

Applied Linear Algebra

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Corrections to Second Printing (2008)

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*** Page xvii ***

Add the following sentence at the end:

We would also like to thank Nihat Bayhan, Juan Cockburn, Richard Cook, Stephen DeSalvo, Anne Dougherty, Kathleen Fuller, Stuart Hastings, Roberta Jaskolski, Tian-Jun Li, James Meiss, Willard Miller, Jr., Timo Schürg, David Tieri, and Timothy Welle for sending us their comments, suggestions, and corrections to earlier printings of this book. A particular thanks to David Hiebeler for his careful reading and corrections.

*** Page 43 *** Theorem 1.29:

To avoid confusion, change “having the nonzero pivots on the diagonal” to “with nonzero diagonal entries”.

*** Page 43 *** Theorem 1.31:

Insert “with nonzero diagonal entries” after “diagonal”.

*** Page 51 *** second displayed equation:

Replace the summand j by $j - 1$:

$$\sum_{j=1}^n (j - 1) = \frac{n^2 - n}{2}$$

*** Page 57 *** last displayed equation:

Replace 3210 by 32100:

$$10x + 1600y = 32100, \quad x + .6y = 22,$$

*** Page 58 *** first displayed equation:

Replace 3210 by 32100:

$$\left(\begin{array}{cc|c} 1600 & 10 & 32100 \\ .6 & 1 & 22 \end{array} \right)$$

*** Page 100 *** Exercise 2.3.39 (b):

Add closing bracket to $W[f(x), g(x)]$.

*** Page 106 *** Exercise 2.4.24 (b):

Change “Under the hypotheses of part (b)” to “Under the hypothesis of part (a)”.

*** Page 118 *** lines 12–13:

Change “Solving the homogeneous system $\widehat{U}\mathbf{y} = \mathbf{0}$, we conclude that” to

The two nonzero rows of \widehat{U} form a basis for $\text{corng } A^T$, and therefore

*** Page 130 *** line 6 and line 8:

Delete first “both”’s:

Inner products and norms lie at the heart of linear (and nonlinear) analysis, in both finite-dimensional vector spaces and infinite-dimensional function spaces. It is impossible to overemphasize their importance for theoretical developments, practical applications, and the design of numerical solution algorithms.

*** Page 143 *** Exercise 3.2.31 (a):

Add T superscripts to $(1, 2, 3)^T$ and $(1, -1, 2)^T$.

*** Page 161 *** Formula before Proposition 3.34:

Change dt to dx .

*** Page 161 *** Two lines before Proposition 3.34:

Change Theorem 3.31 to Theorem 3.28.

*** Page 162 *** Exercise 3.4.22 (c):

Change “null vectors” to “null directions”.

*** Page 162 *** Exercise 3.4.32:

Change “null vector” to “null direction” and $K = A^T A$ to $K = A^T C A$:

Show that $\mathbf{0} \neq \mathbf{z}$ is a null direction for the quadratic form $q(\mathbf{x}) = \mathbf{x}^T K \mathbf{x}$ based on the Gram matrix $K = A^T C A$ if and only if $\mathbf{z} \in \ker K$.

*** Page 163 *** Exercise 3.4.35 (d):

Rephrase for clarity:

Show that K is also a Gram matrix, by finding a matrix A such that $K = A^T C A$.

*** Page 168 *** Sentence after that containing (3.70):

Rephrase for clarity:

Note that M is a lower triangular matrix with all positive diagonal entries, namely the square roots of the pivots: $m_{ii} = \sqrt{d_i}$.

*** Page 177 *** Exercise 3.6.29:

Delete part (e). (“Orthogonal” and “orthonormal” are not yet defined.)

*** Page 179 *** Exercise 3.6.51:

For each of the following ...

*** Page 188 *** Formula in middle of page:

y^* and z^* should not be bold face.

*** Page 188 *** Theorem 4.4:

Delete the words “null vector”.

*** Page 191 *** Equation (4.26):

The last equality, $c = \|\mathbf{b}\|^2$, is correct provided one uses the weighted norm. However, to avoid confusion with the Euclidean norm used in (4.25), it would be better to write this as $c = \mathbf{b}^T C \mathbf{b}$.

