

Introduction to Partial Differential Equations

by Peter J. Olver

Corrections to Second Printing (2016)

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*** Page 8 ***

Exercise 1.10(a): change $4t^2 - x^2$ to $4t^2 + x^2$.

*** Page 31 ***

Exercise 2.2.31(b): insert $= 0$ in equation: $u_t + yu_x - xu_y = 0$.

*** Page 57 ***

In the last two displayed formulas, the first term on the right hand side of the equals sign is missing a minus sign:

$$\frac{\partial v}{\partial \xi}(\xi, \eta) = -\frac{1}{2c} \frac{\partial u}{\partial t} \left(\frac{\eta - \xi}{2c}, \frac{\eta + \xi}{2} \right) + \frac{1}{2} \frac{\partial u}{\partial x} \left(\frac{\eta - \xi}{2c}, \frac{\eta + \xi}{2} \right),$$

and so, in particular,

$$\frac{\partial v}{\partial \xi}(\xi, \xi) = -\frac{1}{2c} \frac{\partial u}{\partial t}(0, \xi) + \frac{1}{2} \frac{\partial u}{\partial x}(0, \xi) = 0,$$

*** Page 82 ***

Exercise 3.2.14: insert after first sentence:

(See (3.81) for the definition of the function $\text{sign } x$.)

*** Page 105 ***

Line -4: change “second derivative” to “first derivative”

*** Page 108 ***

Line 2 before (3.106): remove square root from “... equal to $\frac{1}{2\pi} \int_a^b |\varphi(x)|^2 dx$.”

*** Page 131 ***

In (4.37), change final $+$ to $-$:

$$u(t, x) \approx \frac{1}{2} a_0 + e^{-t} (a_1 \cos x + b_1 \sin x) = \frac{1}{2} a_0 + r_1 e^{-t} \cos(x - \delta_1), \quad (4.37)$$

*** Page 152 ***

Line -6: change "... appear the context of boundary value problems." to "... appear in the context of boundary value problems."

*** Page 153 ***

Line 5 after (4.86): change "heat flux out of a plate" to "heat flux into a plate"

*** Page 163 ***

Last line of table: change $x^4 - 4x^2y^2 + y^4$ to $x^4 - 6x^2y^2 + y^4$

*** Page 170 ***

Exercise 4.3.25(b): change $x^2 + y^2 = 1$; to $x^2 + y^2 = 2$;

*** Page 175 ***

Exercise 4.4.12(a): switch t and x in the function: $u_n(t, x) = \frac{\cosh n\pi t \sin n\pi x}{n}$.

*** Page 187 ***

Line 2 before (5.14): change "... heat equation (5.14) ..." to "... heat equation (5.7) ...".

*** Page 188 ***

Example 5.4: change rest of sentence after displayed formula to

"... used earlier in Example 4.1, along with homogeneous Dirichlet boundary conditions, so $u(t, 0) = u(t, 1) = 0$."

*** Page 190 ***

Equation (5.28): change $O((\Delta t)^2)$ to $O(\Delta t)$:

$$\frac{\partial u}{\partial t}(t_j, x_m) \approx \frac{u(t_j, x_m) - u(t_{j-1}, x_m)}{\Delta t} + O(\Delta t). \quad (5.28)$$

*** Page 195 ***

Change sentence after equation (5.40): "We use step sizes $\Delta t = \Delta x = .005$, set $\ell = 1$, and try four different values of the wave speed."

*** Page 198 ***

Equation (5.45): change denominator to $2\Delta x$:

$$\frac{\partial u}{\partial x}(t_j, x_m) \approx \frac{u_{j,m+1} - u_{j,m-1}}{2\Delta x} + O((\Delta x)^2). \quad (5.45)$$

*** Page 200 ***

Line 4 after (5.50): reverse the inequality: $\Delta x/\Delta t \geq |c_{j,m}|$

*** Page 250 ***

Displayed formula after Theorem 6.17: change \mathbb{R}^2 to Ω :

$$u(x, y) = - \iint_{\Omega} G_0(x, y; \xi, \eta) \Delta u(\xi, \eta) d\xi d\eta.$$

