

Ghost Symmetries

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Jet Notation

(x^1, \dots, x^p) — independent variables

(u^1, \dots, u^q) — dependent variables

Total derivative

$$D_i(x^j) = \delta_i^j, \quad D_i(u_J^\alpha) = u_{J+e_i}^\alpha, \\ D^J = (D_1)^{j_1} \dots (D_p)^{j_p}$$

$u_J^\alpha = D^J(u^\alpha)$ — derivative coordinates

Differential polynomial:

$$Q[u] = \sum_{K, \mathcal{J}} c_K(x) u_{J_1}^{\alpha_1} \dots u_{J_k}^{\alpha_k}$$

Local algebra

$$J = (j_1, \dots, j_p) \geq 0$$

Nonlocal algebra

$$J \in \mathbb{Z}^p \quad \text{i.e.} \quad j_\nu < 0 \quad \text{allowed}$$

or, more generally

$$D^J Q \quad \text{is defined for all} \quad J \in \mathbb{Z}^p$$

The Kadomtsev–Petviashvili equation

$$u_{xt} = u_{yy} - 6u u_{xx} - 6u_x^2 - u_{xxxx}$$

Evolutionary form

$$\begin{aligned} u_t &= D_x^{-1} u_{yy} - 6u u_x - u_{xxx} \\ &= u_{-1,2} - 6u_{0,0} u_{1,0} - u_{3,0} \end{aligned}$$

Symmetries and loop algebras

- Chen, Lee, Lin: 1982
- David, Kamran, Levi, Winternitz: 1985

Nonlocal Symmetries

- Vinogradov, Krasil'shchik: 1980, 1984 \implies “coverings”
- Kapcov: 1982
- Vladimirov, Volovich: 1985
- Fushchych, Nikitin: 1987
- Bluman, Kumei, Reid: 1988
- Akhatov, Gazizov, Ibragimov: 1991
- Galas: 1992
- Guthrie, Hickman: 1993
- Dodd: 1994
- Anco, Bluman: 1995
- Sanders, Wang: 2000
- Leo, Leo, Soliani, Tempesta: 2002
- Mikhailov, V. Novikov: 2002

Generalized vector field

$$\mathbf{v} = \mathbf{v}_Q = \sum_{\alpha, J} D^J Q^\alpha \frac{\partial}{\partial u_J^\alpha}$$

Characteristic

$$Q^\alpha = \mathbf{v}_Q(u^\alpha) \quad \alpha = 1, \dots, q$$

$$\mathbf{v}_Q(u_J^\alpha) = D_J(Q^\alpha)$$

$$[\mathbf{v}_Q, D_i] = 0$$

$$\mathbf{v}_Q(P) = D_P(Q) = \sum_{\alpha=1}^q D_P^\alpha(Q^\alpha)$$

Fréchet derivative

$$D_P^\alpha = \sum_J \frac{\partial P}{\partial u_J^\alpha} D^J$$

Commutator

Lie bracket or commutator

$$[\mathbf{v}_P, \mathbf{v}_Q] = \mathbf{v}_{[P, Q]}$$

where

$$[P, Q] = \mathbf{v}_P(Q) - \mathbf{v}_Q(P) = D_Q(P) - D_P(Q)$$

Theorem. The generalized vector field \mathbf{v}_Q is a symmetry of the evolution equation

$$u_t = P$$

if and only if

$$\frac{\partial Q}{\partial t} + [P, Q] = 0.$$

A Jacobi Paradox?

$$\begin{aligned} [1, [u_x, D_x^{-1}u]] + [u_x, [D_x^{-1}u, 1]] \\ + [D_x^{-1}u, [1, u_x]] = 1 \end{aligned}$$

$$\begin{aligned} [1, u_x] = D_{u_x}(1) - D_1(u_x) = 0 \\ \implies [\partial_u, \partial_x] = 0 \end{aligned}$$

$$\begin{aligned} [u_x, D_x^{-1}u] &= D_{D_x^{-1}u}(u_x) - D_{u_x}(D_x^{-1}u) \\ &= D_x^{-1}u_x - D_x(D_x^{-1}u) \\ &= (u + c) - u = c \end{aligned}$$

$$[1, [u_x, D_x^{-1}u]] = [1, c] = 0$$

$$\begin{aligned} [D_x^{-1}u, 1] &= -D_x^{-1}(1) = -x + d \\ [u_x, [D_x^{-1}u, 1]] &= [u_x, -x + d] \\ &= -D_x(-x + d) = 1 \end{aligned}$$