*** Page 194 *** Equation (4.30):

$$\|A\mathbf{x}^* - \mathbf{b}\| = \sqrt{\|\mathbf{b}\|^2 - \mathbf{f}^T \mathbf{x}^*} = \sqrt{\|\mathbf{b}\|^2 - \mathbf{b}^T A(A^T A)^{-1} A^T \mathbf{b}}.$$

*** Page 201 *** line after Equation (4.43) :

Delete first “coefficient”:

The $m \times (n + 1)$ coefficient matrix ...

*** Page 221 *** Exercise 5.1.11:

$$\mathbf{u}_2 = \pm \begin{pmatrix} -\sin \theta \\ \cos \theta \end{pmatrix}$$

*** Page 231 *** Second line:

Replace “For exercises #1–8 use ” by “For Exercises #1–7 use ”.

*** Page 245 *** First line under Figure:

Change “ \mathbf{x} and \mathbf{y} ” to “ \mathbf{v} and \mathbf{w} ”.

*** Page 274 *** Remark:

... solving the homogeneous adjoint system, ...

*** Page 276 *** Exercise 5.6.20 (d):

Change the sign in front of $4x_3$ in last equation:

$$x_1 + 2x_2 + 3x_3 = b_1, \quad x_2 + 2x_3 = b_2, \quad 3x_1 + 5x_2 + 7x_3 = b_3, \quad -2x_1 + x_2 + 4x_3 = b_4;$$

*** Page 279 *** Equation (5.90):

Change e^{ikx_n} to $e^{ikx_{n-1}}$ in first line.

*** Page 285 *** Line -5:

Change $n = 2^8 = 256$ to $n = 2^9 = 512$.

*** Page 296 *** Equation (6.9):

Insert space between 1 and -1 in last row of matrix.

*** Page 298 *** Two lines before (6.15):

Change $K\mathbf{x} = \mathbf{f}$ to $K\mathbf{u} = \mathbf{f}$.

*** Page 298 *** Four lines after (6.15):

Change $\mathbf{y} = A^{-1}\mathbf{f}$ to $\mathbf{y} = A^{-T}\mathbf{f}$.

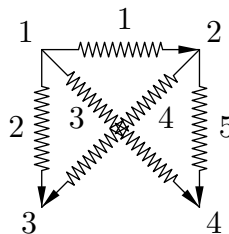
*** Page 311 *** Exercise 6.2.1 (b):

Change last row of matrix:

$$\begin{pmatrix} 0 & 0 & 1 & -1 \\ 1 & 0 & 0 & -1 \\ 0 & -1 & 1 & 0 \\ 1 & 0 & -1 & 0 \end{pmatrix}$$

*** Page 311 *** Exercise 6.2.2:

Add labels to the wires:



*** Page 312 *** Exercise 6.2.12 (a):

Start the exercise with:

Assuming all wires have unit resistance, find the voltage ...

*** Page 313 *** Line 19:

Delete "the" before "Section 6.1".

*** Page 317 *** Displayed equation above (6.51):

Change 0 to $\mathbf{0}$.

*** Page 319 *** Equation (6.58):

Change the last formula to

$$\mathbf{z}_3 \cdot \mathbf{f} = -\frac{\sqrt{3}}{2} f_1 + \frac{1}{2} g_1 + g_2 = 0.$$

*** Page 319 *** Last line:

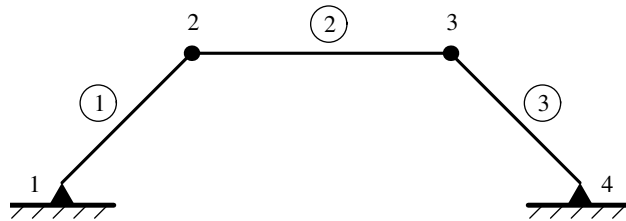
Change “first node” to “third node”.

*** Page 320 *** Two lines before displayed equation for A^{**} :

This serves to also eliminate ...