Equation (6.108): change \mathbb{R}^2 to Ω twice:

$$\iint_{\Omega} \delta(x - \xi) \delta(y - \eta) u(\xi, \eta) d\xi d\eta = \iint_{\Omega} -\Delta G_0(x, y; \xi, \eta) u(\xi, \eta) d\xi d\eta. \quad (6.108)$$

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Equation (6.135): correct left hand side:

$$\frac{\partial G}{\partial \rho}(r, \theta; 1, \phi) = -\frac{1}{2\pi} \frac{1 - r^2}{1 + r^2 - 2r \cos(\theta - \phi)}, \quad (6.135)$$

*** Pages 276–7 ***

The proof of Proposition 7.10 is flawed. Since $k \delta(k) \equiv 0$, dividing equation (7.47) by $i k$ could also introduce a multiple of the delta function, and it seems difficult to dismiss this term. A better proof uses the Convolution Theorem 7.13, as follows.

The first step is to note that we can write the integral of $f(x)$ as a convolution with the step function:

$$g(x) = \int_{-\infty}^x f(\xi) d\xi = \int_{-\infty}^{\infty} \sigma(x - \xi) f(\xi) d\xi,$$

Thus, according to the convolution formula (7.55),

$$\widehat{g}(k) = \sqrt{2\pi} \widehat{\sigma}(k) \widehat{f}(k).$$

Consulting our Table of Fourier transforms, we find

$$\widehat{g}(k) = \sqrt{2\pi} \left(\sqrt{\frac{\pi}{2}} \delta(k) - \frac{i}{\sqrt{2\pi} k} \right) \widehat{f}(k) = -\frac{i}{k} \widehat{f}(k) + \pi \widehat{f}(k) \delta(k) = -\frac{i}{k} \widehat{f}(k) + \pi \widehat{f}(0) \delta(k),$$

which establishes the desired formula.

** Thanks to William Young for alerting me to this issue and for sharing the above convolution-based proof.

*** Page 277 ***

In the displayed equation immediately above the Exercises, delete one factor of $1/k$ in the first term after the equals sign:

$$\widehat{f}(k) = \left(-\frac{i}{k} \sqrt{\frac{\pi}{2}} e^{-|k|} + \frac{\pi^{3/2}}{\sqrt{2}} \delta(k) \right) - \frac{\pi^{3/2}}{\sqrt{2}} \delta(k) = -i \sqrt{\frac{\pi}{2}} \frac{e^{-|k|}}{k}.$$

*** Page 278 ***

Exercise 7.2.12. insert factor of $\sqrt{2\pi}$ in formula $\hat{f}(k) = \sqrt{2\pi} \sum_{n=-\infty}^{\infty} c_n \delta(k-n)$.

*** Page 310 ***

Second displayed formula after equation (8.63): insert missing factor of $\frac{1}{2}$:

$$u(t, x) = c_1 + c_2 \operatorname{erf}\left(\frac{x}{2\sqrt{t}}\right).$$

*** Page 363 ***

Insert parenthetical comment at end of page:

(The case $q(x) \equiv 0$ can also be positive definite, when subject to suitable boundary conditions, but is treated differently, in accordance with the weighted inner product construction appearing in Example 9.23.)

*** Page 389 ***

Change (9.131–132) to the following:

$$\begin{aligned} u(t, x) &= \sum_{k=1}^{\infty} [c_k u_k(t, x) + d_k \tilde{u}_k(t, x)] \\ &= \sum_{k=1}^{\infty} [c_k \cos(\omega_k t) + d_k \sin(\omega_k t)] v_k(x) = \sum_{k=1}^{\infty} r_k \cos(\omega_k t - \delta_k) v_k, \end{aligned} \tag{9.131}$$

where (r_k, δ_k) are the polar coordinates of (c_k, d_k) :

$$c_k = r_k \cos \delta_k, \quad d_k = r_k \sin \delta_k. \tag{9.132}$$

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Change (9.145) to the following:

$$0 = \langle h - 2a\omega_k v_k, v_k \rangle = \langle h, v_k \rangle - 2a\omega_k \|v_k\|^2, \quad \text{and hence} \quad a = \frac{\langle h, v_k \rangle}{2\omega_k \|v_k\|^2}, \tag{9.145}$$