General Framework

\mathcal{A} — algebra of functions $f(x)$

\mathcal{U}_0 — u -dependent differential functions

$\mathcal{U} = \mathcal{A} \oplus \mathcal{U}_0$ — full differential algebra

$$F(x, u^{(n)}) = f(x) + P(x, u^{(n)})$$

$$\implies P(x, 0) \equiv 0$$

D_i — total derivatives on \mathcal{U}

$$\ker D_i = \{ f(x^1, \dots, x^{i-1}, x^{i+1}, \dots, x^p) \} \subset \mathcal{A}$$

Definition. A *evolutionary vector field* \mathbf{v} is a derivation $\mathbf{v}: \mathcal{U} \rightarrow \mathcal{U}$, with

$$\mathbf{v}(P + Q) = \mathbf{v}(P) + \mathbf{v}(Q)$$

$$\mathbf{v}(P \cdot Q) = \mathbf{v}(P) \cdot Q + P \cdot \mathbf{v}(Q)$$

$$\mathbf{v}(x^i) = 0 \quad \implies \quad \mathcal{A} \subset \ker \mathbf{v}$$

$$[\mathbf{v}, D_i] = 0$$

Commutator:

$$[\mathbf{v}, \mathbf{w}](P) = \mathbf{v}(\mathbf{w}(P)) - \mathbf{w}(\mathbf{v}(P))$$

Theorem. The Jacobi identity holds!

$$[\mathbf{u}, [\mathbf{v}, \mathbf{w}]] + [\mathbf{v}, [\mathbf{w}, \mathbf{u}]] + [\mathbf{w}, [\mathbf{u}, \mathbf{v}]] = 0$$

Characteristic:

$$\mathbf{v}(u^\alpha) = Q^\alpha \quad \alpha = 1, \dots, q.$$

Note

$$\mathbf{v}(u_J^\alpha) = \mathbf{v}(D_J u^\alpha) = D_J \mathbf{v}(u^\alpha) = D_J Q^\alpha$$

Key observation:

For local differential algebras, an evolutionary vector field is uniquely determined by its characteristic. This is *not* true in nonlocal differential algebras. There are nonzero evolutionary vector fields with zero characteristic — *ghosts*.

Ghosts

Definition. An evolutionary vector field γ is called a K -ghost if

$$\gamma(u_L^\alpha) = 0$$

for all $L \geq K$ and $\alpha = 1, \dots, q$.

Example. $p = 1$ $u_n = D_x^n u$

The vector field \mathbf{v}_1 with characteristic $Q = 1$ is a 1-ghost:

$$\mathbf{v}_1(u_x) = D_x(1) = 0$$

$$\mathbf{v}_1(u_n) = D_x^n(1) = 0 \quad n \geq 1$$

\implies positive (local) ghost

Example. A non-local ghost:

$$\begin{aligned}\gamma(u_k) &= \chi_{k+1}(x) = D_x^{k+1}(1) \\ &= \begin{cases} \frac{x^{-k-1}}{(-k-1)!} & k \leq -1 \\ 0 & \text{otherwise} \end{cases}\end{aligned}$$

Characteristic:

$$\gamma(u) = Q = 0$$

$$\gamma(u_n) = D_x^n(Q) = 0 \quad n \geq 0$$

$$\gamma(u_{-1}) = 1$$

$$\gamma(u_{-n}) = D_x^{-n+1}(1)$$

\implies Only polynomial u -independent vector fields can be ghosts!

$$\mathbf{v}(u_j^\alpha) = q_j^\alpha(x) \in \mathcal{A}$$

Jacobi Revisited

$$[1, [u_x, D_x^{-1}u]] + [u_x, [D_x^{-1}u, 1]] + [D_x^{-1}u, [1, u_x]]$$

Generalized vector fields \sim characteristics

$$\mathbf{v} \sim 1, \quad \mathbf{w} \sim u_x, \quad \mathbf{z} \sim D_x^{-1}u.$$

Surprise: The problem is with the local commutator

$$[\partial_u, \partial_x] \sim [1, u_x] \sim [\mathbf{v}, \mathbf{w}] = \gamma \neq 0$$

On the nonlocal differential algebra, γ is a ghost vector field!