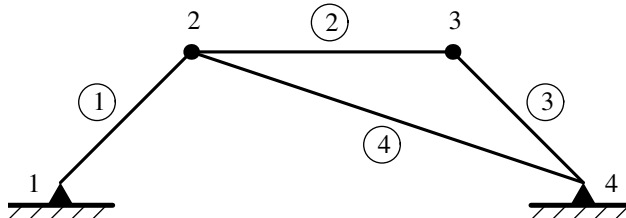
*** Page 321 *** Figure 6.13:

Label the bars in the figure:



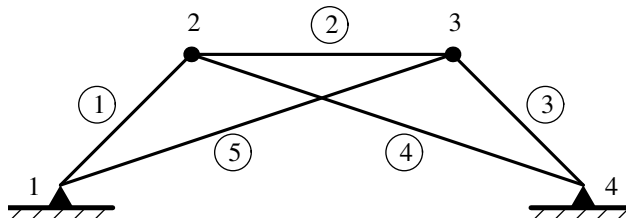
*** Page 323 *** Figure 6.16:

Label the bars in the figure:



*** Page 324 *** Figure 6.17:

Label the bars in the figure:



*** Page 325 *** Line -5:

Change “three bars” to “five bars”.

*** Page 339 *** Equation (7.12):

Add period at end of equation.

*** Page 384 *** Exercise 7.5.1 (b):

$$\langle \mathbf{v}; \mathbf{w} \rangle = 2v_1 w_1 + 3v_2 w_2$$

*** Page 399 *** Final displayed equation:

The bar on the second term should extend over both A and \mathbf{v} :

$$\overline{A} \overline{\mathbf{v}} = \overline{A\mathbf{v}} = \overline{\lambda\mathbf{v}} = \overline{\lambda} \overline{\mathbf{v}}.$$

*** Page 400 *** Two lines before Remark:

Change “combinations of the real eigenvalues” to “ combinations of the real eigenvectors”.

*** Page 411 *** Last line:

Delete “the” before “Section 8.6”.

*** Page 432 *** Fourth displayed formula. Switch T superscript:

$$A^+ = Q \Sigma^{-1} P^T = \begin{pmatrix} .2444 & .1333 & .0556 & .1889 \\ .1556 & -.0667 & .1111 & .0444 \\ -.1111 & 0 & -.0556 & -.0556 \end{pmatrix}.$$

*** Page 572 *** Displayed formula before (10.102):

The subscripts on R and Q are wrong:

$$A_2 = R_1 Q_1.$$

*** Page 575 *** Change equations (10.106) and (10.107) to:

$$A^k = (Q_0 Q_1 \cdots Q_{k-1}) (R_{k-1} \cdots R_1 R_0). \quad (10.106)$$

$$\begin{aligned} S_k &= Q_0 Q_1 \cdots Q_{k-1} = S_{k-1} Q_{k-1}, \\ P_k &= R_{k-1} \cdots R_2 R_1 = R_{k-1} P_{k-1}. \end{aligned} \quad (10.107)$$

*** Page 577 *** Replace the paragraph after Theorem 10.57 by the following::

The last remaining item is a proof of Lemma 10.56. We write

$$S = (\mathbf{u}_1 \ \mathbf{u}_2 \ \dots \ \mathbf{u}_n), \quad S_k = (\mathbf{u}_1^{(k)}, \dots, \mathbf{u}_n^{(k)})$$

in columnar form. Let $t_{ij}^{(k)}$ denote the entries of the positive upper triangular matrix T_k . The first column of the limiting equation $S_k T_k \rightarrow S$ reads

$$t_{11}^{(k)} \mathbf{u}_1^{(k)} \rightarrow \mathbf{u}_1.$$

Since both $\mathbf{u}_1^{(k)}$ and \mathbf{u}_1 are unit vectors, and $t_{11}^{(k)} > 0$,

$$\|t_{11}^{(k)} \mathbf{u}_1^{(k)}\| = t_{11}^{(k)} \rightarrow \|\mathbf{u}_1\| = 1, \quad \text{and hence} \quad \mathbf{u}_1^{(k)} \rightarrow \mathbf{u}_1.$$

The second column reads

$$t_{12}^{(k)} \mathbf{u}_1^{(k)} + t_{22}^{(k)} \mathbf{u}_2^{(k)} \rightarrow \mathbf{u}_2.$$

Taking the inner product with $\mathbf{u}_1^{(k)} \rightarrow \mathbf{u}_1$ and using orthonormality, we deduce $t_{12}^{(k)} \rightarrow 0$, and so $t_{22}^{(k)} \mathbf{u}_2^{(k)} \rightarrow \mathbf{u}_2$, which, by the previous reasoning, implies $t_{22}^{(k)} \rightarrow 1$ and $\mathbf{u}_2^{(k)} \rightarrow \mathbf{u}_2$. The proof is completed by working in order through the remaining columns, employing a similar argument at each step. Details are left to the interested reader.