*** Page 392 ***

Correct sign errors in (9.149):

$$v_*(x) = \frac{\sin k\pi x}{k^2 \pi^2 c^2 - \omega^2}, \quad \text{so that} \quad u_*(t, x) = \frac{\cos \omega t \sin k\pi x}{k^2 \pi^2 c^2 - \omega^2}, \tag{9.149}$$

and in the last displayed equation:

$$z(0, x) = f(x) - \frac{\sin k\pi x}{k^2 \pi^2 c^2 - \omega^2}, \quad \frac{\partial z}{\partial t}(0, x) = g(x),$$

*** Page 411 ***

Line 9 in paragraph beginning “The first ...”: change “vertexvertices” to “vertices”.

*** Page 413 ***

Last equation in (10.32): change y_k to y_l :

$$\begin{aligned}\omega_l^\nu(x_i, y_i) &= \alpha_l^\nu + \beta_l^\nu x_i + \gamma_l^\nu y_i = 0, \\ \omega_l^\nu(x_j, y_j) &= \alpha_l^\nu + \beta_l^\nu x_j + \gamma_l^\nu y_j = 0, \\ \omega_l^\nu(x_l, y_l) &= \alpha_l^\nu + \beta_l^\nu x_l + \gamma_l^\nu y_l = 1.\end{aligned}\tag{10.32}$$

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The first term in the integral in (10.38) is the Euclidean norm of a vector:

$$\begin{aligned}Q[w] &= Q \left[\sum_{i=1}^n c_i \varphi_i \right] = \iint_{\Omega} \left[\left\| \sum_{i=1}^n c_i \nabla \varphi_i \right\|^2 - f(x, y) \left(\sum_{i=1}^n c_i \varphi_i \right) \right] dx dy \\ &= \frac{1}{2} \sum_{i,j=1}^n k_{ij} c_i c_j - \sum_{i=1}^n b_i c_i = \frac{1}{2} \mathbf{c}^T K \mathbf{c} - \mathbf{b}^T \mathbf{c}.\end{aligned}\tag{10.38}$$

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Correct last line in (10.45):

$$\begin{aligned}k_{ij}^\nu &= \frac{1}{2} \frac{(y_j - y_l)(y_l - y_i) + (x_l - x_j)(x_i - x_l)}{(\Delta_\nu)^2} |\Delta_\nu| = -\frac{(\mathbf{x}_i - \mathbf{x}_l) \cdot (\mathbf{x}_j - \mathbf{x}_l)}{2 |\Delta_\nu|}, \quad i \neq j, \\ k_{ii}^\nu &= \frac{1}{2} \frac{(y_j - y_l)^2 + (x_l - x_j)^2}{(\Delta_\nu)^2} |\Delta_\nu| = \frac{\|\mathbf{x}_j - \mathbf{x}_l\|^2}{2 |\Delta_\nu|} \\ &= \frac{(\mathbf{x}_i - \mathbf{x}_l) \cdot (\mathbf{x}_j - \mathbf{x}_l) + (\mathbf{x}_l - \mathbf{x}_j) \cdot (\mathbf{x}_i - \mathbf{x}_j)}{2 \Delta_\nu} = -k_{ij}^\nu - k_{il}^\nu.\end{aligned}\tag{10.45}$$

*** Pages 418–9 ***

Change first sentence in Example 10.7 to

A metal plate has the shape of an oval running track, consisting of a square, with side lengths 2 m, and two semi-circular disks glued onto opposite sides, as sketched in Figure 10.9.

*** Page 426 ***

Exercise 10.3.16: change $n = 2$ in part (b) to $n = 3$, and change $n = 3$ in part (c) to $n = 4$.

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Exercise 10.4.3(c): change "... wave equation." to "... transport equation."