$$\mathbf{v}(u_k) = D_x^k(1) = \chi_k(x) = \begin{cases} \frac{x^{-k}}{(-k)!}, & k \leq 0, \\ 0 & \text{otherwise,} \end{cases}$$

$$\mathbf{w}(u_k) = D_x(u_k) = u_{k+1}$$

$$\mathbf{w}(\mathbf{v}(u_k)) = 0,$$

$$\mathbf{v}(\mathbf{w}(u_k)) = \mathbf{v}(u_{k+1}) = \chi_{k+1}(x)$$

$$\gamma(u_k) = \mathbf{v}(\mathbf{w}(u_k)) - \mathbf{w}(\mathbf{v}(u_k)) = \chi_{k+1}(x)$$

$$[1, [u_x, D_x^{-1}u]] + [u_x, [D_x^{-1}u, 1]] + [D_x^{-1}u, [1, u_x]]$$

$$\mathbf{v} \sim 1, \quad \mathbf{w} \sim u_x, \quad \mathbf{z} \sim D_x^{-1}u.$$

$$[1, u_x] \sim [\mathbf{v}, \mathbf{w}] = \gamma$$

This ghost provides the missing terms in the Jacobi identity:

$$[\mathbf{z}, \gamma] = -\mathbf{v}$$

because

$$[\mathbf{z}, \gamma](u) = -\gamma(\mathbf{z}(u)) = -\gamma(D_x^{-1}u) = -1.$$

$$[\mathbf{z}, [\mathbf{v}, \mathbf{w}]] = [\mathbf{z}, \gamma] = -\mathbf{v}$$

$$[\mathbf{v}, [\mathbf{w}, \mathbf{z}]] = [\mathbf{v}, \mathbf{v}_c] = 0$$

$$[\mathbf{w}, [\mathbf{z}, \mathbf{v}]] = [\mathbf{w}, \mathbf{v}_{-x+d}] = \mathbf{v}$$

The Ghost Calculus

Assume $q = 1$ — one dependent variable u

Restrict to polynomial vector fields.

Only vector fields that do not depend on u_K can be ghosts!

Define

$$\chi_K = D^K(1) = \begin{cases} \frac{x^{-K}}{(-K)!}, & -K \geq 0, \\ 0 & \text{otherwise,} \end{cases}$$

Basis ghost vector field:

$$\gamma_J(u_K) = \chi_{J+K},$$

Theorem. Every ghost vector field is a constant coefficient linear combination of the basis ghosts

$$\gamma = \sum_J c_J \gamma_J.$$

\implies The summation can be infinite, but with certain restrictions.

Theorem. Any evolutionary vector field on a polynomial differential algebra can be written a linear combination of basis ghosts and a polynomial u -dependent vector field with characteristic Q

$$\mathbf{v} = \mathbf{v}_Q + \sum_J c_J \gamma_J$$

$$\begin{aligned} \mathbf{v}(u) &= Q + \sum_J c_J \chi_J \\ &= Q + \sum_{-J \geq 0} c_J \frac{x^{-J}}{(-J)!} \end{aligned}$$

$$\begin{aligned} \mathbf{v}(u_K) &= D^K Q + \sum_J c_J \chi_{K+J} \\ &= D^K Q + \sum_{-J-K \geq 0} c_J \frac{x^{-J-K}}{(-J-K)!} \end{aligned}$$

\implies sums must be finite

Ghost calculus rules

Uniform notation: Replace

$$x^J \implies J! \chi_{-J} \quad J \geq 0$$

$$\gamma_K \implies \chi_K$$

Every differential polynomial is a sum of monomials

$$\chi_L u_{K_1} \cdots u_{K_m} \sim \frac{x^{-L}}{(-L)!} u_{K_1} \cdots u_{K_m} \quad -L \geq 0$$

$$\chi_L \chi_K = \binom{-K-L}{-L} \chi_{K+L}$$

$$[\chi_J, \chi_K] = 0 \quad [\chi_J, u_K] = \chi_{J+K}$$

$$[\chi_J, \chi_L u_{K_1} \cdots u_{K_m}]$$

$$= \sum \binom{-K_\nu - L}{-L} \chi_{J+K_\nu+L} u_{K_1} \cdots \widehat{u_{K_\nu}} \cdots u_{K_m}$$

$$[Q, R] = \mathbf{v}_Q(R) - \mathbf{v}_R(Q)$$

Jacobi paradox revisited

$$\begin{aligned} & [1, [u_x, D_x^{-1}u]] + [u_x, [D_x^{-1}u, 1]] \\ & \qquad \qquad \qquad + [D_x^{-1}u, [1, u_x]] \end{aligned}$$

