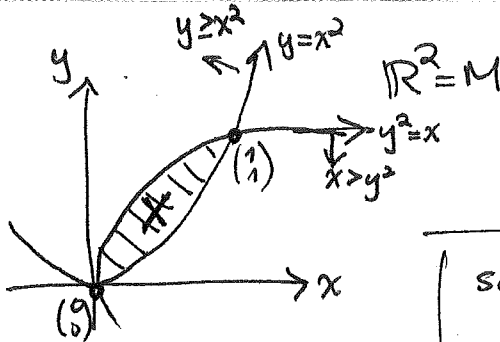
(109)

② (EXAMPLE 6.6.3)

$$X = \left\{ \begin{pmatrix} x \\ y \end{pmatrix} \in \mathbb{R}^2 : \begin{array}{l} y \geq x^2, \\ x \geq y^2 \end{array} \right\}$$

$$\partial_M X = \left\{ \begin{pmatrix} x \\ y \end{pmatrix} \in X : \begin{array}{l} y = x^2 \text{ or} \\ x = y^2 \end{array} \right\}$$

$$\partial_M^s X = \left\{ \begin{pmatrix} x \\ y \end{pmatrix} \in X : \begin{array}{l} y = x^2 \text{ or} \\ x = y^2 \end{array} \text{ but } \begin{pmatrix} x \\ y \end{pmatrix} \neq \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \end{pmatrix} \right\}$$



see (NON-) EXAMPLE 6.6.4 in book for $X \subset \mathbb{R}^2 = M$ having $\partial_M^s X = \emptyset$! (called the Koch snowflake a fractal!)

~~PROP~~ PROP 6.6.5: $\partial_M^s X$ is always a $(k-1)$ -dim'l manifold.

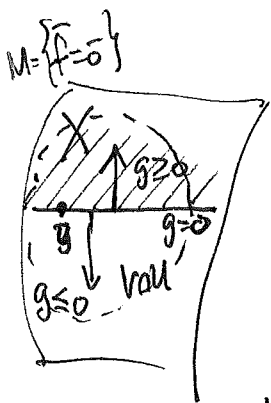
proof: Because $\begin{pmatrix} f \\ g \end{pmatrix} : U \rightarrow \mathbb{R}^{\overset{n-(k-1)}{m-k+1}}$ is in $C^1(U)$,

and $D\begin{pmatrix} f \\ g \end{pmatrix}(\bar{x})$ is ~~surjective~~ ^{i.e.} full rank $n-(k-1)$,

there is some neighborhood V of \bar{x} with $D\begin{pmatrix} f \\ g \end{pmatrix}(\bar{y})$ of full rank (why?),

and hence on $V \cap U$, the locus $Y = \begin{pmatrix} f \\ g \end{pmatrix} = \bar{0}$ defines a $(k-1)$ -dim'l manifold by Implicit Function Thm.

Then check that since $X \cap U = \{ \bar{f} = \bar{0}, g \geq 0 \}$, and $D\begin{pmatrix} f \\ g \end{pmatrix}(\bar{y})$ has full rank for each $\bar{y} \in Y = \begin{pmatrix} f \\ g \end{pmatrix} = \bar{0}$, the set $\partial_M X \cap (V \cap U) = Y$ \square



^{not too hard;} back suggests showing $T_{\bar{y}} M \xrightarrow{Dg} \mathbb{R}$ is surjective as a 1st step. Still a nontrivial exercise!

~~DEFIN 6.6.6~~ DEFIN 6.6.6: Call a compact subset $X \subset M$ (a k -dim'l manifold)

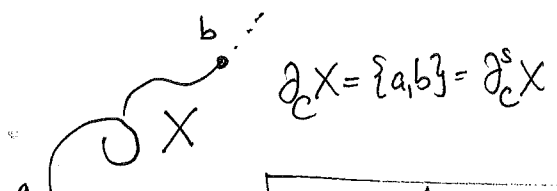
a piece-with-boundary in M if $\bullet \text{vol}_k(\partial_M^s X) < \infty$

and $\bullet \text{vol}_{k-1}(\underbrace{\partial_M X - \partial_M^s X}_{\text{non-smooth points in } \partial_M X}) = 0$

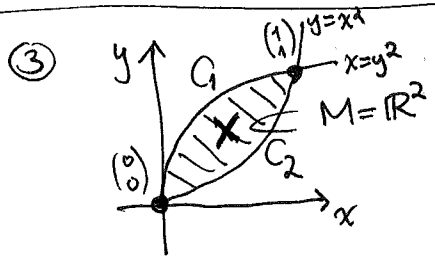
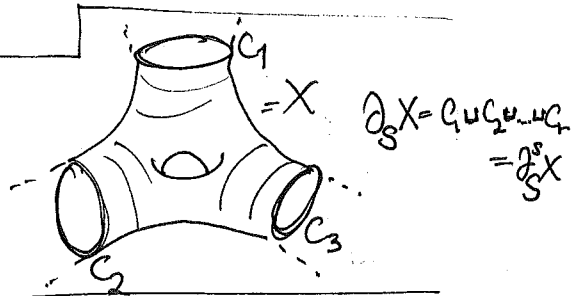
(Not used in our book, but X is just a plain-old manifold-with-boundary if $\partial_M X = \partial_M^s X$, i.e. its entire boundary in M is smooth.)

