

(62) We need to avoid this pathology.

DEFIN 1.9.6: A function $\bar{f}: \underbrace{U}_{\mathbb{R}^m}^{\text{open}} \rightarrow \mathbb{R}^m$ is called continuously differentiable on U if all its partial derivatives $\frac{\partial f_i}{\partial x_j}$ $i=1, \dots, m$ $j=1, \dots, m$ exist on U , and are continuous on U .

(NOTATION: \bar{f} is C^1 on U)
or $\bar{f} \in C^1(U)$

THM 1.9.8: If \bar{f} is C^1 on U , then it is differentiable at every $\bar{a} \in U$
(and $D\bar{f}(\bar{a})$ has matrix $J\bar{f}(\bar{a}) = \left[\frac{\partial f_i}{\partial x_j}(\bar{a}) \right]_{\substack{i=1, \dots, m \\ j=1, \dots, m}}$, of course)

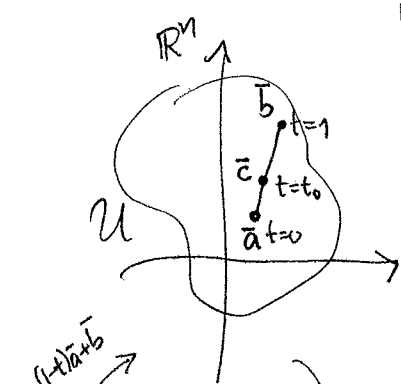
10/21/2016 > proof: We are going to need the multivariate version of M.V.T. here (and again later):

THM 1.9.1 (multivariate MVT)

If $f: \underbrace{U}_{\mathbb{R}^m}^{\text{open}} \rightarrow \mathbb{R}$ contains a line segment $[\bar{a}, \bar{b}]$ and f is differentiable on U , then \exists some $\bar{c} \in [\bar{a}, \bar{b}]$ with $[Df(\bar{c})](\bar{b} - \bar{a}) = f(\bar{b}) - f(\bar{a})$.

In particular, if $\| [Df(\bar{c})] \| \leq M \quad \forall \bar{c} \in [\bar{a}, \bar{b}]$ (COR. 1.9.2) then $|f(\bar{b}) - f(\bar{a})| \leq M \|\bar{b} - \bar{a}\|$

UNNECESSARILY STRONG HYPOTHESIS - replace with:
 f having a directional derivative in direction $\bar{b} - \bar{a}$ at every point of $[\bar{a}, \bar{b}]$ continuous on $[\bar{a}, \bar{b}]$



proof of multivar. MVT:

Parametrize $[\bar{a}, \bar{b}] = \{(1-t)\bar{a} + t\bar{b} : 0 \leq t \leq 1\}$ and apply usual MVT to $g: [0, 1] \rightarrow \mathbb{R}$ (continuous on $[0, 1]$ - why? differentiable on $(0, 1)$ - why?)

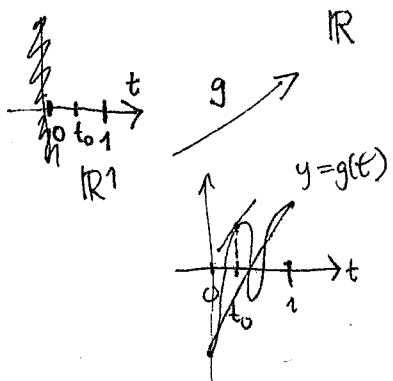
$$g(t) = f((1-t)\bar{a} + t\bar{b}) = \begin{cases} f(\bar{a}) & \text{if } t=0 \\ f(\bar{b}) & \text{if } t=1 \end{cases}$$

$$\text{to get } t_0 \in (0, 1) \text{ with } g'(t_0) = \frac{g(1) - g(0)}{1 - 0} = f(\bar{b}) - f(\bar{a})$$

name ~~name~~

$$\begin{aligned} & \lim_{h \rightarrow 0} \frac{g(t_0+h) - g(t_0)}{h} \\ &= \lim_{h \rightarrow 0} \frac{f(\bar{c} + h(\bar{b} - \bar{a})) - f(\bar{c})}{h} \\ &= \text{dir. deriv. of } f \text{ at } \bar{c} \text{ in dir. } \bar{b} - \bar{a} \\ &= [Df(\bar{c})](\bar{b} - \bar{a}) \quad \blacksquare \end{aligned}$$

