

Crash course on Symplectic Manifolds & Poisson algebras

A symplectic manifold is a manifold M plus "geometric structure" ω

(Analogous to a Riemannian manifold where extra geom. structure is a metric)

Warm-up e.g. A symplectic vector space is a

real vector space V (say of dim d) and a non-degenerate 2-form ω s.t.
i.e. $V \cong \mathbb{R}^d$

$$\omega(\vec{v}, \vec{w}) = \vec{v}^T A \vec{w} \text{ where } A \text{ is a } d \times d \text{ matrix satisfying } A^T = -A \text{ and } \det A \neq 0.$$

e.g. ~~J~~ $J = \begin{bmatrix} 0 & -I \\ I & 0 \end{bmatrix}$ is an example of such a possible A .

Fact: Every symplectic vec. space is even dim ($d=2n$) and has a basis $\{p_1, p_2, \dots, p_n, q_1, q_2, \dots, q_n\}$ s.t.

$$\omega(\vec{v}, \vec{w}) = \vec{v}^T J \vec{w}.$$

Kronecker delta
↓

Thus $\omega(p_i, q_j) = -\omega(q_i, p_j) = \delta_{ij}$
and $\omega = dp_1 \wedge dq_1 + \dots + dp_n \wedge dq_n$.

(2)

Warning: If W is a subspace of symplectic vec. space V , it is possible

for $W^\perp := \{ \vec{v} \in V : w(\vec{v}, \vec{w}) = 0 \ \forall \vec{w} \in W \}$

to satisfy $W \cap W^\perp \neq \{0\}$.

In fact, for any $\vec{v} \in V$, $w(\vec{v}, \vec{v}) = 0$

\Rightarrow If we let $W = \langle \vec{v} \rangle$, one-dim subspace,

$\langle \vec{v} \rangle^\perp \ni \vec{v} \notin V \neq \langle \vec{v} \rangle \oplus \langle \vec{v} \rangle^\perp$, for e.g.

Subspace W of symplectic vec space V is

- symplectic if $W \cap W^\perp = \{0\}$
(i.e. form restricted to W and W^\perp each non-degenerate)
- Lagrangian if $W = W^\perp$
(i.e. form w restricted to W is zero)
- isotropic if $W \subset W^\perp$, or
- co-isotropic if $W^\perp \subset W$.

e.g. For any ^{non zero} $\vec{v} \in V$, $\langle \vec{v} \rangle$ is isotropic.

e.g. any hyperplane (codim 1) is co-isotropic.

③ e.g. In \mathbb{R}^4 w/ coordinates p_1, p_2, q_1, q_2 and

$$\omega = dp_1 \wedge dq_1 + dp_2 \wedge dq_2, \text{ i.e.}$$

$$\omega(\vec{v}, \vec{w}) = \vec{v}^T \begin{bmatrix} 0 & I \\ -I & 0 \end{bmatrix} \vec{w}, \text{ then the}$$

Z-planes $\langle p_1, p_2 \rangle \neq \langle q_1, q_2 \rangle$ are Lagrangian

while the Z-planes $\langle p_1, q_1 \rangle \neq \langle p_2, q_2 \rangle$ are symplectic.

- $p_1 \leftrightarrow [1000]$
- $p_2 \leftrightarrow [0100]$
- $q_1 \leftrightarrow [0010]$
- $q_2 \leftrightarrow [0001]$

so $\omega(p_1, \vec{w}) = [1000] \begin{bmatrix} 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} w_{p_1} \\ w_{p_2} \\ w_{q_1} \\ w_{q_2} \end{bmatrix} = -w_{q_1}$

So $\langle p_1, p_2 \rangle^\perp = \langle p_1, p_2 \rangle$ since $\omega(p_1, q_1) = -1 \neq 0$
Lagrangian \checkmark $\omega(p_2, q_2) = -1 \neq 0$

Similarly $\langle p_1, q_1 \rangle^\perp = \langle p_2, q_2 \rangle$ since

$$\omega(p_1, \vec{w}) = -w_{q_1}, \quad \omega(q_1, \vec{w}) = +w_{p_1}$$

So symplectic \checkmark .

Rem: Can get all symplectic Z-planes of \mathbb{R}^4 using Plücker words.

Def: A symplectic manifold "locally looks like"
 symplectic (real) vec space.

Def:

(4)

Given a symplectic manifold (M, ω) and two smooth functions $F, G: M \rightarrow \mathbb{R}$, the Poisson bracket $\{F, G\}$ is defined as a scalar function whose value at point x is

$$\{F, G\}(x) := \frac{d}{dt} F(\rho_t(x)) \Big|_{t=0} \quad \text{where}$$

ρ_t is the Hamiltonian (local) flow of X_G
Hamiltonian vec field.

In particular,

$$\{F, G\}(x) = dF(x)(X_G(x)),$$

$$\{F, G\} = \omega(X_G, X_F) = -\omega(X_F, X_G)$$

Cor: $\{G, F\} = -\{F, G\}$.

In (p, q) -words for \mathbb{R}^{2n} case,

$$\begin{aligned} \{F, G\} &:= \begin{bmatrix} G_q^T & -G_p^T \end{bmatrix} \begin{bmatrix} 0 & -I \\ I & 0 \end{bmatrix} \begin{bmatrix} F_p \\ -F_q \end{bmatrix} \\ &= \sum_{i=1}^n \frac{\partial F}{\partial p_i} \frac{\partial G}{\partial q_i} - \frac{\partial F}{\partial q_i} \frac{\partial G}{\partial p_i} \end{aligned}$$

⑤ As motivated, an (abstract) Poisson bracket is a skew-symmetric bilinear map $\{ \cdot, \cdot \}$ satisfying the Leibniz identity $\{f_1, f_2, f_3\} = f_1 \{f_2, f_3\} + \{f_1, f_3\} f_2$ and the Jacobi identity

$$\{f_1, \{f_2, f_3\}\} + \{f_2, \{f_3, f_1\}\} + \{f_3, \{f_1, f_2\}\} = 0.$$

Def: A Poisson algebra is a commutative associative algebra \mathfrak{g} equipped w/ a Poisson bracket

$$\{ \cdot, \cdot \}: \mathfrak{g} \times \mathfrak{g} \rightarrow \mathfrak{g}.$$

Remark: If we let $\mathfrak{g} = \mathcal{C}^\infty(M)$, the alg. of smooth functions on a symplectic manifold, the usual product & chain rules of differentiation, verify these two identities.

Rem: Given an assoc. alg. A , letting $\{x, y\}$ be defined as $[x, y] = xy - yx$, the commutator, yields a Lie algebra w/ Lie bracket $[\cdot, \cdot]$ and together w/ the multi structure of A , this is a Poisson algebra.

Rem: The tensor algebra of a Lie algebra is a Poisson alg.

Def:

(6)

For $H \in \mathfrak{g}$, if $\int \{F, H\} = 0$, $F \in \mathfrak{g}$ is called an integral of the motion H .

(Thinking of X_F & X_H as vec. fields)

$$\text{i.e. } [X_F, X_H] = X_{-\{F, H\}}$$

Also said that they commute.

Def: An element $c \in \mathfrak{g}$ s.t. $\{c, f\} = 0 \forall f \in \mathfrak{g}$ is called a Casimir element or

conserved quantity.

We will see later on the course that Poisson alg's and Casimir elts/conserved quantities have roles in cluster algebra theory.