

(9)

EXAMPLES ①
$$\begin{bmatrix} 1 & 2 & 3 \\ 6 & 5 & 4 \end{bmatrix} \begin{bmatrix} 2 \\ 0 \\ 3 \end{bmatrix} = \begin{bmatrix} 1 \cdot 2 + 2 \cdot 0 + 3 \cdot 3 \\ 6 \cdot 2 + 5 \cdot 0 + 4 \cdot 3 \end{bmatrix} = \begin{bmatrix} 11 \\ 24 \end{bmatrix}$$

$A \quad B = C$
 $2 \times 3 \quad 3 \times 1 \quad 2 \times 1$

$$\begin{bmatrix} -F_1^T & - \\ -F_2^T & - \end{bmatrix} \begin{bmatrix} 1 \\ \bar{c}_1 \\ 1 \end{bmatrix} = \begin{bmatrix} F_1^T \bar{c}_1 \\ F_2^T \bar{c}_2 \end{bmatrix} = \begin{bmatrix} F_1 \cdot \bar{c}_1 \\ F_2 \cdot \bar{c}_2 \end{bmatrix}$$

②
$$F_2^T \rightarrow \begin{bmatrix} 1 & 6 \\ 2 & 5 \\ 3 & 4 \end{bmatrix} \begin{bmatrix} -1 & 0 & 1 \\ 1 & 0 & 1 \end{bmatrix} \begin{matrix} \bar{c}_3 \\ \downarrow \\ 2 \\ 4 \end{matrix} = \begin{bmatrix} 5 & 0 & 7 & 26 \\ 3 & 0 & 7 & 24 \\ 1 & 0 & 7 & 22 \end{bmatrix}$$

$A \quad B = C$
 $3 \times 2 \quad 2 \times 4 \quad 3 \times 4$

$F_2^T \bar{c}_3 =$
 $F_2 \cdot \bar{c}_3 =$
 $\begin{bmatrix} 2 \\ 5 \end{bmatrix} \begin{bmatrix} 2 \\ 4 \end{bmatrix} =$
 $2 \cdot 2 + 5 \cdot 4 = 24$

Matrix multiplication has lots of good properties that are not hard to verify, such as its interactions with

scaling matrices $cA := \begin{bmatrix} ca_{11} & ca_{12} & \dots \\ ca_{21} & \dots & \dots \\ \vdots & \dots & \dots \end{bmatrix}$
 (entrywise)

adding matrices $A+B := \begin{bmatrix} a_{11}+b_{11} & a_{12}+b_{12} \\ a_{21}+b_{21} & \dots \end{bmatrix}$
 (entrywise)

like $(cA) \cdot B = A(cB) = cAB$

$(A_1+A_2)B = A_1B+A_2B$

$A(B_1+B_2) = AB_1+AB_2$

} all pretty easy

associativity: $(AB)C = A(BC)$ for A, B, C
 (PROP 1.2.9 in book)

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proof: Let's calculate (i,j) entry on both sides for $i=1 \rightarrow m, j=1 \rightarrow q$:

$$[(AB)C]_{i,j} = \sum_{k=1}^p (AB)_{ik} c_{kj} = \sum_{k=1}^p \left(\sum_{l=1}^m a_{il} b_{lk} \right) c_{kj}$$

$$= \sum_{k=1}^p \sum_{l=1}^m a_{il} b_{lk} c_{kj}$$

$$[A(BC)]_{i,j} = \sum_{k=1}^m a_{ik} (BC)_{kj} = \sum_{k=1}^m a_{ik} \left(\sum_{l=1}^p b_{kl} c_{lj} \right)$$

same!

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$$(AB)^T = B^T A^T \quad \left(\begin{array}{l} \text{THEOREM 1.2.17} \\ \text{in book} \end{array}, \text{ EXER. 1.2.14 on HW} \right)$$

Perhaps disappointingly, but interestingly,
 $AB \neq BA$ in general!

not commutative, even when both are square
of same dimensions

e.g. $\underbrace{\begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix}}_A \underbrace{\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}}_B = \underbrace{\begin{bmatrix} 0 & 2 \\ 0 & 0 \end{bmatrix}}_{AB}$ ← not equal

$\underbrace{\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}}_B \underbrace{\begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix}}_A = \underbrace{\begin{bmatrix} 0 & 3 \\ 0 & 0 \end{bmatrix}}_{BA}$ ←

(Why is there no hope for $AB = BA$ if $\begin{matrix} A \text{ is } m \times n \\ B \text{ is } n \times m \end{matrix}$ with $m \neq n$?)

Try it with $m=1$
 $n > 1$.

The special case of $\underbrace{AB}_{m \times n \cdot n \times 1}$ where $B = \vec{v} = \begin{bmatrix} v_1 \\ \vdots \\ v_n \end{bmatrix}$ is a column vector

gives us all linear transformations...