$\bar{c} := (1-t_0)\bar{a} + t_0\bar{b}$



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Continuing the proof of THM 1.9.8,
 assuming $\bar{f}: \underset{\mathbb{R}^n}{U}^{\text{open}} \rightarrow \mathbb{R}^m$ is C^1 , and given $\bar{a} \in U$

we want to show $\lim_{h \rightarrow 0} \frac{\bar{f}(\bar{a}+h) - \bar{f}(\bar{a}) - [J\bar{f}(\bar{a})]h}{|h|} = 0$.

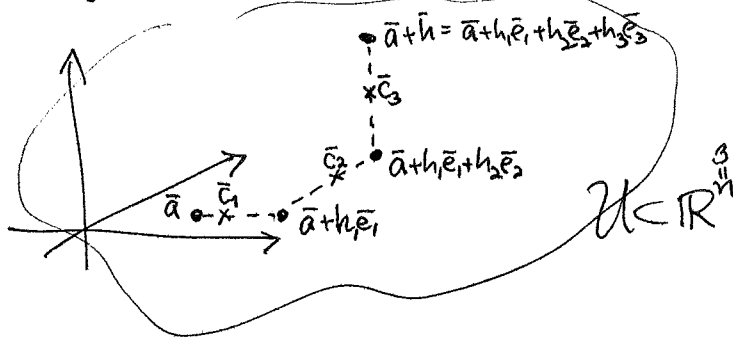
Since the limits go componentwise for $\bar{f} = \begin{pmatrix} f_1 \\ \vdots \\ f_m \end{pmatrix}$, we may as well assume $m=1$,

i.e. $f: \underset{\mathbb{R}^n}{U}^{\text{open}} \rightarrow \mathbb{R}$, and we want to show

$$\lim_{h \rightarrow 0} \frac{f(\bar{a}+h) - f(\bar{a}) - [Jf(\bar{a})]h}{|h|} = 0 \quad \text{where here} \quad [Jf(\bar{a})] = \left[\frac{\partial f}{\partial x_1}(\bar{a}) \dots \frac{\partial f}{\partial x_n}(\bar{a}) \right]$$

Make sure $|h|$ is small enough so that when we write $h = \begin{bmatrix} h_1 \\ \vdots \\ h_n \end{bmatrix} = h_1 \bar{e}_1 + \dots + h_n \bar{e}_n$,

all these segments $[\bar{a}, \bar{a}+h\bar{e}_1]$, $[\bar{a}+h\bar{e}_1, \bar{a}+h\bar{e}_1+h_2\bar{e}_2]$, \dots , $[\bar{a}+h\bar{e}_1+\dots+h_{n-1}\bar{e}_{n-1}, \bar{a}+h]$ lie in U :



Then by telescoping,

$$f(\bar{a}+h) - f(\bar{a}) = \sum_{i=1}^n f(\bar{a}+h_1\bar{e}_1+\dots+h_i\bar{e}_i) - f(\bar{a}+h_1\bar{e}_1+\dots+h_{i-1}\bar{e}_{i-1})$$