*** Page 591 *** Equation (11.21):

Insert minus sign before integral:

$$u'(\ell) = - \int_0^\ell f(x) dx = 0, \tag{11.21}$$

*** Page 594 *** Line before (11.28):

Change “to satisfy” to “satisfy”.

*** Page 598 *** 3 lines after (11.40):

Change $L[u] = u(y)$ to $L_y[u] = u(y)$.

*** Page 607 *** equation (11.60):

Missing factor of c in differential equation:

$$-cu'' = f(x), \quad u(0) = 0 = u(1),$$

*** Page 608 *** Lines 10 and 7 from bottom:

Two missing factors of c :

$$\begin{aligned} c \frac{du}{dx} &= (1-x)x f(x) + \int_0^x [-y f(y)] dy - x(1-x) f(x) + \int_x^1 (1-y) f(y) dy \\ &= - \int_0^1 y f(y) dy + \int_x^1 f(y) dy. \end{aligned}$$

Differentiating again, we conclude that $-c \frac{d^2u}{dx^2} = f(x)$, as claimed.

*** Page 619 *** Exercise 11.3.16 (b):

Delete “is” after $K = L^* \circ L$.

*** Page 653 *** Solution 1.2.4 (d):

$$A = \begin{pmatrix} 2 & -1 & 2 \\ -1 & -1 & 3 \\ 3 & 0 & -2 \end{pmatrix}, \quad \mathbf{x} = \begin{pmatrix} u \\ v \\ w \end{pmatrix}, \quad \mathbf{b} = \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix};$$

*** Page 653 *** Solution 1.2.4 (f):

$$\mathbf{b} = \begin{pmatrix} -3 \\ -5 \\ 2 \\ 1 \end{pmatrix}.$$

*** Page 655 *** Solution 1.4.15 (a):

$$\begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix}.$$

*** Page 658 *** Solution 1.8.4:

(i) $a \neq b$ and $b \neq 0$; (ii) $a = b \neq 0$, or $a = -2$, $b = 0$; (iii) $a \neq -2$, $b = 0$.

*** Page 659 *** Solution 1.8.23 (e):

$$(0, 0, 0)^T;$$

*** Page 665 *** Solution 3.4.22 (v):

Change “null vectors” to “null directions”.

*** Page 665 *** Solution 3.4.32:

Change all \mathbf{x} 's to \mathbf{z} :

$0 = \mathbf{z}^T K \mathbf{z} = \mathbf{z}^T A^T C A \mathbf{z} = \mathbf{y}^T C \mathbf{y}$, where $\mathbf{y} = A \mathbf{z}$. Since $C > 0$, this implies $\mathbf{y} = \mathbf{0}$, and hence $\mathbf{z} \in \ker A = \ker K$.

*** Page 667 *** Solution 4.4.27 (a):

Change “the interpolating polynomial” to “an interpolating polynomial”.

*** Page 667 *** Solution 4.4.52 (b):

Delete the sentence:

(The solution given in the text is for the square $S = \{ 0 \leq x \leq 1, 0 \leq y \leq 1 \}$.)

*** Page 668 *** Solution 5.1.14 (b):

$$\mathbf{v}_2 = \pm \left(-\sin \theta, \frac{1}{\sqrt{2}} \cos \theta \right)^T$$

*** Page 670 *** Solution 5.4.15:

$$p_0(x) = 1, \quad p_1(x) = x, \quad p_2(x) = x^2 - \frac{1}{3}, \quad p_3(x) = x^3 - \frac{9}{10}x.$$

(The solution given in the text is for the interval $[0, 1]$, not $[-1, 1]$.)

