

## Practice Problems 2

### Math 5467

#### 1. Least Squares Hyperplanes and Orthogonal Least Squares Planes

a) Create an artificial data set of 1000 points in  $\mathbb{R}^4$  by typing the following Matlab commands

```
x1(1:500,1) = rand(500,1);
x1(501:1000,1) = 2+rand(500,1);
x2(1:500,1) = rand(500,1);
x2(501:1000,1) = 2+rand(500,1);
x3(1:1000,1) = rand(1000,1)/5;
epsilon = 1;
x4 = 0.25*x1+1.3*x2-1.2*x3+23+ epsilon*randn(1000,1);
```

Use SVD decomposition implemented in Matlab (do not use the command *regress*) to find the equation of the least squares approximation of the form  $x_4 = a_1 \cdot x_1 + a_2 \cdot x_2 + a_3 \cdot x_3 + a_0$  (that is, specify the coefficients  $a_0$ ,  $a_1$ ,  $a_2$  and  $a_3$ ) and the corresponding averaged  $l_2$  error, that it minimizes:

$$\left( \frac{1}{N} \sum_{i=1}^N ((x_4)_i - (a_1 \cdot (x_1)_i + a_2 \cdot (x_2)_i + a_3 \cdot (x_3)_i + a_0))^2 \right)^{\frac{1}{2}}.$$

Next, change  $\epsilon = \frac{1}{10}$  and report your answer in that case.

b) Use the data set created above (apply both  $\epsilon = 1$  and  $\epsilon = \frac{1}{10}$  for all of the following questions) to find a 3-dimensional plane which minimizes the orthogonal  $l_2$  error (we refer to it as best  $l_2$  3-plane). Express the plane in the form  $c + \text{Sp}(v_1, v_2, v_3)$ , where  $\{v_1, v_2, v_3\}$  is an orthonormal set of vectors (do not confuse the notation above for the columns  $x_1, x_2, x_3, x_4$  with the different notation used in class for the  $N$  rows of the data matrix, where here  $N = 1000$ ).

c) Form the data matrix  $A$ , whose rows are the data vectors (in  $\mathbb{R}^4$ ) minus the vector  $c$  found above. Then form a  $4 \times 3$  matrix  $P$ , whose columns are  $v_1, v_2, v_3$ . Multiplying  $A$  by  $P$ , we obtain a matrix with the coordinates of the shifted data points projected onto the best (orthogonal)  $l_2$  3-plane (which passes through  $c$ ). Plot the vectors projected on this plane (i.e. the rows of  $A \cdot P$ ; use the command *plot3*). Similarly plot the projection onto the best (orthogonal)  $l_2$  2-plane (use the command *plot*). Does the outcome make sense to you?

d) In <http://www.ics.uci.edu/~mlern/databases/iris/iris.data> you may find the Iris data. It lists information on 150 Iris flowers. It includes three Iris species: Setosa, Versicolour, and Virginica (50 flowers per class). Each flower is characterized by five attributes: sepal length in centimeters,

sepal width in centimeters, petal length in centimeters, petal width in centimeters, class (Setosa, Versicolour, and Virginica). In the attached file to the homework (*Iris\_data.mat*) the data was saved as Matlab file, separated to the 3 classes. In each class a flower is represented by a four dimensional data point according to the first four attributes. Project that data on the best (orthogonal)  $l_2$  2-plane and plot the projected points, where each class is distinguished (use e.g. 'o','x','+'). Which class is easily separated from the others using that projection?

## 2. Image compression

Choose your favorite image of size at least  $512 \times 512$ . Apply SVD compression with 3, 10, 20 and 40 top singular values and vectors. Plot your original image and the “compressed” ones. Also make a table with relative errors and compression ratios (i.e., ratios between sizes of the compressed SVD nonzero components to the sizes of the original matrices) for each of the images.

## 3. Properties of Convolution

You may solve only 5 out the following 6 subquestions.

- Show that if  $v = \{v_i\}_{i \in \mathbb{Z}}$  and  $u = \{u_i\}_{i \in \mathbb{Z}}$  are two vectors in  $\ell_1(\mathbb{Z})$ , then their convolution  $u * v$  is also in  $\ell_1(\mathbb{Z})$ .
- Show that if  $v = \{v_i\}_{i \in \mathbb{Z}}$  and  $u = \{u_i\}_{i \in \mathbb{Z}}$  are two probability vectors in  $\ell_1(\mathbb{Z})$ , that is their elements are positive and sum to 1, then their convolution  $u * v$  is also a probability vector. (If you can, give an interpretation of those probabilities).
- Show that if  $v = \{v_i\}_{i \in \mathbb{Z}} \in \ell_1(\mathbb{Z})$  and  $u = \{u_i\}_{i \in \mathbb{Z}}$  is of period  $N$ , that is for all  $i \in \mathbb{Z}$ :  $u_i = u_{i+N}$ , then their convolution is well defined and is also of period  $N$ .
- Show that the convolution of signals in  $\ell_1(\mathbb{Z})$  is commutative. That is, if  $v = \{v_i\}_{i \in \mathbb{Z}}$  and  $u = \{u_i\}_{i \in \mathbb{Z}}$  are in  $\ell_1(\mathbb{Z})$ , then  $u * v = v * u$ .
- Show that the convolution of signals in  $\ell_1(\mathbb{Z})$  is associative. That is, if  $v, u, w \in \ell_1(\mathbb{Z})$ , then  $(u * v) * w = u * (v * w)$ .
- Let  $p_1(x) = \sum_{i=1}^{11} i \cdot x^i$  and  $p_2(x) = \sum_{i=1}^9 i^2 \cdot x^i$ . By only using the command *conv* in Matlab, find  $p_1(x) \cdot p_2(x)$  (print your Matlab output and explain how it is related to  $p_1(x) \cdot p_2(x)$ ).