THM 1.3.4:

(1) Every $m \times n$ matrix A gives a linear transformation

$$T: \mathbb{R}^n \rightarrow \mathbb{R}^m$$

$$\vec{v} = \begin{bmatrix} v_1 \\ \vdots \\ v_n \end{bmatrix} \mapsto T(\vec{v}) = A\vec{v} = \begin{bmatrix} a_{11} & a_{12} & \dots \\ \vdots & \vdots & \ddots \end{bmatrix} \begin{bmatrix} v_1 \\ \vdots \\ v_n \end{bmatrix}$$

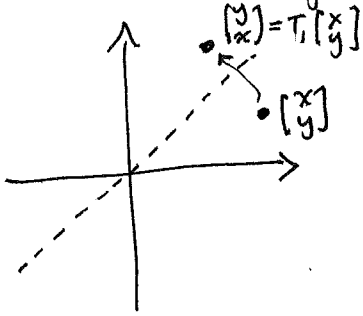
(2) Every linear transformation $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is of this form,
namely $T(\vec{v}) = [T]\vec{v}$ where $[T]$ is the $m \times n$ matrix
whose j^{th} column is $T(\vec{e}_j)$, i.e.

$$[T] = \begin{bmatrix} | & | & & | \\ T(\vec{e}_1) & T(\vec{e}_2) & \dots & T(\vec{e}_n) \\ | & | & & | \end{bmatrix}$$

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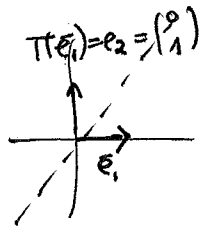
EXAMPLES of (2):

$T_1 =$ reflection in \mathbb{R}^2
through symmetry line $y=x$



$$T_1 \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} y \\ x \end{bmatrix}$$

Images of \bar{e}_1, \bar{e}_2 ?

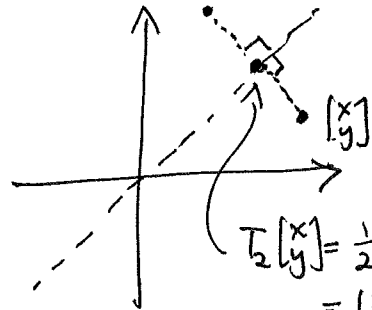


$$T_1(\bar{e}_1) = \bar{e}_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$\text{so } [T_1] = \begin{bmatrix} | & | \\ T_1(\bar{e}_1) & T_1(\bar{e}_2) \\ | & | \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

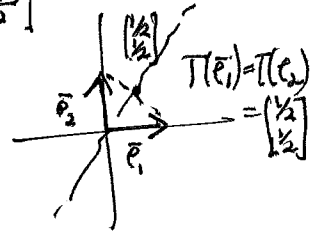
Check: $[T_1] \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} y \\ x \end{bmatrix} \stackrel{\vee}{=} T_1 \begin{bmatrix} x \\ y \end{bmatrix}$

$T_2 =$ projection in \mathbb{R}^2
orthogonally onto
line $y=x$



$$T_2 \begin{bmatrix} x \\ y \end{bmatrix} = \frac{1}{2} \left(\begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} y \\ x \end{bmatrix} \right) = \begin{bmatrix} \frac{x+y}{2} \\ \frac{x+y}{2} \end{bmatrix}$$

Images of \bar{e}_1, \bar{e}_2 ?



$$T_2(\bar{e}_1) = T_2 \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1/2 \\ 1/2 \end{bmatrix}$$

$$\text{so } [T_2] = \begin{bmatrix} | & | \\ T_2(\bar{e}_1) & T_2(\bar{e}_2) \\ | & | \end{bmatrix} = \begin{bmatrix} 1/2 & 1/2 \\ 1/2 & 1/2 \end{bmatrix}$$

Check: $[T_2] \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 1/2 & 1/2 \\ 1/2 & 1/2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} \frac{x+y}{2} \\ \frac{x+y}{2} \end{bmatrix} \stackrel{\vee}{=} T_2 \begin{bmatrix} x \\ y \end{bmatrix}$

