

Math3592 review sheet for the final exam

The final exam will take place on Friday December 15, 12:00-3:00, in room **Vincent Hall 211**. I will hold a review session in a room in Vincent Hall, probably on the second floor, from 10:00-11:00 on Friday morning. Come to my office (Vincent 350) then to find out.

There are 12 questions on the exam, some divided into parts, with each question part usually worth 6% of the total. You may not use books. You may use a single sheet of your own notes. You may use a calculator. Always show your work, and be sure to write down sufficient detail so that I can see that you are able to do all calculations without a calculator if necessary. If you are not sure what is required in any question, or what the question means, do ask.

Here is a start on some review questions. I may come up with some more.

1. Let $f : \text{Mat}(2, 2) \rightarrow \mathbb{R}$ be the mapping $f(A) = \text{trace}(A^2)$. Find the directional derivative of f at the matrix $\begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}$ in the direction of the matrix $\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$.
2. Consider the following functions which are defined to be 0 at $(0, 0)$. Are they continuous at the origin? Differentiable? Do the partial derivatives exist?

$$\frac{x^2}{\sqrt{x^2 + y^2}}, \quad \frac{2x - 5y}{\sqrt{x^2 + y^2}}, \quad \frac{xy}{\sqrt{x^2 + y^2}}, \quad \frac{x^2 + y^2}{x + y^2}$$

3. True or false? For each of the following statements, decide whether it is true or false, and then either give brief reasons or a counterexample to justify your assertion.
 - (a) There exists a surjective linear mapping $\mathbb{R}^7 \rightarrow \mathbb{R}^{10}$.
 - (b) If $f : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ is a differentiable function, there can never be a function $g : \mathbb{R}^3 \rightarrow \mathbb{R}^2$ with $gf = 1_{\mathbb{R}^2}$, the identity mapping on \mathbb{R}^2 .
 - (c) If $f : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ is a differentiable function, there can never be a function $g : \mathbb{R}^3 \rightarrow \mathbb{R}^2$ with $fg = 1_{\mathbb{R}^3}$, the identity mapping on \mathbb{R}^3 .
 - (d) Let v_1, \dots, v_r be a linearly independent set of vectors in a vector space V and w_1, \dots, w_r another set of vectors in a vector space W . Then there exists a linear mapping $T : V \rightarrow W$ with $T(v_i) = w_i$ for all i with $1 \leq i \leq r$.
 - (e) If S is an $m \times n$ matrix of rank m then there exists an $n \times m$ matrix T with $ST = I$, the identity matrix.
 - (f) Suppose that $f : \mathbb{R}^n \rightarrow \mathbb{R}^n$ is continuously differentiable and there exists $g : \mathbb{R}^n \rightarrow \mathbb{R}^n$ with $fg = gf = 1$. Then g is differentiable.
 - (g) If $f : U \rightarrow V$ and $g : V \rightarrow W$ are linear mappings then $\text{rank}(gf) \leq \text{rank}(f)$ always and $\text{rank}(gf) \leq \text{rank}(g)$ always.
 - (h) If $S : U \rightarrow V$ is a linear mapping which is onto then there exists a linear mapping $T : V \rightarrow U$ with $ST = I$.

- (i) If $S : U \rightarrow V$ is a linear mapping which is onto then there exists a linear mapping $T : V \rightarrow U$ with $TS = I$.
 - (j) If $S : U \rightarrow V$ is a linear mapping which is 1-1 then there exists a linear mapping $T : V \rightarrow U$ with $ST = I$.
 - (k) If $S : U \rightarrow V$ is a linear mapping which is 1-1 then there exists a linear mapping $T : V \rightarrow U$ with $TS = I$.
 - (l) Same questions as (h) (i), (j), (k) with the additional hypothesis that $\dim U = \dim V$.
4. Let S be a subset of \mathbb{R}^n . We will say that x is a *limit point* of $S \Leftrightarrow$ for all $\epsilon > 0$ there exists $y \in S$ with $0 < |x - y| < \epsilon$. Using the definition that S is closed \Leftrightarrow for every point x not in S there is a ball of some positive radius with center x which contains no point of S , prove that

$$S \text{ is closed} \Leftrightarrow S \supseteq \text{its limit points.}$$

Which of the following statements means x is not a limit point of S ?

- (i) There exists $\epsilon > 0$ such that for all $y \in S$ either $y = x$ or $|y - x| \geq \epsilon$.
 - (ii) There exists $\epsilon > 0$ such that for all $y \in S$ either $y = x$ or $|y - x| > \epsilon$.
 - (iii) There exists $\epsilon > 0$ such that there exists $y \in S$ with either $y = x$ or $|y - x| \geq \epsilon$.
 - (iv) There exists $y \in S$ such that there exists $\epsilon > 0$ with either $y = x$ or $|y - x| > \epsilon$.
5. Do one step of Newton's method to solve the system of equations

$$\begin{aligned} ye^x + xe^y &= 1 \\ x^3 + xy + \sin y &= 0 \end{aligned} \quad \text{starting at } a_0 = \begin{pmatrix} 0 \\ 0 \end{pmatrix}.$$

6. Calculate $\det \begin{pmatrix} 1 & 2 & -1 \\ 5 & 1 & 0 \\ 4 & 1 & 1 \end{pmatrix}$.

7. Prove that

$$Df(a)(h) = \lim_{t \rightarrow 0} \frac{f(a + th) - f(a)}{t}.$$

8. Let $T : \mathbb{R}^3 \rightarrow \mathbb{R}^2$ be the linear map whose matrix with respect to the standard bases is $\begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{pmatrix}$. Find the matrix of T with respect to the bases

$$\begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 3 \\ -2 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} \quad \text{and} \quad \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \end{pmatrix}.$$

9. Questions about compactness, open, closed, boundary etc. Questions about distance between points lines and planes.