*** Page 670 *** Solution 5.5.6 (ii) (c):

$$\left(\frac{23}{43}, \frac{19}{43}, -\frac{1}{43} \right)^T.$$

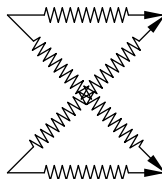
*** Page 674 ***

The page layout is a bit strange. The top of the second column (before Solution 6.2.1) is the solution to Exercise 6.1.16(c). Also, the solution to Exercise 6.2.10 spans across both columns.

*** Page 674 *** Solution 6.2.1 (b):

The solution corresponds to the revised exercise — see correction on page 311.

For the given matrix, the solution is



*** Page 674 *** Solution 6.2.12 & 6.2.13:

Change all \mathbf{e} 's to \mathbf{y} 's.

*** Page 674 *** Solution 6.3.5 (b):

$$\begin{aligned} \frac{3}{2}u_1 - \frac{1}{2}v_1 - u_2 &= f_1, \\ -\frac{1}{2}u_1 + \frac{3}{2}v_1 &= g_1, \\ -u_1 + \frac{3}{2}u_2 + \frac{1}{2}v_2 &= f_2, \\ \frac{1}{2}u_2 + \frac{3}{2}v_2 &= g_2. \end{aligned}$$

*** Page 684 *** Solution 8.5.26:

Change (b) to (c).

*** Page 694 *** Solution 11.2.8 (d):

$$\begin{aligned} f'(x) &= 4\delta(x+2) + 4\delta(x-2) + \begin{cases} 1, & |x| > 2, \\ -1, & |x| < 2, \end{cases} \\ &= 4\delta(x+2) + 4\delta(x-2) + 1 - 2\sigma(x+2) + 2\sigma(x-2), \\ f''(x) &= 4\delta'(x+2) + 4\delta'(x-2) - 2\delta(x+2) + 2\delta(x-2). \end{aligned}$$

*** Page 694 *** Solution 11.2.31 (a):

$$u_n(x) = \begin{cases} x(1-y), & 0 \leq x \leq y - \frac{1}{n}, \\ -\frac{1}{4}nx^2 + (\frac{1}{2}n-1)xy - \frac{1}{4}ny^2 + \frac{1}{2}y + \frac{1}{2}x - \frac{1}{4n}, & |x-y| \leq \frac{1}{n}, \\ y(1-x), & y + \frac{1}{n} \leq x \leq 1. \end{cases}$$

*** Page 694 *** Solution 11.3.3 (c):

$$\begin{aligned} (i) \quad u_*(x) &= \frac{1}{2}x^2 - \frac{5}{2} + x^{-1}, \\ (ii) \quad \mathcal{P}[u] &= \int_1^2 \left[\frac{1}{2}x^2(u')^2 + 3x^2u \right] dx, \quad u'(1) = u(2) = 0, \\ (iii) \quad \mathcal{P}[u_*] &= -\frac{37}{20} = -1.85, \\ (iv) \quad \mathcal{P}[x^2 - 2x] &= -\frac{11}{6} = -1.83333, \quad \mathcal{P}[-\sin \frac{1}{2}\pi x] = -1.84534. \end{aligned}$$

*** Page 696 *** Solution 11.5.7 (b):

$$\begin{aligned} \lambda = -\omega^2 < 0, \quad G(x, y) &= \begin{cases} \frac{\sinh \omega(y-1) \sinh \omega x}{\omega \sinh \omega}, & x < y, \\ \frac{\sinh \omega(x-1) \sinh \omega y}{\omega \sinh \omega}, & x > y; \end{cases} \\ \lambda = 0, \quad G(x, y) &= \begin{cases} x(y-1), & x < y, \\ y(x-1), & x > y; \end{cases} \\ \lambda = \omega^2 \neq n^2\pi^2 > 0, \quad G(x, y) &= \begin{cases} \frac{\sin \omega(y-1) \sin \omega x}{\omega \sin \omega}, & x < y, \\ \frac{\sin \omega(x-1) \sin \omega y}{\omega \sin \omega}, & x > y. \end{cases} \end{aligned}$$