EXAMPLES:

- ① $k=1$ curves with endpoints C a smooth curve



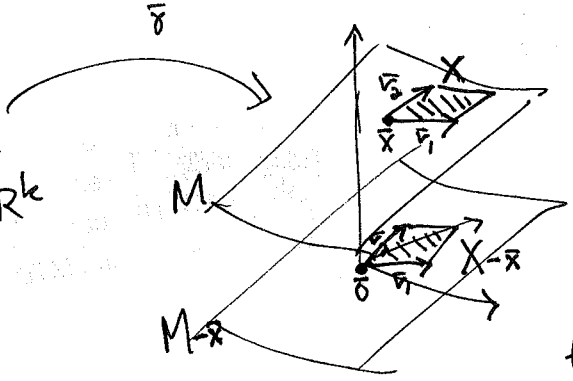
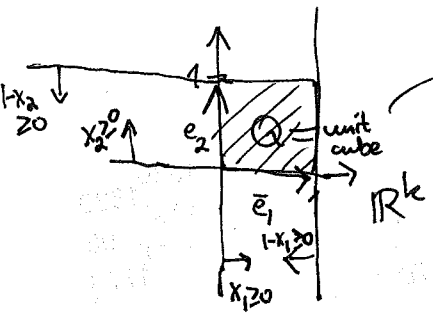
- ② $k=2$ surfaces with boundary curves C_1, C_2, \dots, C_n
 $X \cap S$ a smooth surface



$\partial_M X = C_1 \cup C_2$
 $\partial_M^S X = C_1 \cup C_2 - \{(0,0), (1,1)\}$ (why?)

- ④ Parallelepipeds $X = P_{\bar{x}}(\bar{v}_1, \dots, \bar{v}_k) \subset \mathbb{R}^n$ are always pieces-with-boundary inside the k -dim manifold $M = \{ \bar{x} + t_1 \bar{v}_1 + \dots + t_k \bar{v}_k : t_i \in \mathbb{R} \}$

the (affine) k -dim subspace containing X



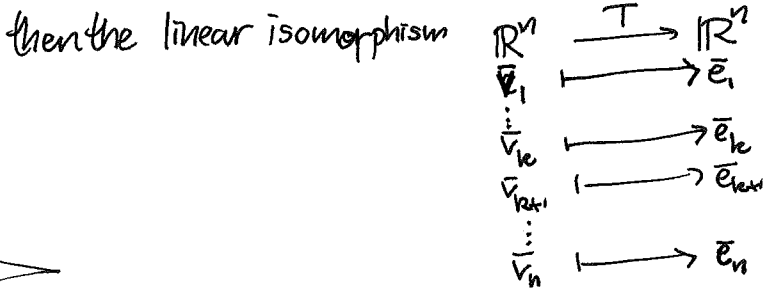
Not hard to check X is compact (=closed, bounded).

For each $(k-1)$ -dim "face" of X , to get the appropriate functions

$\mathbb{R}^n \xrightarrow{\begin{pmatrix} f \\ g \end{pmatrix}} \mathbb{R}^{n-(k-1)}$
 $\bar{y} \longmapsto \begin{pmatrix} f(\bar{y}) \\ g(\bar{y}) \end{pmatrix}$

it's probably easier to work with $X - \bar{x} = P_{\bar{0}}(\bar{v}_1, \dots, \bar{v}_k)$

since then if one extends $\bar{v}_1, \dots, \bar{v}_k$ to a basis $\bar{v}_1, \dots, \bar{v}_k, \bar{v}_{k+1}, \dots, \bar{v}_n$ for \mathbb{R}^n ,



lets one define $\bar{f}(\bar{y}) = \begin{pmatrix} T(\bar{y})_{k+1} \\ \vdots \\ T(\bar{y})_n \end{pmatrix}$

to cut out $M - \bar{x}$ as $\bar{f}^{-1}(\bar{0})$, and cut out various faces/half spaces via $g(\bar{y}) = T(\bar{y})_{i,20} \geq 0$ for $i=1,2,\dots,k$ or $1 - T(\bar{y})_{i,20} \geq 0$

4/19/2017

⑤ see NON-EXAMPLES 6.6.8, 6.6.9 in book!