~~Proof of THM 1.3.4:~~

(1) Given an $m \times n$ matrix $A = \begin{bmatrix} \overbrace{\quad}^n \\ \hline \bar{a}_1^T \\ \hline \bar{a}_m^T \\ \hline \end{bmatrix}$, note that

$$T(\vec{v}) := A\vec{v} = \begin{bmatrix} \bar{a}_1^T \\ \vdots \\ \bar{a}_m^T \end{bmatrix} \begin{bmatrix} v_1 \\ \vdots \\ v_n \end{bmatrix} = \begin{bmatrix} \bar{a}_1^T \vec{v} \\ \vdots \\ \bar{a}_m^T \vec{v} \end{bmatrix}$$

so to show T is linear, i.e. $T(c\vec{v}) = cT(\vec{v})$
 $T(\vec{v} + \vec{w}) = T(\vec{v}) + T(\vec{w})$

it helps to deal with the $m=1$ row case first, i.e. $A = \begin{bmatrix} \bar{a}^T \end{bmatrix}$

and then $T(\vec{v}) = \bar{a}^T \vec{v}$, with $T(c\vec{v}) = \bar{a}^T \cdot c\vec{v} = \sum_{i=1}^n a_i \cdot cv_i = c \sum_{i=1}^n a_i v_i = c \bar{a}^T \vec{v} = cT(\vec{v})$

$$T(\vec{v} + \vec{w}) = \bar{a}^T (\vec{v} + \vec{w}) = \sum_{i=1}^n a_i (v_i + w_i) = \bar{a}^T \vec{v} + \bar{a}^T \vec{w} = T(\vec{v}) + T(\vec{w})$$

~~Proof of THM 1.3.4:~~

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Generally $\Rightarrow T(\vec{v}) = A\vec{v}$ has $T(c\vec{v}) = \begin{bmatrix} a_{11}c \\ \vdots \\ a_{m1}c \end{bmatrix} = c \begin{bmatrix} a_{11} \\ \vdots \\ a_{m1} \end{bmatrix} = cT(\vec{v})$

$$T(\vec{v} + \vec{w}) = \begin{bmatrix} a_{11}(\vec{v} + \vec{w}) \\ \vdots \\ a_{m1}(\vec{v} + \vec{w}) \end{bmatrix} = \begin{bmatrix} a_{11}\vec{v} \\ \vdots \\ a_{m1}\vec{v} \end{bmatrix} + \begin{bmatrix} a_{11}\vec{w} \\ \vdots \\ a_{m1}\vec{w} \end{bmatrix} = T(\vec{v}) + T(\vec{w})$$

(2) It helps here to note $A\vec{v} = \begin{bmatrix} a_{11} & \dots & a_{1n} \\ \vdots & & \vdots \\ a_{m1} & \dots & a_{mn} \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix} = \begin{bmatrix} v_1 a_{11} + \dots + v_n a_{1n} \\ \vdots \\ v_1 a_{m1} + \dots + v_n a_{mn} \end{bmatrix}$

i.e. $A\vec{v} = v_1 \begin{bmatrix} a_{11} \\ \vdots \\ a_{m1} \end{bmatrix} + v_2 \begin{bmatrix} a_{12} \\ \vdots \\ a_{m2} \end{bmatrix} + \dots + v_n \begin{bmatrix} a_{1n} \\ \vdots \\ a_{mn} \end{bmatrix}$

1st col of A
2nd col of A
nth col of A

So given any linear transformation $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$,
 applying the boxed fact to $A = [T] := \begin{bmatrix} | & | & \dots & | \\ T(\vec{e}_1) & T(\vec{e}_2) & \dots & T(\vec{e}_n) \\ | & | & \dots & | \end{bmatrix}$

one gets $[T]\vec{v} = \begin{bmatrix} | & | & \dots & | \\ T(\vec{e}_1) & T(\vec{e}_2) & \dots & T(\vec{e}_n) \\ | & | & \dots & | \end{bmatrix} \begin{bmatrix} v_1 \\ \vdots \\ v_n \end{bmatrix} = v_1 T(\vec{e}_1) + \dots + v_n T(\vec{e}_n)$
 $\stackrel{\text{by linearity of } T}{=} T(v_1 \vec{e}_1 + \dots + v_n \vec{e}_n)$
 $= T\left(\begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix}\right) = T(\vec{v})$ \blacksquare

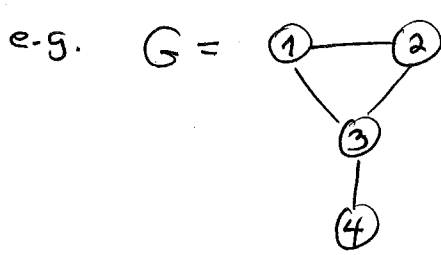
THM 1.3.10

~~COROLLARY~~: Composing linear transformations $T_1: \mathbb{R}^n \rightarrow \mathbb{R}^m$, $T_2: \mathbb{R}^m \rightarrow \mathbb{R}^p$ gives a linear transformation $T_2 \circ T_1: \mathbb{R}^n \rightarrow \mathbb{R}^p$ with matrix $[T_2 \circ T_1] = [T_2][T_1]$

9/16/2016 > Another way matrix multiplication arises naturally...

