

AA3 - Sol

1) (i)

$$\bar{T}^{-1} A \bar{T} = (\text{id} + \mu \bar{T}_1)^{-1} A (\text{id} + \mu \bar{T}_1) =$$

$$(\text{id} - \mu \bar{T}_1 + \mathcal{O}(\mu^2)) A (\text{id} + \mu \bar{T}_1) = A + \mu [A, \bar{T}_1] + \mathcal{O}(\mu^2)$$

$$(ii) \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} t_{11} & t_{12} \\ t_{21} & t_{22} \end{pmatrix} - \begin{pmatrix} t_{11} & t_{12} \\ t_{21} & t_{22} \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} t_{21} & t_{22} - t_{11} \\ 0 & -t_{21} \end{pmatrix}$$

$$(iii) \begin{pmatrix} a & 0 \\ b & a \end{pmatrix} + \begin{pmatrix} \alpha & \beta \\ 0 & -\alpha \end{pmatrix} = \begin{pmatrix} a+\alpha & \beta \\ b & a-\alpha \end{pmatrix} \text{ general matrix}$$

(iv) Solve $\begin{matrix} \text{ } \\ \text{ } \\ \text{ } \end{matrix}$

$$\begin{pmatrix} \mu a & 1 \\ \mu b & \mu a \end{pmatrix} = \begin{pmatrix} \mu a_{11} & 1 + \mu a_{12} \\ \mu a_{21} & \mu a_{22} \end{pmatrix} + \mu (A \bar{T}_1 - \bar{T}_1 A) + \mathcal{O}(\mu^2)$$

$$a = a_{11} + t_{21} + \mathcal{O}(\mu)$$

$$0 = a_{12} + t_{22} - t_{11} + \mathcal{O}(\mu)$$

$$b = a_{21} + \mathcal{O}(\mu)$$

$$a = a_{22} - t_{21} + \mathcal{O}(\mu)$$

$t_{11} = 0$, lin' in a, t_{21}, t_{22}, b is impossible

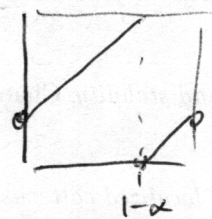
$\rightarrow \bar{T}^{-1}$ for sol!

$$(v) \langle \text{ad}_l(A)u, v \rangle = \text{tr}((Au - uA)v^T) = \text{tr}(Auv^T - uAv^T)$$

$$\begin{aligned} \langle u, \text{ad}_l(A^T)v \rangle &= \text{tr}(u(A^T v - vA^T)^T) \\ &= \text{tr}(u v^T A - u A v^T) \end{aligned}$$

$$\text{tr}(u v^T A) = \text{tr}(A u v^T) \quad \text{since } \text{tr}(abc) = \text{tr}(cab)$$

2) (i)



$$x = 1-x \Rightarrow k(x) = l+1$$

(more iterations needed)

$$x = 1 \Rightarrow k(x) = l$$

$$\underbrace{l + l\alpha}_{\text{iterations}} - 1 \geq 1 - \alpha$$

$$l + (l-1)\alpha - 1 < 1 - \alpha$$

$$\frac{1}{\alpha} > l > \frac{1}{\alpha} - 1 \Rightarrow l = \left\lceil \frac{1}{\alpha} \right\rceil$$

(ii) Since $1 = (1-\alpha) + \alpha = \mathcal{P}_\alpha(1-\alpha)$

(iii) $\phi(1-\alpha) = (l+1)\alpha + (1-\alpha) - 1 = \left\lceil \frac{1}{\alpha} \right\rceil \cdot \alpha$

renormalize: subtract $1-\alpha \hookrightarrow \left\lceil \frac{1}{\alpha} \right\rceil \cdot \alpha - (1-\alpha)$

scale $\frac{1}{\alpha} \hookrightarrow \left\lceil \frac{1}{\alpha} \right\rceil - \frac{1}{\alpha} + 1$

reflect $1-\alpha \hookrightarrow \frac{1}{\alpha} - \left\lceil \frac{1}{\alpha} \right\rceil$

$$(iv) \quad \alpha = \frac{1}{a_1 + \frac{1}{a_2 + \dots}} \quad a_1 = \left[\frac{1}{\alpha} \right],$$

$$\frac{1}{a_2 + \dots} = \frac{1}{\alpha} - \left[\frac{1}{\alpha} \right]$$

So iterating the map $x \mapsto \frac{1}{x} - \left[\frac{1}{x} \right]$

gives the sequence of rational numbers,

which are $\frac{1}{a_1 + \frac{1}{a_2 + \dots}}$, $\frac{1}{a_2 + \frac{1}{a_3 + \dots}}$, $\frac{1}{a_3 + \frac{1}{a_4 + \dots}}$

$$\text{and } a_j = \left[\frac{1}{\alpha_j} \right] \quad , \quad \alpha_{j+1} = \frac{1}{\alpha_j} - \left[\frac{1}{\alpha_j} \right]$$

(v) Clearly every orbit has to hit J_1 precisely once since J_1 has length α , before returning (or $y_0 + 1$) to J_0 . Therefore l

$$\text{is } \left[\frac{l-\alpha}{\alpha} \right] = \left[\frac{1}{\alpha} \right] - 1$$

(vi) The number of iterates for the return map jumps precisely at the "jump location", such that the length of the block encodes location relative to $l-\alpha$, in the renormalized map