*** Page 450 ***

Exercise 11.2.12: correct boundary conditions:

$$u(t, 0, y) = u(t, \pi, y) = 0 = u(t, x, 0), \quad u(t, x, \pi) = f(x), \quad 0 < x, y < \pi, \quad t > 0.$$

*** Pages 464–5 ***

In equation (11.91) and the subsequent displayed formula, change all s, t, r to a, b, c :

$$a_0 r(r-1) + b_0 r + c_0 = 0, \tag{11.91}$$

where, referring back to (11.71),

$$a_0 = a(x_0), \quad b_0 = b(x_0), \quad c_0 = c(x_0),$$

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Case (iii): change $r_2 = r_1 + k$ to $r_1 = r_2 + k$; change "smaller" to "larger", and change x^{r_2} to $(x - x_0)^{r_2}$ in equation (11.93):

(iii) Finally, if $r_1 = r_2 + k$, where $k > 0$ is a positive integer, then there is a nonzero solution $\widehat{u}(x)$ with a convergent Frobenius expansion corresponding to the larger index r_1 . One can construct a second independent solution of the form

$$\widetilde{u}(x) = c \log(x - x_0) \widehat{u}(x) + v(x), \quad \text{where} \quad v(x) = (x - x_0)^{r_2} + \sum_{n=1}^{\infty} v_n (x - x_0)^{n+r_2} \tag{11.93}$$

is a convergent Frobenius series, and c is a constant, which may be 0, in which case the second solution $\widetilde{u}(x)$ is also of Frobenius form.

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Correct formulas after equation (11.96) as follows:

$$\begin{aligned} u'' + \left(\frac{1}{x} + \frac{x}{2}\right) u' + u &= v \left[\widehat{u}'' + \left(\frac{1}{x} + \frac{x}{2}\right) \widehat{u}' + \widehat{u} \right] + v' \left[2\widehat{u}' + \left(\frac{1}{x} + \frac{x}{2}\right) \widehat{u} \right] + v'' \widehat{u} \\ &= e^{-x^2/4} \left[v'' + \left(\frac{1}{x} - \frac{x}{2}\right) v' \right]. \end{aligned}$$

If u is to be a solution, v' must satisfy a linear first-order ordinary differential equation:

$$v'' + \left(\frac{1}{x} - \frac{x}{2}\right) v' = 0, \quad \text{and hence} \quad v' = \frac{c}{x} e^{x^2/4}, \quad v = c \int \frac{e^{x^2/4}}{x} + d,$$

where c, d are arbitrary constants. We conclude that the general solution to the original differential equation is

$$\tilde{u}(x) = v(x)\hat{u}(x) = \left(c \int \frac{e^{x^2/4}}{x} + d \right) e^{-x^2/4}. \quad (11.97)$$

★ ★ Thanks to Manuel Mañas for alerting me to this error.

★ ★ ★ Page 471 ★ ★ ★

In Figure 11.5, the graphs of $Y_1(x), Y_2(x), Y_3(x)$ are poorly reproduced:

