

HA-7 Solutions

1) Stable manifold is of the form

$$W = h^S(u) = h_2^S u^2 + \mathcal{O}(u^3)$$

$$h_2^S = -\frac{1}{2(2+s)} f_{uu}(0)$$

$$\hookrightarrow u' = -u + f(u, h^S(u))$$

on W^S . Since $f = \mathcal{O}(2)$,

$$u' = -u + \frac{1}{2} f_{uu}(0,0) u^2 + \mathcal{O}(3)$$

Ausatz $u = u_0 e^{-t} + u_2 e^{-2t} + \dots$ gives

$$-2u_2 = -u_2 + \frac{1}{2} f_{uu} u_0^2 \quad \text{at } \mathcal{O}(e^{-2t})$$

$$\hookrightarrow u = u_0 e^{-t} - \frac{1}{2} f_{uu}(0) u_0^2 e^{-2t} + \dots$$

$$v = h_2^S u_0^2 e^{-2t}$$

Now show that remainders are actually small!

Here, geometric proof:

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$$f' = -f$$

$$u' = -u + \alpha u^2 + \mathcal{O}(3)$$

find $u = h(f)$ invariant manifold

$$u_1 = u/f \quad \text{new variable}$$

$$u_1' f + u_1 f' = -u_1 f + \alpha u_1^2 f^2 + \mathcal{O}(f^3)$$

$$\begin{cases} u_1' = \alpha u_1^2 f + \mathcal{O}(f^2) \\ f' = -f \end{cases}$$

$$\text{eq' } f=0, u_1 = u_0^*, \quad \text{lin} \begin{pmatrix} 0 & \alpha u_0^2 \\ 0 & -1 \end{pmatrix}$$

\hookrightarrow ex. strong stable mfd

$$u_1 = u_0 + \alpha u_0^2 f + \mathcal{O}(f^2)$$

$$\hookrightarrow u = u_0 e^{-t} - \alpha u_0^2 e^{-2t} + \mathcal{O}(e^{-3t})$$

W

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$$3) \quad u' = -u + v, \quad v' = -v + u^2$$

$$u = u_1, \quad v = u_1 v_1$$

$$\boxed{u_1' = -u_1 + u_1 v_1} \quad \boxed{v_1' u_1 + v_1 u_1' = -u_1 v_1 + u_1^2}$$

$$\hookrightarrow v_1' + v_1(-u_1 + v_1) = -v_1 + u_1$$

$$\boxed{v_1' = u_1 + v_1^2}$$

$$u_1 = 0 \text{ invariant}, \quad v_1' = v_1^2$$

lin. at origin

$$\begin{pmatrix} -1 & 0 \\ 1 & 0 \end{pmatrix}$$



$$\hookrightarrow \text{strongly stable w.r.t } v_1 = -u_1 + \mathcal{O}(2)$$

$$v = -u^2 + \mathcal{O}(3), \quad \text{target to } v = 0. \quad \mu$$

$$4) a) \quad x' = -x, \quad y' = -2y + x^2$$

$$y = h_2 x^2 + \mathcal{O}(3)$$

$$2h_2 x \underbrace{x'}_{-x} = -2h_2 x^2 + x^2 + \mathcal{O}(3)$$

h_2 -terms cancel!

$$0 = x^2 + \mathcal{O}(3) \quad \downarrow$$

$x(t) = x_0 e^{-t}$ $x_0 = 1$ wlog.
 $y(t) = y_0 e^{-2t} + x_0^2 t e^{-2t}$ $t = -\log x$

$$\Rightarrow y = y_0 x^2 + (-\log x) x^2$$

$\notin C^2$ \Downarrow

2) a) (i) $x=y=z=0$, lin. $(1, 1, 1)$, unstable

b) (ii) $x=y=z \neq 0$, $x = (1+b+c)^{1/2}$ if $1+b+c > 0$

lin' has eigenspace $(1,1,1)^T$, eig'val' -2

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cyclic permutations, the two other eigenvalues are complex conjugate

$$\frac{(-2 + b + c \pm \sqrt{3} \sqrt{-(b-c)^2})}{(1+b+c)}$$

> 0

\rightarrow stable if $b+c-2 < 0$

unstable if $b+c-2 > 0$

(iii) $x \geq 0, y = z = 0 \rightarrow x = 1,$

$$\lambda_1 = -2, (1, 0, 0)^T$$

$$\lambda_2 = 1 - c, (0, 1, 0)^T$$

$$\lambda_3 = 1 - b, (0, 0, 1)^T$$

\Rightarrow stable iff $c, b > 1$

(iv) $x = 0, y, z \neq 0$

$$\rightarrow y = \sqrt{\frac{1-b}{bc-1}}$$

$$\hookrightarrow 1 - y^2 - bz^2 = 0$$

$$1 - z^2 - cy^2 = 0$$

$$z = \sqrt{\frac{1-c}{bc-1}}$$

if square roots are real

so $\frac{bc > 1, b, c < 1}{bc < 1, b, c > 1} (b, c < 0!)$

$$bc < 1, b, c > 1 \quad \downarrow$$

one eigenvalue is $\frac{2(b-1)(c-1)}{bc-1} > 0$

hence always unstable.

(v) other eq': $x, y, z > 0$ and not all equal

$$\begin{aligned} \hookrightarrow 1 - x^2 - by^2 - cz^2 &= 0 \\ 1 - y^2 - bz^2 - cx^2 &= 0 \\ 1 - z^2 - bx^2 - cy^2 &= 0 \end{aligned} \quad \rightarrow \text{linear in } x^2, y^2, z^2$$

\hookrightarrow unique sol' ($x^2=y^2=z^2$) if $\det \neq 0$

$$\begin{vmatrix} -1 & -b & -c \\ -c & -1 & -b \\ -b & -c & -1 \end{vmatrix} = 0 \Leftrightarrow \begin{array}{l} \text{I) } b+c = -1 \text{ or} \\ \text{II) } b=c=1 \end{array}$$

II) all eq' on $S^2 = \{x^2+y^2+z^2=1\}$,
not hyperbolic.

I) kernel 1d, spanned by $(1,1,1)^T$, also
column. \Rightarrow this $(1,1,1)$ not in range
 \hookrightarrow no sol'.

(b) not: $b, c > 1, b, c < 1$, $\left\{ \begin{array}{l} \text{so } b > 1 > c, bc < 1, \\ b+c > 2 \end{array} \right.$

(c)



solutions spiral out
towards a "triangle" in
coordinate planes $\cap S^2$

(d) The stable manifold of $\{x > 0, y = z = 0\}$ is two-dimensional by the linearization.

Restricting to a coordinate plane, we find that the eq' is stable inside the coordinate plane. By invariance of the coordinate planes, W^s (which is unique) is therefore contained in the plane.

Similarly, the stable mfd of $(x = y = z > 0)$ is contained in $\{x = y = z\}$.