Use the multivariate MVT on each segment to find a \bar{c}_i on the segment $[\bar{a}+h_1\bar{e}_1+\dots+h_{i-1}\bar{e}_{i-1}, \bar{a}+h_1\bar{e}_1+\dots+h_i\bar{e}_i]$ for $i=1, \dots, n$

$$\begin{aligned} \text{with } f(\bar{a}+h_1\bar{e}_1+\dots+h_i\bar{e}_i) - f(\bar{a}+h_1\bar{e}_1+\dots+h_{i-1}\bar{e}_{i-1}) &= Df(\bar{c}_i)(h\bar{e}_i) = h [Jf(\bar{c}_i)](\bar{e}_i) \\ &= h \cdot \frac{\partial f}{\partial x_i}(\bar{c}_i) \end{aligned}$$

$$\begin{aligned} \text{Thus } \left| \frac{f(\bar{a}+h) - f(\bar{a}) - [Jf(\bar{a})]h}{|h|} \right| &= \left| \sum_{i=1}^n h_i \frac{\partial f}{\partial x_i}(\bar{c}_i) - \sum_{i=1}^n \frac{\partial f}{\partial x_i}(\bar{a}) h_i \right| / |h| \\ &= \left| \sum_{i=1}^n h_i \left(\frac{\partial f}{\partial x_i}(\bar{c}_i) - \frac{\partial f}{\partial x_i}(\bar{a}) \right) \right| \leq \sum_{i=1}^n \frac{|h_i|}{|h|} \left(\frac{\partial f}{\partial x_i}(\bar{c}_i) - \frac{\partial f}{\partial x_i}(\bar{a}) \right) \quad \text{all } \leq 1 \end{aligned}$$

Now use C^1 : as $h \rightarrow 0$, each $h_i \rightarrow 0$, and each $\bar{c}_i \rightarrow \bar{a}$, so continuity of $\frac{\partial f}{\partial x_i}$

implies $\frac{\partial f}{\partial x_i}(\bar{c}_i) \rightarrow \frac{\partial f}{\partial x_i}(\bar{a})$. Hence the above expression $\rightarrow 0$ \square

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Chapter 2 Solving equations (i.e. back to more linear algebra!)

How would you solve the system

$$\begin{aligned} x+y+z+w &= 1 \\ 2x+2y+6z+8w &= 0 \\ 4x+4y+8z+10w &= 1 \end{aligned} \quad ?$$

In matrix form, it's $A\bar{x} = \bar{b}$

$$\begin{pmatrix} 1 & 1 & 1 & 1 \\ 2 & 2 & 6 & 8 \\ 4 & 4 & 8 & 10 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \\ w \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$$

$$A \quad \bar{x} = \bar{b}$$

Adding/scaling equations is easiest to perform/mimic on the augmented matrix $[A|b] =$

$$\left[\begin{array}{cccc|c} 1 & 1 & 1 & 1 & 1 \\ 2 & 2 & 6 & 8 & 0 \\ 4 & 4 & 8 & 10 & 1 \end{array} \right]$$

by performing (invertible) row operations:
(DEFN 2.1.1)

1. scale a row by some $c \in \mathbb{R} - \{0\}$
2. add a multiple of a row to another
3. exchange rows

One systematic way to do this brings $[A|b]$ into what is called (row-reduced) echelon form (DEFN 2.1.4):

schematically:

$$\left[\begin{array}{cccccccc} 0 & 0 & \dots & 0 & 1 & * & * & * & * & 0 & * & * & * & * & * & * & * \\ 0 & 0 & \dots & 0 & 0 & \dots & 0 & 1 & * & * & * & 0 & * & * & * & * & * \\ 0 & 0 & \dots & 0 & 0 & \dots & 0 & 0 & \dots & 0 & 1 & * & * & * & * & * & * \\ 0 & 0 & \dots & 0 & 0 & \dots & 0 & 0 & \dots & 0 & 0 & \dots & 0 & 0 & \dots & 0 & 0 \\ 0 & 0 & \dots & 0 & 0 & \dots & 0 & 0 & \dots & 0 & 0 & \dots & 0 & 0 & \dots & 0 & 0 \end{array} \right]$$

10/24/2016 >

- rules:
1. every row has leftmost non zero entry scaled to 1 (called a pivot 1)
 2. pivot 1's go left-to-right as row index increases
 3. pivot 1's are the only nonzero entry in their columns
 4. zero rows can only go at the bottom