Counting Walks in graphs

DEFN: Given a graph G with nodes/vertices labeled $1, 2, \dots, m$ and edges between some pairs $\{i, j\}$ of vertices,

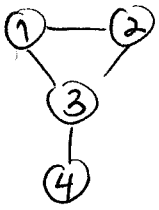


one can form its $m \times n$ adjacency matrix

e.g. $A = \begin{matrix} & \begin{matrix} 1 & 2 & 3 & 4 \end{matrix} \\ \begin{matrix} 1 \\ 2 \\ 3 \\ 4 \end{matrix} & \begin{bmatrix} 0 & 1 & 1 & 0 \\ 1 & 0 & 1 & 0 \\ 1 & 1 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \end{matrix}$

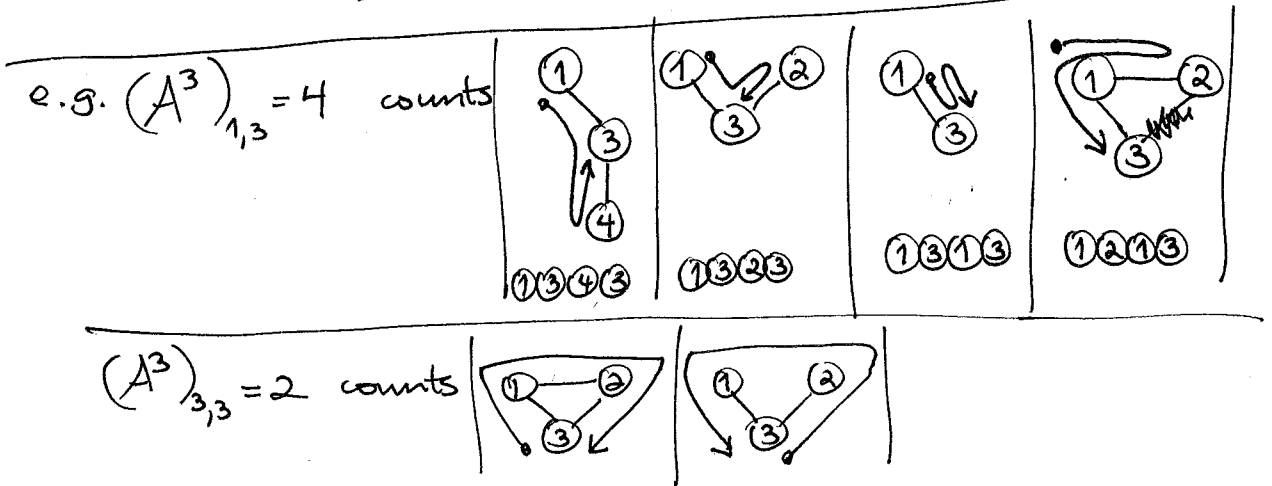
having $a_{ij} = \begin{cases} 1 & \text{if } \{i, j\} \text{ is an edge of } G \\ 0 & \text{if not.} \end{cases}$

(b) Then powers A, A^2, A^3, \dots have entries that count walks along edges of G



$$A = \begin{matrix} & \begin{matrix} 1 & 2 & 3 & 4 \end{matrix} \\ \begin{matrix} 1 \\ 2 \\ 3 \\ 4 \end{matrix} & \begin{bmatrix} 2 & 1 & 1 & 1 \\ 1 & 2 & 1 & 1 \\ 1 & 1 & 3 & 0 \\ 1 & 1 & 0 & 1 \end{bmatrix} \end{matrix}$$

PROPOSITION 1.2.23: $(A^n)_{ij} = \#$ of walks along edges of G from i to j taking exactly n steps for $n \geq 1$



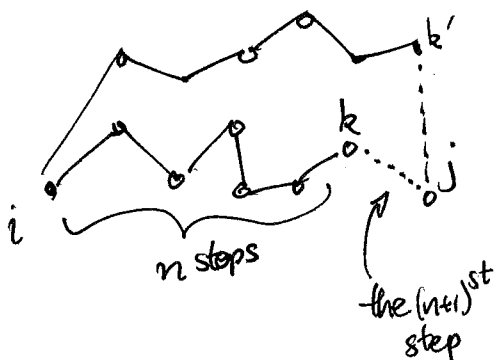
proof of PROP 1.2.23:

Induction on n , with base case $n=1$ true by definition of adjacency matrix A .

In the inductive step, assume the assertion of the PROP is true for n , and we'll show it for $n+1$:

$$(A^{n+1})_{ij} = (A^n \cdot A)_{ij} = \sum_{k=1}^m (A^n)_{ik} a_{kj}$$

0 or 1 depending on whether $\{j,k\}$ is an edge of G



$$= \sum_{\substack{k \text{ with} \\ \text{an edge } \{j,k\} \\ \text{in } G}} (A^n)_{ik}$$

of walks with n steps from i to k in G

$$= \# \text{ of walks with } n+1 \text{ steps from } i \text{ to } j \text{ in } G \quad \blacksquare$$