## 4. Properties of Correlation

If  $v = \{v_i\}_{i \in \mathbb{Z}}$  and  $u = \{u_i\}_{i \in \mathbb{Z}}$  are two vectors in  $\ell_1(\mathbb{Z})$ , we denote by  $\diamond$  their correlation and by  $\tilde{u}$  and  $\tilde{v}$  their reflection with respect to zero ( $\tilde{u}_i = u_{-i}$ ).

- Show that  $u \diamond v = \widetilde{v \diamond u}$ .
- Show that  $u \diamond v = u * \tilde{v} = \tilde{v} * u$  and  $u * v = u \diamond \tilde{v} = \widetilde{\tilde{v} \diamond u}$ .

## 5. Questions from Textbook

Solve problems 3.1, 3.6 (the solution on the textbook webpage is not sufficiently clearly, i suggest you consider a particular case of 2-bit image, where 0 is obtained with frequency  $p$  and 1 with frequency  $1 - p$  and show what you get by histogram equalization and then conclude on other discrete cases), 3.7, 3.11, 3.14, 3.21, 3.24, 3.29.

## 6. Bonus Problem: Best Low Rank Approximation of a Matrix

You do not need to submit this problem, but you will get bonus points if you solve it correctly (there is no partial credit).

If  $A \in \mathbb{R}^{m \times n}$  is a matrix with rank  $r$  and singular value decomposition  $A = \sum_{j=1}^r \sigma_j u_j v_j^T$  and if  $0 \leq \nu \leq r$ , then we denote

$$A_\nu := \sum_{j=1}^{\nu} \sigma_j u_j v_j^T.$$

You have used this  $\nu$ -rank approximation before in order to compress an image.

a) Prove that

$$\|A - A_\nu\|_2 = \inf_{\substack{B \in \mathbb{R}^{m \times n} \\ \text{rank}(B) \leq \nu}} \|A - B\|_2 = \sigma_{\nu+1}.$$

b) Prove that

$$\|A - A_\nu\|_F = \inf_{\substack{B \in \mathbb{R}^{m \times n} \\ \text{rank}(B) \leq \nu}} \|A - B\|_F = \sqrt{\sum_{i=\nu+1}^r \sigma_i^2}.$$

## 7. Bonus Problem: Geometric Interpretation of PCA

You do not need to submit this problem, but you will get bonus points if you solve it correctly (there is no partial credit).

Let  $\{\underline{x}_i\}_{i=1}^m$  denote a set of  $m$  data points in  $\mathbb{R}^p$ . If  $V$  is a  $d$ -dimensional plane in  $\mathbb{R}^p$  ( $d < p$ ), we denote the  $l_2$  averaged distance of the data set from  $V$  by  $\text{dist}_2(\{\underline{x}_i\}_{i=1}^m, V)$ . That is,

$$\text{dist}_2(\{\underline{x}_i\}_{i=1}^m, V) = \sqrt{\frac{1}{m} \sum_{i=1}^m \text{dist}(\underline{x}_i, V)^2}.$$

Show that a minimizer of this distance among all  $d$ -planes in  $\mathbb{R}^p$  is

$$V = \underline{c} + Sp\{\underline{v}_1, \dots, \underline{v}_d\}, \tag{1}$$

where  $\underline{c}$  is the center of mass (mean) of the data points and  $v_1, \dots, v_d$  are the top  $d$  principal vectors (i.e. the top  $d$  right vectors of the centered data matrix). This  $d$ -plane is unique if and only if the principal values satisfy  $\sigma_d < \sigma_{d+1}$ .

Guide: Represent any  $d$ -plane  $V$  in the form of equation (1), where  $\underline{c}$  is an arbitrary vector in  $\mathbb{R}^p$  and  $\{v_1, \dots, v_d\}$  is an arbitrary orthonormal system in  $\mathbb{R}^p$ ; then express  $\text{dist}_2(\{\underline{x}_i\}_{i=1}^m, V)$  as a function of  $\underline{c}, v_1, \dots, v_d$ . Next, minimize  $\text{dist}_2(\{\underline{x}_i\}_{i=1}^m, V)$  as a function of  $\underline{c}$  for any fixed  $v_1, \dots, v_d$ . The last step of specifying  $Sp\{v_1, \dots, v_d\}$  can be done in different ways, I will let you be creative.