The three ghost characteristics are

$$\begin{aligned} 1 & \implies \chi_0 & u_x & \implies u_1 & D_x^{-1}u & \implies u_{-1} \\ & [\chi_0, [u_1, u_{-1}]] & = & 0 \\ & [u_1, [u_{-1}, \chi_0]] & = & - [u_1, \chi_{-1}] = \chi_0 \\ & [u_{-1}, [\chi_0, u_1]] & = & [u_{-1}, \chi_1] = -\chi_0 \end{aligned}$$

The sum of these three terms is 0.

The Original Jacobi Paradox

Independent variables — x, y

Dependent variable — u

Characteristics: $y, yu_x, u_x D_x^{-1} u_y$.

Without ghost terms:

$$\begin{aligned} & [y, [u_x D_x^{-1} u_y, yu_x]] + [yu_x, [y, u_x D_x^{-1} u_y]] \\ & + [u_x D_x^{-1} u_y, [yu_x, y]] = -2yu_x \neq 0 \end{aligned}$$

Ghost characteristics

$$y \implies \chi_{0,-1} \quad yu_x \implies \chi_{0,-1} u_{1,0} \quad u_x D_x^{-1} u_y \implies u_{1,0} u_{-1,1}$$

The three terms are

$$\begin{aligned} [\chi_{0,-1}, \chi_{0,-1} u_{1,0}] &= \chi_{0,-1} \chi_{1,-1} = 2 \chi_{1,-2} \\ [u_{1,0} u_{-1,1}, 2 \chi_{1,-2}] &= -2 \chi_{0,-1} u_{1,0}, \\ [\chi_{0,-1} u_{1,0}, u_{1,0} u_{-1,1}] &= u_{0,0} u_{1,0} \\ [\chi_{0,-1}, u_{0,0} u_{1,0}] &= \chi_{0,-1} u_{1,0} \\ [u_{1,0} u_{-1,1}, \chi_{0,-1}] &= -\chi_{1,-1} u_{-1,1} - \chi_{-1,0} u_{1,0} = -\chi_{-1,0} u_{1,0} \\ [\chi_{0,-1} u_{1,0}, -\chi_{-1,0} u_{1,0}] &= \chi_{0,-1} u_{1,0} \end{aligned}$$

The sum of these three terms is 0, and so the Jacobi identity is valid in the ghost framework.

The Kadomtsev–Petviashvili equation

$$u_t = D_x^{-1} u_{yy} - 6 u u_x - u_{xxx}$$

The following known KP symmetries

$$M = \frac{1}{12} D_x^{-2} u_{yyy} - \frac{1}{4} u_{xxy} - u u_y - \frac{1}{2} u_x D_x^{-1} u_y$$

$$N = y$$

$$H = y u_y + \frac{1}{2} x u_x + u,$$

span an $\mathfrak{sl}(2, \mathbb{R})$ Lie algebra:

$$[M, N] = H, \quad [H, M] = 2M, \quad [H, N] = -2N.$$

Paradox:

$$[M, u_x] = [N, u_x] = 0, \quad \text{but} \quad [H, u_x] = \frac{1}{2} u_x$$

\implies The vector space spanned by u_x is a one-dimensional representation of $\mathfrak{sl}(2, \mathbb{R})$, but representation theory requires that

$$[H, u_x] = 0.$$

Ghosts to the Rescue!

The symmetries do not, in fact, form a Lie algebra, but must be modified by appending a ghost to

$$[M, N] = yu_y + \frac{1}{2}xu_x + u + \frac{1}{4}\gamma_{2,0} = H + \frac{1}{4}\gamma_{2,0} \equiv \widehat{H}$$

Now, their Lie brackets are correct:

$$[M, N] = \widehat{H}, \quad [\widehat{H}, M] = 2M, \quad [\widehat{H}, N] = -2N.$$

We have

$$[\widehat{H}, u_x] = \frac{1}{2}u_x + \frac{1}{4}\gamma_{3,0}$$

Thus u_x is *not* an eigenvector for H , but actually belongs to a two-dimensional $\mathfrak{sl}(2, \mathbb{R})$ representation space spanned by u_x and $\gamma_{3,0}$.