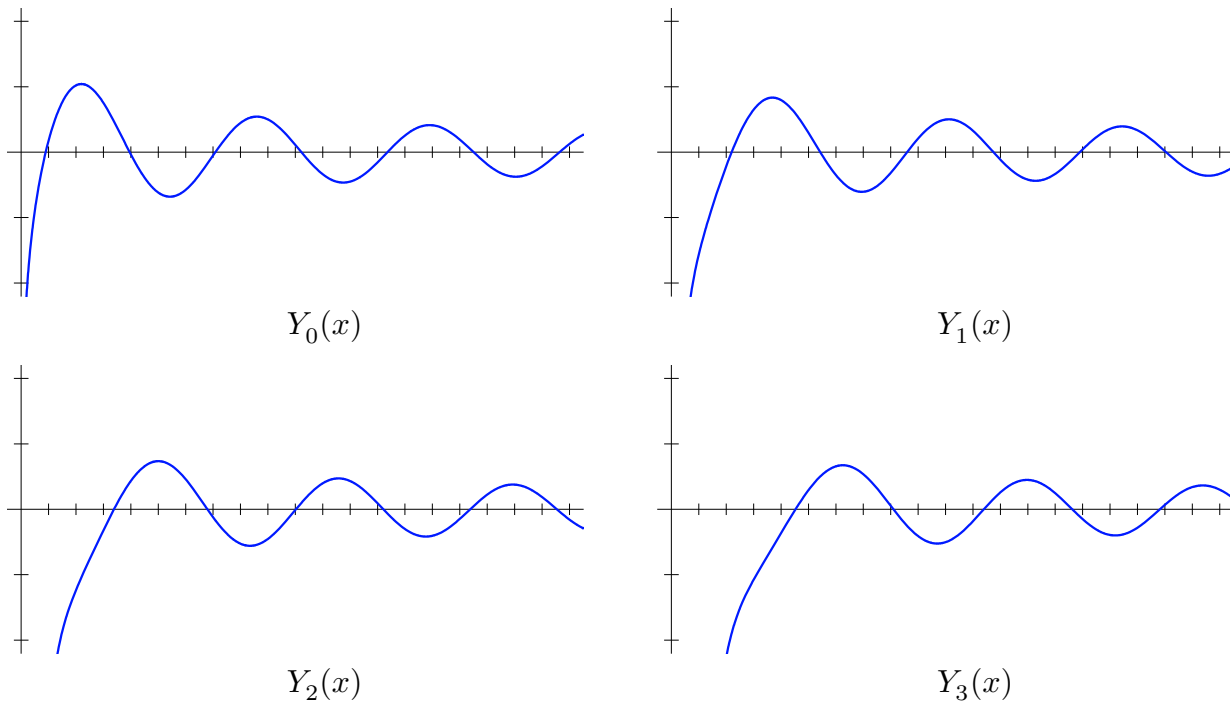


Figure 11.5. Bessel functions of the second kind.

★ ★ ★ Page 489 ★ ★ ★

Add movie symbol $\left[\text{+} \right]$ to Figure 11.10.

★ ★ ★ Page 499 ★ ★ ★

Example 11.15: correct equation 2 lines from the end: $\zeta_{0,1}/\zeta_{0,2} \approx .43565$

★ ★ ★ Page 500 ★ ★ ★

Exercise 11.6.41: switch indices on $\omega_{i,j}$:

$$(a) \omega_{0,4}, \quad (b) \omega_{2,4}, \quad (c) \omega_{4,2}, \quad (d) \omega_{3,3}, \quad (e) \omega_{5,1}.$$

★ ★ ★ Page 532 ★ ★ ★

Line -3: change comma to semicolon in $v(\mathbf{x}; \boldsymbol{\xi})$

*** Page 548 ***

Equation (12.131): add t dependence to $u_{0,0,n}$ and $\widehat{u}_{0,0,n}$, and correct denominators in final expressions:

$$\begin{aligned} u_{0,0,n}(t, r, \varphi, \theta) &= \cos(cn\pi t) S_0(n\pi r) = \frac{\cos cn\pi t \sin n\pi r}{n\pi r}, \\ \widehat{u}_{0,0,n}(t, r, \varphi, \theta) &= \sin(cn\pi t) S_0(n\pi r) = \frac{\sin cn\pi t \sin n\pi r}{n\pi r}, \end{aligned} \quad n = 1, 2, 3, \dots \quad (12.131)$$

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In equation (12.145) and the displayed equation immediately after, the limit should be as $t \rightarrow 0$:

$$\begin{aligned} \lim_{t \rightarrow 0} M_{ct} [f] &= M_0 [f] = f(\mathbf{0}). \quad (12.145) \\ \lim_{t \rightarrow 0} \langle u(t, \cdot), f \rangle &= \langle u(0, \cdot), f \rangle = 0 \quad \text{for all functions } f, \end{aligned}$$

*** Page 555 ***

Replace the period in equation (12.151) by a comma, and replace the following sentence by

where $M_{ct}^{\mathbf{x}} [g]$ denotes the average of the initial velocity function g over the sphere $S_{ct}^{\mathbf{x}} = \{\|\boldsymbol{\xi} - \mathbf{x}\| = ct\}$ of radius ct centered at the point \mathbf{x} . Thus, the value of our solution at position \mathbf{x} and time $t > 0$ only depends upon the initial data a distance ct away from the point \mathbf{x} .

*** Page 579 ***

At the end of the statement of Theorem B.15, add “; for the triangle equality, the scalar multiples must be nonnegative.”

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